

# Reverse Engineering for Beginners



Dennis Yurichev

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Text version (October 10, 2015).

The latest version (and Russian edition) of this text accessible at [beginners.re](http://beginners.re). An e-book reader version is also available.

You can also follow me on twitter to get information about updates of this text: @yurichev<sup>1</sup> or to subscribe to the mailing list<sup>2</sup>.

The cover was made by Andy Nechaevsky: [facebook](#).

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<sup>1</sup>[twitter.com/yurichev](http://twitter.com/yurichev)

<sup>2</sup>[yurichev.com](http://yurichev.com)

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## Warning: this is a shortened LITE-version!

It is approximately 6 times shorter than full version (~150 pages) and intended to those who wants for very quick introduction to reverse engineering basics. There are nothing about MIPS, ARM, OllyDBG, GCC, GDB, IDA, there are no exercises, examples, etc.

If you still interesting in reverse engineering, full version of the book is always available on my website: [beginners.re](http://beginners.re).

# Contents

<b>I</b>	<b>Code patterns</b>	<b>1</b>
<b>1</b>	<b>A short introduction to the CPU</b>	<b>3</b>
<b>2</b>	<b>The simplest Function</b>	<b>4</b>
2.1	x86	4
<b>3</b>	<b>Hello, world!</b>	<b>5</b>
3.1	x86	5
3.1.1	MSVC	5
3.2	x86-64	6
3.2.1	MSVC-x86-64	6
3.3	Conclusion	7
<b>4</b>	<b>Function prologue and epilogue</b>	<b>8</b>
4.1	Recursion	8
<b>5</b>	<b>Stack</b>	<b>9</b>
5.1	Why does the stack grow backwards?	9
5.2	What is the stack used for?	10
5.2.1	Save the function's return address	10
5.2.2	Passing function arguments	10
5.2.3	Local variable storage	11
5.2.4	x86: <code>alloca()</code> function	11
5.2.5	(Windows) SEH	12
5.2.6	Buffer overflow protection	12
5.2.7	Automatic deallocation of data in stack	13
5.3	A typical stack layout	13
<b>6</b>	<b><code>printf()</code> with several arguments</b>	<b>14</b>
6.1	x86	14
6.1.1	x86: 3 arguments	14
6.1.2	x64: 8 arguments	15
6.2	Conclusion	16
6.3	By the way	16
<b>7</b>	<b><code>scanf()</code></b>	<b>17</b>
7.1	Simple example	17
7.1.1	About pointers	17
7.1.2	x86	18
7.1.3	x64	19
7.2	Global variables	19
7.2.1	MSVC: x86	20
7.2.2	MSVC: x64	21
7.3	<code>scanf()</code> result checking	21
7.3.1	MSVC: x86	22
7.3.2	MSVC: x86 + Hiew	24
7.3.3	MSVC: x64	25
7.4	Exercises	26
7.4.1	Exercise #1	26

<b>8</b>	<b>Accessing passed arguments</b>	<b>27</b>
8.1	x86	27
8.1.1	MSVC	27
8.2	x64	28
8.2.1	MSVC	28
<b>9</b>	<b>More about results returning</b>	<b>30</b>
9.1	Attempt to use the result of a function returning <i>void</i>	30
9.2	What if we do not use the function result?	31
<b>10</b>	<b>GOTO operator</b>	<b>32</b>
10.1	Dead code	33
<b>11</b>	<b>Conditional jumps</b>	<b>34</b>
11.1	Simple example	34
11.1.1	x86	34
11.2	Calculating absolute value	38
11.2.1	Optimizing MSVC	38
11.3	Ternary conditional operator	39
11.3.1	x86	39
11.3.2	Let's rewrite it in an <i>if/else</i> way	40
11.4	Getting minimal and maximal values	40
11.4.1	32-bit	40
11.5	Conclusion	42
11.5.1	x86	42
11.5.2	Branchless	42
<b>12</b>	<b>switch()/case/default</b>	<b>43</b>
12.1	Small number of cases	43
12.1.1	x86	43
12.1.2	Conclusion	45
12.2	A lot of cases	45
12.2.1	x86	45
12.2.2	Conclusion	48
12.3	When there are several <i>case</i> statements in one block	48
12.3.1	MSVC	49
12.4	Fall-through	50
12.4.1	MSVC x86	51
<b>13</b>	<b>Loops</b>	<b>52</b>
13.1	Simple example	52
13.1.1	x86	52
13.1.2	One more thing	53
13.2	Memory blocks copying routine	53
13.2.1	Straight-forward implementation	54
13.3	Conclusion	54
<b>14</b>	<b>Simple C-strings processing</b>	<b>56</b>
14.1	strlen()	56
14.1.1	x86	56
<b>15</b>	<b>Replacing arithmetic instructions to other ones</b>	<b>58</b>
15.1	Multiplication	58
15.1.1	Multiplication using addition	58
15.1.2	Multiplication using shifting	58
15.1.3	Multiplication using shifting, subtracting, and adding	59
15.2	Division	61
15.2.1	Division using shifts	61
<b>16</b>	<b>Arrays</b>	<b>62</b>
16.1	Simple example	62
16.1.1	x86	62
16.2	Buffer overflow	63
16.2.1	Reading outside array bounds	63
16.2.2	Writing beyond array bounds	64

16.3	One more word about arrays	68
16.4	Array of pointers to strings	68
16.4.1	x64	68
16.5	Multidimensional arrays	70
16.5.1	Two-dimensional array example	70
16.5.2	Access two-dimensional array as one-dimensional	71
16.5.3	Three-dimensional array example	73
16.6	Conclusion	74
<b>17</b>	<b>Manipulating specific bit(s)</b>	<b>75</b>
17.1	Specific bit checking	75
17.1.1	x86	75
17.2	Setting and clearing specific bits	76
17.2.1	x86	76
17.3	Shifts	77
17.4	Counting bits set to 1	77
17.4.1	x86	78
17.4.2	x64	79
17.5	Conclusion	81
17.5.1	Check for specific bit (known at compile stage)	81
17.5.2	Check for specific bit (specified at runtime)	81
17.5.3	Set specific bit (known at compile stage)	82
17.5.4	Set specific bit (specified at runtime)	82
17.5.5	Clear specific bit (known at compile stage)	82
17.5.6	Clear specific bit (specified at runtime)	82
<b>18</b>	<b>Linear congruential generator</b>	<b>83</b>
18.1	x86	83
18.2	x64	84
<b>19</b>	<b>Structures</b>	<b>86</b>
19.1	MSVC: SYSTEMTIME example	86
19.1.1	Replacing the structure with array	87
19.2	Let's allocate space for a structure using malloc()	88
19.3	Fields packing in structure	90
19.3.1	x86	90
19.3.2	One more word	93
19.4	Nested structures	93
19.5	Bit fields in a structure	94
19.5.1	CPUID example	94
<b>20</b>	<b>64-bit values in 32-bit environment</b>	<b>98</b>
20.1	Returning of 64-bit value	98
20.1.1	x86	98
20.2	Arguments passing, addition, subtraction	98
20.2.1	x86	99
20.3	Multiplication, division	99
20.3.1	x86	100
20.4	Shifting right	100
20.4.1	x86	101
20.5	Converting 32-bit value into 64-bit one	101
20.5.1	x86	101
<b>21</b>	<b>64 bits</b>	<b>102</b>
21.1	x86-64	102
<b>II</b>	<b>Important fundamentals</b>	<b>103</b>
<b>22</b>	<b>Signed number representations</b>	<b>105</b>
<b>23</b>	<b>Memory</b>	<b>107</b>

<b>III Finding important/interesting stuff in the code</b>	<b>108</b>
<b>24 Communication with the outer world (win32)</b>	<b>110</b>
24.1 Often used functions in the Windows API	110
24.2 tracer: Intercepting all functions in specific module	111
<b>25 Strings</b>	<b>112</b>
25.1 Text strings	112
25.1.1 C/C++	112
25.1.2 Borland Delphi	112
25.1.3 Unicode	113
25.1.4 Base64	115
25.2 Error/debug messages	116
25.3 Suspicious magic strings	116
<b>26 Calls to assert()</b>	<b>117</b>
<b>27 Constants</b>	<b>118</b>
27.1 Magic numbers	118
27.1.1 DHCP	119
27.2 Searching for constants	119
<b>28 Finding the right instructions</b>	<b>120</b>
<b>29 Suspicious code patterns</b>	<b>122</b>
29.1 XOR instructions	122
29.2 Hand-written assembly code	122
<b>30 Using magic numbers while tracing</b>	<b>124</b>
<b>31 Other things</b>	<b>125</b>
31.1 General idea	125
31.2 Some binary file patterns	125
31.3 Memory “snapshots” comparing	126
31.3.1 Windows registry	127
31.3.2 Blink-comparator	127
<b>IV Tools</b>	<b>128</b>
<b>32 Disassembler</b>	<b>129</b>
32.1 IDA	129
<b>33 Debugger</b>	<b>130</b>
33.1 tracer	130
<b>34 Decompilers</b>	<b>131</b>
<b>35 Other tools</b>	<b>132</b>
<b>V Books/blogs worth reading</b>	<b>133</b>
<b>36 Books</b>	<b>134</b>
36.1 Windows	134
36.2 C/C++	134
36.3 x86 / x86-64	134
36.4 ARM	134
36.5 Cryptography	134
<b>37 Blogs</b>	<b>135</b>
37.1 Windows	135
<b>38 Other</b>	<b>136</b>

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<b>Afterword</b>	<b>138</b>
<b>39 Questions?</b>	<b>138</b>
<b>Acronyms used</b>	<b>141</b>
<b>Glossary</b>	<b>143</b>
<b>Index</b>	<b>144</b>
<b>Bibliography</b>	<b>146</b>

## Preface

There are several popular meanings of the term “reverse engineering”: 1) The reverse engineering of software: researching compiled programs; 2) The scanning of 3D structures and the subsequent digital manipulation required order to duplicate them; 3) recreating DBMS<sup>3</sup> structure. This book is about the first meaning.

### About the author



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### Praise for *Reverse Engineering for Beginners*

- “It’s very well done .. and for free .. amazing.”<sup>4</sup> Daniel Bilar, Siege Technologies, LLC.
- “... excellent and free”<sup>5</sup> Pete Finnigan, Oracle RDBMS security guru.
- “... book is interesting, great job!” Michael Sikorski, author of *Practical Malware Analysis: The Hands-On Guide to Dissecting Malicious Software*.
- “... my compliments for the very nice tutorial!” Herbert Bos, full professor at the Vrije Universiteit Amsterdam, co-author of *Modern Operating Systems (4th Edition)*.
- “... It is amazing and unbelievable.” Luis Rocha, CISSP / ISSAP, Technical Manager, Network & Information Security at Verizon Business.
- “Thanks for the great work and your book.” Joris van de Vis, SAP Netweaver & Security specialist.
- “... reasonable intro to some of the techniques.”<sup>6</sup> Mike Stay, teacher at the Federal Law Enforcement Training Center, Georgia, US.
- “I love this book! I have several students reading it at the moment, plan to use it in graduate course.”<sup>7</sup> Sergey Bratus, Research Assistant Professor at the Computer Science Department at Dartmouth College
- “Dennis @Yurichev has published an impressive (and free!) book on reverse engineering”<sup>8</sup> Tanel Poder, Oracle RDBMS performance tuning expert.
- “This book is some kind of Wikipedia to beginners...” Archer, Chinese Translator, IT Security Researcher.

### Thanks

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For translating the book into Simplified Chinese: Antiy Labs ([antiy.cn](http://antiy.cn)) and Archer.

For translating the book into Korean: Byungho Min.

<sup>3</sup>Database management systems

<sup>4</sup>[twitter.com/daniel\\_bilar/status/436578617221742593](https://twitter.com/daniel_bilar/status/436578617221742593)

<sup>5</sup>[twitter.com/petefinnigan/status/400551705797869568](https://twitter.com/petefinnigan/status/400551705797869568)

<sup>6</sup>[reddit](https://www.reddit.com/)

<sup>7</sup>[twitter.com/sergeybratus/status/505590326560833536](https://twitter.com/sergeybratus/status/505590326560833536)

<sup>8</sup>[twitter.com/TanelPoder/status/524668104065159169](https://twitter.com/TanelPoder/status/524668104065159169)

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Many  $\LaTeX$  packages were used: I would like to thank the authors as well.

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Those who supported me during the time when I wrote significant part of the book:

2 \* Oleg Vygovsky (50+100 UAH), Daniel Bilar (\$50), James Truscott (\$4.5), Luis Rocha (\$63), Joris van de Vis (\$127), Richard S Shultz (\$20), Jang Minchang (\$20), Shade Atlas (5 AUD), Yao Xiao (\$10), Pawel Szczur (40 CHF), Justin Simms (\$20), Shawn the R0ck (\$27), Ki Chan Ahn (\$50), Triop AB (100 SEK), Ange Albertini (€10+50), Sergey Lukianov (300 RUR), Ludvig Gislason (200 SEK), Gérard Labadie (€40), Sergey Volchkov (10 AUD), Vankayala Vigneswararao (\$50), Philippe Teuwen (\$4), Martin Haerberli (\$10), Victor Cazacov (€5), Tobias Sturzenegger (10 CHF), Sonny Thai (\$15), Bayna AlZaabi (\$75), Redfive B.V. (€25), Joonas Oskari Heikkilä (€5), Marshall Bishop (\$50), Nicolas Werner (€12), Jeremy Brown (\$100), Alexandre Borges (\$25), Vladimir Dikovski (€50), Jiarui Hong (100.00 SEK), Jim Di (500 RUR), Tan Vincent (\$30), Sri Harsha Kandrakota (10 AUD), Pillay Harish (10 SGD), Timur Valiev (230 RUR), Carlos Garcia Prado (€10), Salikov Alexander (500 RUR), Oliver Whitehouse (30 GBP), Katy Moe (\$14), Maxim Dyakonov (\$3), Sebastian Aguilera (€20), Hans-Martin Münch (€15), Jarle Thorsen (100 NOK), Vitaly Osipov (\$100), Yuri Romanov (1000 RUR), Aliaksandr Autayeu (€10), Tudor Azoitei (\$40), Z0vsky (€10), Yu Dai (\$10).

Thanks a lot to every donor!

## mini-FAQ

Q: Why should one learn assembly language these days?

A: Unless you are an [OS](#)<sup>9</sup> developer, you probably don't need to code in assembly—modern compilers are much better at performing optimizations than humans<sup>10</sup>. Also, modern [CPU](#)<sup>11</sup>s are very complex devices and assembly knowledge doesn't really help one to understand their internals. That being said, there are at least two areas where a good understanding of assembly can be helpful: First and foremost, security/malware research. It is also a good way to gain a better understanding of your compiled code whilst debugging. This book is therefore intended for those who want to understand assembly language rather than to code in it, which is why there are many examples of compiler output contained within.

Q: I clicked on a hyperlink inside a PDF-document, how do I go back?

A: In Adobe Acrobat Reader click Alt+LeftArrow.

Q: I'm not sure if I should try to learn reverse engineering or not.

A: Perhaps, the average time to become familiar with the contents of the shortened LITE-version is 1-2 month(s).

Q: May I print this book? Use it for teaching?

A: Of course! That's why the book is licensed under the Creative Commons license. One might also want to build one's own version of book—read [here](#) to find out more.

Q: I want to translate your book to some other language.

A: Read [my note to translators](#).

Q: How does one get a job in reverse engineering?

A: There are hiring threads that appear from time to time on reddit, devoted to RE<sup>12</sup> ([2013 Q3](#), [2014](#)). Try looking there. A somewhat related hiring thread can be found in the “netsec” subreddit: [2014 Q2](#).

Q: I have a question...

A: Send it to me by email ([dennis\(a\)yurichev.com](mailto:dennis(a)yurichev.com)).

<sup>9</sup>Operating System

<sup>10</sup>A very good text about this topic: [\[Fog13\]](#)

<sup>11</sup>Central processing unit

<sup>12</sup>[reddit.com/r/ReverseEngineering/](https://reddit.com/r/ReverseEngineering/)

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## About the Korean translation

In January 2015, the Acorn publishing company ([www.acornpub.co.kr](http://www.acornpub.co.kr)) in South Korea did a huge amount of work in translating and publishing my book (as it was in August 2014) into Korean.

It's now available at [their website](#).

The translator is Byungho Min ([twitter/tais9](https://twitter.com/tais9)).

The cover art was done by my artistic friend, Andy Nechaevsky : [facebook/andydinka](https://facebook.com/andydinka).

They also hold the copyright to the Korean translation.

So, if you want to have a *real* book on your shelf in Korean and want to support my work, it is now available for purchase.

## **Part I**

# **Code patterns**

When the author of this book first started learning C and, later, C++, he used to write small pieces of code, compile them, and then look at the assembly language output. This made it very easy for him to understand what was going on in the code that he had written.<sup>13</sup> He did it so many times that the relationship between the C/C++ code and what the compiler produced was imprinted deeply in his mind. It's easy to imagine instantly a rough outline of C code's appearance and function. Perhaps this technique could be helpful for others.

Sometimes ancient compilers are used here, in order to get the shortest (or simplest) possible code snippet.

## Optimization levels and debug information

Source code can be compiled by different compilers with various optimization levels. A typical compiler has about three such levels, where level zero means disable optimization. Optimization can also be targeted towards code size or code speed.

A non-optimizing compiler is faster and produces more understandable (albeit verbose) code, whereas an optimizing compiler is slower and tries to produce code that runs faster (but is not necessarily more compact).

In addition to optimization levels and direction, a compiler can include in the resulting file some debug information, thus producing code for easy debugging.

One of the important features of the 'debug' code is that it might contain links between each line of the source code and the respective machine code addresses. Optimizing compilers, on the other hand, tend to produce output where entire lines of source code can be optimized away and thus not even be present in the resulting machine code.

Reverse engineers can encounter either version, simply because some developers turn on the compiler's optimization flags and others do not. Because of this, we'll try to work on examples of both debug and release versions of the code featured in this book, where possible.

---

<sup>13</sup>In fact, he still does it when he can't understand what a particular bit of code does.

# Chapter 1

## A short introduction to the CPU

The **CPU** is the device that executes the machine code a program consists of.

### A short glossary:

**Instruction** : A primitive **CPU** command. The simplest examples include: moving data between registers, working with memory, primitive arithmetic operations . As a rule, each **CPU** has its own instruction set architecture (**ISA**<sup>1</sup>).

**Machine code** : Code that the **CPU** directly processes. Each instruction is usually encoded by several bytes.

**Assembly language** : Mnemonic code and some extensions like macros that are intended to make a programmer's life easier.

**CPU register** : Each **CPU** has a fixed set of general purpose registers (**GPR**<sup>2</sup>).  $\approx 8$  in x86,  $\approx 16$  in x86-64,  $\approx 16$  in ARM. The easiest way to understand a register is to think of it as an untyped temporary variable . Imagine if you were working with a high-level **PL**<sup>3</sup> and could only use eight 32-bit (or 64-bit) variables . Yet a lot can be done using just these!

One might wonder why there needs to be a difference between machine code and a **PL**. The answer lies in the fact that humans and **CPUs** are not alike— . It is much easier for humans to use a high-level **PL** like C/C++, Java, Python, etc., but it is easier for a **CPU** to use a much lower level of abstraction . Perhaps it would be possible to invent a **CPU** that can execute high-level **PL** code, but it would be many times more complex than the **CPUs** we know of today . In a similar fashion, it is very inconvenient for humans to write in assembly language, due to it being so low-level and difficult to write in without making a huge number of annoying mistakes. The program that converts the high-level **PL** code into assembly is called a *compiler*.

---

<sup>1</sup>Instruction Set Architecture

<sup>2</sup>General Purpose Registers

<sup>3</sup>Programming language

## Chapter 2

# The simplest Function

The simplest possible function is arguably one that simply returns a constant value:

Here it is:

Listing 2.1: C/C++ Code

```
int f()
{
    return 123;
};
```

Lets compile it!

### 2.1 x86

Here's what both the optimizing GCC and MSVC compilers produce on the x86 platform:

Listing 2.2: Optimizing GCC/MSVC (assembly output)

```
f:
    mov     eax, 123
    ret
```

There are just two instructions: the first places the value 123 into the EAX register, which is used by convention for storing the return value and the second one is RET, which returns execution to the [caller](#). The caller will take the result from the EAX register.

It is worth noting that MOV is a misleading name for the instruction in both x86 and ARM ISAs. The data is not in fact *moved*, but *copied*.

## Chapter 3

# Hello, world!

Let's use the famous example from the book "The C programming Language"[\[Ker88\]](#):

```
#include <stdio.h>

int main()
{
    printf("hello, world\n");
    return 0;
}
```

### 3.1 x86

#### 3.1.1 MSVC

Let's compile it in MSVC 2010:

```
cl 1.cpp /Fa1.asm
```

(/Fa option instructs the compiler to generate assembly listing file)

Listing 3.1: MSVC 2010

```
CONST SEGMENT
$SG3830 DB      'hello, world', 0AH, 00H
CONST ENDS
PUBLIC _main
EXTRN _printf:PROC
; Function compile flags: /Odtp
_TEXT SEGMENT
_main PROC
    push    ebp
    mov     ebp, esp
    push    OFFSET $SG3830
    call   _printf
    add     esp, 4
    xor     eax, eax
    pop     ebp
    ret     0
_main ENDP
_TEXT ENDS
```

The compiler generated the file, 1.obj, which is to be linked into 1.exe. In our case, the file contains two segments: CONST (for data constants) and \_TEXT (for code).

The string hello, world in C/C++ has type const char[] [\[Str13, p176, 7.3.2\]](#), but it does not have its own name. The compiler needs to deal with the string somehow so it defines the internal name \$SG3830 for it.

That is why the example may be rewritten as follows:

```
#include <stdio.h>

const char $SG3830[]="hello, world\n";

int main()
{
    printf($SG3830);
    return 0;
}
```

Let's go back to the assembly listing. As we can see, the string is terminated by a zero byte, which is standard for C/C++ strings. More about C strings: [25.1.1 on page 112](#).

In the code segment, `TEXT`, there is only one function so far: `main()`. The function `main()` starts with prologue code and ends with epilogue code (like almost any function)<sup>1</sup>.

After the function prologue we see the call to the `printf()` function: `CALL _printf`. Before the call the string address (or a pointer to it) containing our greeting is placed on the stack with the help of the `PUSH` instruction.

When the `printf()` function returns the control to the `main()` function, the string address (or a pointer to it) is still on the stack. Since we do not need it anymore, the [stack pointer](#) (the `ESP` register) needs to be corrected.

`ADD ESP, 4` means add 4 to the `ESP` register value. Why 4? Since this is a 32-bit program, we need exactly 4 bytes for address passing through the stack. If it was x64 code we would need 8 bytes. `ADD ESP, 4` is effectively equivalent to `POP register` but without using any register<sup>2</sup>.

For the same purpose, some compilers (like the Intel C++ Compiler) may emit `POP ECX` instead of `ADD` (e.g., such a pattern can be observed in the Oracle RDBMS code as it is compiled with the Intel C++ compiler). This instruction has almost the same effect but the `ECX` register contents will be overwritten. The Intel C++ compiler probably uses `POP ECX` since this instruction's opcode is shorter than `ADD ESP, x` (1 byte for `POP` against 3 for `ADD`).

Here is an example of using `POP` instead of `ADD` from Oracle RDBMS:

Listing 3.2: Oracle RDBMS 10.2 Linux (app.o file)

```
.text:0800029A      push    ebx
.text:0800029B      call   qksfroChild
.text:080002A0      pop     ecx
```

After calling `printf()`, the original C/C++ code contains the statement `return 0` – return 0 as the result of the `main()` function. In the generated code this is implemented by the instruction `XOR EAX, EAX`. `XOR` is in fact just “eXclusive OR”<sup>3</sup> but the compilers often use it instead of `MOV EAX, 0` – again because it is a slightly shorter opcode (2 bytes for `XOR` against 5 for `MOV`).

Some compilers emit `SUB EAX, EAX`, which means *SUBtract the value in the EAX from the value in EAX*, which, in any case, results in zero.

The last instruction `RET` returns the control to the [caller](#). Usually, this is C/C++ [CRT](#)<sup>4</sup> code, which, in turn, returns control to the [OS](#).

## 3.2 x86-64

### 3.2.1 MSVC–x86-64

Let's also try 64-bit MSVC:

Listing 3.3: MSVC 2012 x64

```
$SG2989 DB      'hello, world', 0AH, 00H

main PROC
    sub     rsp, 40
    lea    rcx, OFFSET FLAT:$SG2989
    call   printf
    xor     eax, eax
```

<sup>1</sup>You can read more about it in the section about function prologues and epilogues ( [4 on page 8](#) ).

<sup>2</sup>CPU flags, however, are modified

<sup>3</sup>[wikipedia](#)

<sup>4</sup>C runtime library

```

    add    rsp, 40
    ret    0
main     ENDP

```

In x86-64, all registers were extended to 64-bit and now their names have an R- prefix. In order to use the stack less often (in other words, to access external memory/cache less often), there exists a popular way to pass function arguments via registers (fastcall). I.e., a part of the function arguments is passed in registers, the rest—via the stack. In Win64, 4 function arguments are passed in the RCX, RDX, R8, R9 registers. That is what we see here: a pointer to the string for `printf()` is now passed not in the stack, but in the RCX register.

The pointers are 64-bit now, so they are passed in the 64-bit registers (which have the R- prefix). However, for backward compatibility, it is still possible to access the 32-bit parts, using the E- prefix.

This is how the RAX/EAX/AX/AL register looks like in x86-64:

7th (byte number)	6th	5th	4th	3rd	2nd	1st	0th
RAX <sup>x64</sup>							
				EAX			
						AX	
						AH	AL

The `main()` function returns an *int*-typed value, which is, in C/C++, for better backward compatibility and portability, still 32-bit, so that is why the EAX register is cleared at the function end (i.e., the 32-bit part of the register) instead of RAX.

There are also 40 bytes allocated in the local stack. This is called the “shadow space”, about which we are going to talk later: [8.2.1 on page 29](#).

### 3.3 Conclusion

The main difference between x86/ARM and x64/ARM64 code is that the pointer to the string is now 64-bits in length. Indeed, modern CPUs are now 64-bit due to both the reduced cost of memory and the greater demand for it by modern applications. We can add much more memory to our computers than 32-bit pointers are able to address. As such, all pointers are now 64-bit.

## Chapter 4

# Function prologue and epilogue

A function prologue is a sequence of instructions at the start of a function. It often looks something like the following code fragment:

```
push    ebp
mov     ebp, esp
sub     esp, X
```

What these instructions do: save the value in the EBP register, set the value of the EBP register to the value of the ESP and then allocate space on the stack for local variables.

The value in the EBP stays the same over the period of the function execution and is to be used for local variables and arguments access. For the same purpose one can use ESP, but since it changes over time this approach is not too convenient.

The function epilogue frees the allocated space in the stack, returns the value in the EBP register back to its initial state and returns the control flow to the [callee](#):

```
mov     esp, ebp
pop     ebp
ret     0
```

Function prologues and epilogues are usually detected in disassemblers for function delimitation.

### 4.1 Recursion

Epilogues and prologues can negatively affect the recursion performance.

More about recursion in this book: ?? on page ??.

## Chapter 5

# Stack

The stack is one of the most fundamental data structures in computer science<sup>1</sup>.

Technically, it is just a block of memory in process memory along with the ESP or RSP register in x86 or x64, or the SP<sup>2</sup> register in ARM, as a pointer within that block.

The most frequently used stack access instructions are PUSH and POP (in both x86 and ARM Thumb-mode). PUSH subtracts from ESP/RSP/SP 4 in 32-bit mode (or 8 in 64-bit mode) and then writes the contents of its sole operand to the memory address pointed by ESP/RSP/SP.

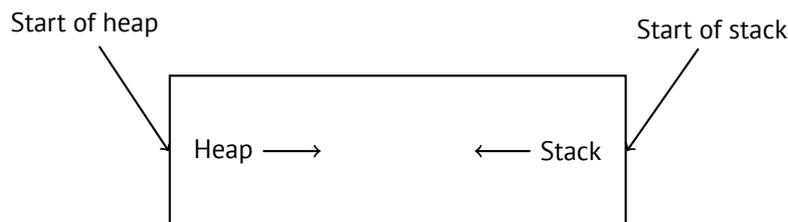
POP is the reverse operation: retrieve the data from the memory location that SP points to, load it into the instruction operand (often a register) and then add 4 (or 8) to the [stack pointer](#).

After stack allocation, the [stack pointer](#) points at the bottom of the stack. PUSH decreases the [stack pointer](#) and POP increases it. The bottom of the stack is actually at the beginning of the memory allocated for the stack block. It seems strange, but that's the way it is.

### 5.1 Why does the stack grow backwards?

Intuitively, we might think that the stack grows upwards, i.e. towards higher addresses, like any other data structure.

The reason that the stack grows backward is probably historical. When the computers were big and occupied a whole room, it was easy to divide memory into two parts, one for the [heap](#) and one for the stack. Of course, it was unknown how big the [heap](#) and the stack would be during program execution, so this solution was the simplest possible.



In [\[RT74\]](#) we can read:

The user-core part of an image is divided into three logical segments. The program text segment begins at location 0 in the virtual address space. During execution, this segment is write-protected and a single copy of it is shared among all processes executing the same program. At the first 8K byte boundary above the program text segment in the virtual address space begins a nonshared, writable data segment, the size of which may be extended by a system call. Starting at the highest address in the virtual address space is a stack segment, which automatically grows downward as the hardware's stack pointer fluctuates.

This reminds us how some students write two lecture notes using only one notebook: notes for the first lecture are written as usual, and notes for the second one are written from the end of notebook, by flipping it. Notes may meet each other somewhere in between, in case of lack of free space.

<sup>1</sup>[wikipedia.org/wiki/Call\\_stack](https://wikipedia.org/wiki/Call_stack)

<sup>2</sup>[stack pointer](#). SP/ESP/RSP in x86/x64. SP in ARM.

## 5.2 What is the stack used for?

### 5.2.1 Save the function's return address

#### x86

When calling another function with a CALL instruction, the address of the point exactly after the CALL instruction is saved to the stack and then an unconditional jump to the address in the CALL operand is executed.

The CALL instruction is equivalent to a PUSH `address_after_call` / JMP operand instruction pair.

RET fetches a value from the stack and jumps to it –that is equivalent to a POP `tmp` / JMP `tmp` instruction pair.

Overflowing the stack is straightforward. Just run eternal recursion:

```
void f()
{
    f();
};
```

MSVC 2008 reports the problem:

```
c:\tmp6>cl ss.cpp /Fass.asm
Microsoft (R) 32-bit C/C++ Optimizing Compiler Version 15.00.21022.08 for 80x86
Copyright (C) Microsoft Corporation. All rights reserved.

ss.cpp
c:\tmp6\ss.cpp(4) : warning C4717: 'f' : recursive on all control paths, function will cause ↵
↳ runtime stack overflow
```

...but generates the right code anyway:

```
?f@@YAXXZ PROC ; f
; File c:\tmp6\ss.cpp
; Line 2
    push    ebp
    mov     ebp, esp
; Line 3
    call   ?f@@YAXXZ ; f
; Line 4
    pop     ebp
    ret     0
?f@@YAXXZ ENDP ; f
```

... Also if we turn on the compiler optimization (/Ox option) the optimized code will not overflow the stack and will work *correctly*<sup>3</sup> instead:

```
?f@@YAXXZ PROC ; f
; File c:\tmp6\ss.cpp
; Line 2
$LL3@f:
; Line 3
    jmp     SHORT $LL3@f
?f@@YAXXZ ENDP ; f
```

### 5.2.2 Passing function arguments

The most popular way to pass parameters in x86 is called “cdecl”:

```
push arg3
push arg2
push arg1
call f
add esp, 12 ; 4*3=12
```

<sup>3</sup>irony here

**Callee** functions get their arguments via the stack pointer.

Therefore, this is how the argument values are located in the stack before the execution of the `f()` function's very first instruction:

ESP	return address
ESP+4	argument#1, marked in IDA <sup>4</sup> as <code>arg_0</code>
ESP+8	argument#2, marked in IDA as <code>arg_4</code>
ESP+0xC	argument#3, marked in IDA as <code>arg_8</code>
...	...

It is worth noting that nothing obliges programmers to pass arguments through the stack. It is not a requirement. One could implement any other method without using the stack at all.

For example, it is possible to allocate a space for arguments in the **heap**, fill it and pass it to a function via a pointer to this block in the EAX register. This will work<sup>5</sup>. However, it is a convenient custom in x86 and ARM to use the stack for this purpose.

By the way, the **callee** function does not have any information about how many arguments were passed. C functions with a variable number of arguments (like `printf()`) determine their number using format string specifiers (which begin with the `%` symbol). If we write something like

```
printf("%d %d %d", 1234);
```

`printf()` will print 1234, and then two random numbers, which were lying next to it in the stack.

That's why it is not very important how we declare the `main()` function: as `main()`, `main(int argc, char *argv[])` or `main(int argc, char *argv[], char *envp[])`.

In fact, the **CRT**-code is calling `main()` roughly as:

```
push envp
push argv
push argc
call main
...
```

If you declare `main()` as `main()` without arguments, they are, nevertheless, still present in the stack, but are not used. If you declare `main()` as `main(int argc, char *argv[])`, you will be able to use first two arguments, and the third will remain "invisible" for your function. Even more, it is possible to declare `main(int argc)`, and it will work.

### 5.2.3 Local variable storage

A function could allocate space in the stack for its local variables just by decreasing the **stack pointer** towards the stack bottom. Hence, it's very fast, no matter how many local variables are defined.

It is also not a requirement to store local variables in the stack. You could store local variables wherever you like, but traditionally this is how it's done.

### 5.2.4 x86: `alloca()` function

It is worth noting the `alloca()` function<sup>6</sup>.

This function works like `malloc()`, but allocates memory directly on the stack.

The allocated memory chunk does not need to be freed via a `free()` function call, since the function epilogue (4 on page 8) returns ESP back to its initial state and the allocated memory is just *dropped*.

It is worth noting how `alloca()` is implemented.

In simple terms, this function just shifts ESP downwards toward the stack bottom by the number of bytes you need and sets ESP as a pointer to the *allocated* block. Let's try:

<sup>5</sup>For example, in the "The Art of Computer Programming" book by Donald Knuth, in section 1.4.1 dedicated to subroutines [Knu98, section 1.4.1], we could read that one way to supply arguments to a subroutine is simply to list them after the JMP instruction passing control to subroutine. Knuth explains that this method was particularly convenient on IBM System/360.

<sup>6</sup>In MSVC, the function implementation can be found in `alloca16.asm` and `chkstk.asm` in `C:\Program Files (x86)\Microsoft Visual Studio 10.0\VC\crt\src\intel`

```

#ifdef __GNUC__
#include <alloca.h> // GCC
#else
#include <malloc.h> // MSVC
#endif
#include <stdio.h>

void f()
{
    char *buf=(char*)alloca (600);
#ifdef __GNUC__
    snprintf (buf, 600, "hi! %d, %d, %d\n", 1, 2, 3); // GCC
#else
    _snprintf (buf, 600, "hi! %d, %d, %d\n", 1, 2, 3); // MSVC
#endif

    puts (buf);
};

```

`_snprintf()` function works just like `printf()`, but instead of dumping the result into `stdout` (e.g., to terminal or console), it writes it to the `buf` buffer. Function `puts()` copies the contents of `buf` to `stdout`. Of course, these two function calls might be replaced by one `printf()` call, but we have to illustrate small buffer usage.

## MSVC

Let's compile (MSVC 2010):

Listing 5.1: MSVC 2010

```

...
mov     eax, 600           ; 00000258H
call    __alloca_probe_16
mov     esi, esp

push   3
push   2
push   1
push   OFFSET $SG2672
push   600                ; 00000258H
push   esi
call   __snprintf

push   esi
call   _puts
add    esp, 28            ; 0000001cH
...

```

The sole `alloca()` argument is passed via `EAX` (instead of pushing it into the stack)<sup>7</sup>. After the `alloca()` call, `ESP` points to the block of 600 bytes and we can use it as memory for the `buf` array.

### 5.2.5 (Windows) SEH

`SEH`<sup>10</sup> records are also stored on the stack (if they are present)..

### 5.2.6 Buffer overflow protection

More about it here ([16.2 on page 63](#)).

<sup>7</sup>It is because `alloca()` is rather a compiler intrinsic than a normal function.

One of the reasons we need a separate function instead of just a couple of instructions in the code, is because the `MSVC`<sup>8</sup> `alloca()` implementation also has code which reads from the memory just allocated, in order to let the `OS` map physical memory to this `VM`<sup>9</sup> region.

<sup>10</sup>Structured Exception Handling

## 5.2.7 Automatic deallocation of data in stack

Perhaps, the reason for storing local variables and SEH records in the stack is that they are freed automatically upon function exit, using just one instruction to correct the stack pointer (it is often ADD). Function arguments, as we could say, are also deallocated automatically at the end of function. In contrast, everything stored in the *heap* must be deallocated explicitly.

## 5.3 A typical stack layout

A typical stack layout in a 32-bit environment at the start of a function, before the first instruction execution looks like this:

...	...
ESP-0xC	local variable #2, marked in IDA as var_8
ESP-8	local variable #1, marked in IDA as var_4
ESP-4	saved value of EBP
ESP	return address
ESP+4	argument#1, marked in IDA as arg_0
ESP+8	argument#2, marked in IDA as arg_4
ESP+0xC	argument#3, marked in IDA as arg_8
...	...

## Chapter 6

# printf() with several arguments

Now let's extend the *Hello, world!* (3 on page 5) example, replacing `printf()` in the `main()` function body with this:

```
#include <stdio.h>

int main()
{
    printf("a=%d; b=%d; c=%d", 1, 2, 3);
    return 0;
};
```

### 6.1 x86

#### 6.1.1 x86: 3 arguments

##### MSVC

When we compile it with MSVC 2010 Express we get:

```
$SG3830 DB      'a=%d; b=%d; c=%d', 00H
...
    push    3
    push    2
    push    1
    push    OFFSET $SG3830
    call    _printf
    add     esp, 16                ; 00000010H
```

Almost the same, but now we can see the `printf()` arguments are pushed onto the stack in reverse order. The first argument is pushed last.

By the way, variables of *int* type in 32-bit environment have 32-bit width, that is 4 bytes.

So, we have 4 arguments here.  $4 * 4 = 16$  –they occupy exactly 16 bytes in the stack: a 32-bit pointer to a string and 3 numbers of type *int*.

When the [stack pointer](#) (ESP register) has changed back by the `ADD ESP, X` instruction after a function call, often, the number of function arguments could be deduced by simply dividing *X* by 4.

Of course, this is specific to the *cdecl* calling convention, and only for 32-bit environment.

In certain cases where several functions return right after one another, the compiler could merge multiple “`ADD ESP, X`” instructions into one, after the last call:

```
push a1
push a2
call ...
...
push a1
call ...
```

```
...
push a1
push a2
push a3
call ...
add esp, 24
```

Here is a real-world example:

Listing 6.1: x86

```
.text:100113E7      push     3
.text:100113E9      call    sub_100018B0 ; takes one argument (3)
.text:100113EE      call    sub_100019D0 ; takes no arguments at all
.text:100113F3      call    sub_10006A90 ; takes no arguments at all
.text:100113F8      push     1
.text:100113FA      call    sub_100018B0 ; takes one argument (1)
.text:100113FF      add     esp, 8      ; drops two arguments from stack at once
```

## 6.1.2 x64: 8 arguments

To see how other arguments are passed via the stack, let's change our example again by increasing the number of arguments to 9 (`printf()` format string + 8 *int* variables):

```
#include <stdio.h>

int main()
{
    printf("a=%d; b=%d; c=%d; d=%d; e=%d; f=%d; g=%d; h=%d\n", 1, 2, 3, 4, 5, 6, 7, 8);
    return 0;
};
```

## MSVC

As it was mentioned earlier, the first 4 arguments has to be passed through the RCX, RDX, R8, R9 registers in Win64, while all the rest—via the stack. That is exactly what we see here. However, the MOV instruction, instead of PUSH, is used for preparing the stack, so the values are stored to the stack in a straightforward manner.

Listing 6.2: MSVC 2012 x64

```
$SG2923 DB      'a=%d; b=%d; c=%d; d=%d; e=%d; f=%d; g=%d; h=%d', 0aH, 00H

main      PROC
          sub     rsp, 88

          mov     DWORD PTR [rsp+64], 8
          mov     DWORD PTR [rsp+56], 7
          mov     DWORD PTR [rsp+48], 6
          mov     DWORD PTR [rsp+40], 5
          mov     DWORD PTR [rsp+32], 4
          mov     r9d, 3
          mov     r8d, 2
          mov     edx, 1
          lea    rcx, OFFSET FLAT:$SG2923
          call   printf

          ; return 0
          xor     eax, eax

          add     rsp, 88
          ret     0
main      ENDP
_TEXT    ENDS
END
```

The observant reader may ask why are 8 bytes allocated for *int* values, when 4 is enough? Yes, one has to remember: 8 bytes are allocated for any data type shorter than 64 bits. This is established for the convenience's sake: it makes it easy to

calculate the address of arbitrary argument. Besides, they are all located at aligned memory addresses. It is the same in the 32-bit environments: 4 bytes are reserved for all data types.

## 6.2 Conclusion

Here is a rough skeleton of the function call:

Listing 6.3: x86

```
...  
PUSH 3rd argument  
PUSH 2nd argument  
PUSH 1st argument  
CALL function  
; modify stack pointer (if needed)
```

Listing 6.4: x64 (MSVC)

```
MOV RCX, 1st argument  
MOV RDX, 2nd argument  
MOV R8, 3rd argument  
MOV R9, 4th argument  
...  
PUSH 5th, 6th argument, etc (if needed)  
CALL function  
; modify stack pointer (if needed)
```

## 6.3 By the way

By the way, this difference between the arguments passing in x86, x64, fastcall, ARM and MIPS is a good illustration of the fact that the CPU is oblivious to how the arguments are passed to functions. It is also possible to create a hypothetical compiler able to pass arguments via a special structure without using stack at all.

The [CPU](#) is not aware of calling conventions whatsoever.

We may also recall how newcomers assembly language programmers passing arguments into other functions: usually via registers, without any explicit order, or even via global variables. Of course, it works fine.

## Chapter 7

# scanf()

Now let's use `scanf()`.

### 7.1 Simple example

```
#include <stdio.h>

int main()
{
    int x;
    printf ("Enter X:\n");

    scanf ("%d", &x);

    printf ("You entered %d...\n", x);

    return 0;
};
```

It's not clever to use `scanf()` for user interactions nowadays. But we can, however, illustrate passing a pointer to a variable of type `int`.

#### 7.1.1 About pointers

Pointers are one of the fundamental concepts in computer science. Often, passing a large array, structure or object as an argument to another function is too expensive, while passing their address is much cheaper. In addition if the [callee](#) function needs to modify something in the large array or structure received as a parameter and return back the entire structure then the situation is close to absurd. So the simplest thing to do is to pass the address of the array or structure to the [callee](#) function, and let it change what needs to be changed.

A pointer in C/C++ is simply an address of some memory location.

In x86, the address is represented as a 32-bit number (i.e., it occupies 4 bytes), while in x86-64 it is a 64-bit number (occupying 8 bytes). By the way, that is the reason behind some people's indignation related to switching to x86-64—all pointers in the x64-architecture require twice as much space, including cache memory, which is "expensive" place.

It is possible to work with untyped pointers only, given some effort; e.g. the standard C function `memcpy()`, that copies a block from one memory location to another, takes 2 pointers of type `void*` as arguments, since it is impossible to predict the type of the data you would like to copy. Data types are not important, only the block size matters.

Pointers are also widely used when a function needs to return more than one value (we are going to get back to this later). `scanf()` is such a case. Besides the fact that the function needs to indicate how many values were successfully read, it also needs to return all these values.

In C/C++ the pointer type is only needed for compile-time type checking. Internally, in the compiled code there is no information about pointer types at all.

**7.1.2 x86****MSVC**

Here is what we get after compiling with MSVC 2010:

```

CONST    SEGMENT
$SG3831  DB    'Enter X:', 0aH, 00H
$SG3832  DB    '%d', 00H
$SG3833  DB    'You entered %d...', 0aH, 00H
CONST    ENDS
PUBLIC   _main
EXTRN   _scanf:PROC
EXTRN   _printf:PROC
; Function compile flags: /Odtp
_TEXT   SEGMENT
_x$ = -4                                ; size = 4
_main   PROC
    push    ebp
    mov     ebp, esp
    push    ecx
    push    OFFSET $SG3831 ; 'Enter X:'
    call    _printf
    add     esp, 4
    lea    eax, DWORD PTR _x$[ebp]
    push    eax
    push    OFFSET $SG3832 ; '%d'
    call    _scanf
    add     esp, 8
    mov     ecx, DWORD PTR _x$[ebp]
    push    ecx
    push    OFFSET $SG3833 ; 'You entered %d...'
    call    _printf
    add     esp, 8

    ; return 0
    xor     eax, eax
    mov     esp, ebp
    pop     ebp
    ret     0
_main    ENDP
_TEXT    ENDS

```

x is a local variable.

According to the C/C++ standard it must be visible only in this function and not from any other external scope. Traditionally, local variables are stored on the stack. There are probably other ways to allocate them, but in x86 that is the way it is.

The goal of the instruction following the function prologue, PUSH ECX, is not to save the ECX state (notice the absence of corresponding POP ECX at the function's end).

In fact it allocates 4 bytes on the stack for storing the x variable.

x is to be accessed with the assistance of the \_x\$ macro (it equals to -4) and the EBP register pointing to the current frame.

Over the span of the function's execution, EBP is pointing to the current [stack frame](#) making it possible to access local variables and function arguments via EBP+offset.

It is also possible to use ESP for the same purpose, although that is not very convenient since it changes frequently. The value of the EBP could be perceived as a *frozen state* of the value in ESP at the start of the function's execution.

Here is a typical [stack frame](#) layout in 32-bit environment:

...	...
EBP-8	local variable #2, marked in <a href="#">IDA</a> as var_8
EBP-4	local variable #1, marked in <a href="#">IDA</a> as var_4
EBP	saved value of EBP
EBP+4	return address
EBP+8	argument#1, marked in <a href="#">IDA</a> as arg_0
EBP+0xC	argument#2, marked in <a href="#">IDA</a> as arg_4
EBP+0x10	argument#3, marked in <a href="#">IDA</a> as arg_8
...	...

The `scanf()` function in our example has two arguments.

The first one is a pointer to the string containing `%d` and the second is the address of the `x` variable.

First, the `x` variable's address is loaded into the `EAX` register by the `lea eax, DWORD PTR _x$[ebp]` instruction

We could say that in this case `LEA` simply stores the sum of the `EBP` register value and the `_x$` macro in the `EAX` register.

This is the same as `lea eax, [ebp-4]`.

So, 4 is being subtracted from the `EBP` register value and the result is loaded in the `EAX` register. Next the `EAX` register value is pushed into the stack and `scanf()` is being called.

`printf()` is being called after that with its first argument – a pointer to the string: `You entered %d...\n`.

The second argument is prepared with: `mov ecx, [ebp-4]`. The instruction stores the `x` variable value and not its address, in the `ECX` register.

Next the value in the `ECX` is stored on the stack and the last `printf()` is being called.

### By the way

By the way, this simple example is a demonstration of the fact that compiler translates list of expressions in C/C++-block into sequential list of instructions. There are nothing between expressions in C/C++, and so in resulting machine code, there are nothing between, control flow slips from one expression to the next one.

### 7.1.3 x64

The picture here is similar with the difference that the registers, rather than the stack, are used for arguments passing.

### MSVC

Listing 7.1: MSVC 2012 x64

```

_DATA SEGMENT
$SG1289 DB 'Enter X:', 0aH, 00H
$SG1291 DB '%d', 00H
$SG1292 DB 'You entered %d...', 0aH, 00H
_DATA ENDS

_TEXT SEGMENT
x$ = 32
main PROC
$LN3:
    sub    rsp, 56
    lea   rcx, OFFSET FLAT:$SG1289 ; 'Enter X:'
    call  printf
    lea   rdx, QWORD PTR x$[rsp]
    lea   rcx, OFFSET FLAT:$SG1291 ; '%d'
    call  scanf
    mov   edx, DWORD PTR x$[rsp]
    lea   rcx, OFFSET FLAT:$SG1292 ; 'You entered %d...'
    call  printf

    ; return 0
    xor   eax, eax
    add   rsp, 56
    ret   0
main    ENDP
_TEXT  ENDS

```

## 7.2 Global variables

What if the `x` variable from the previous example was not local but a global one? Then it would have been accessible from any point, not only from the function body. Global variables are considered [anti-pattern](#), but for the sake of the experiment, we could do this.

```
#include <stdio.h>

// now x is global variable
int x;

int main()
{
    printf ("Enter X:\n");

    scanf ("%d", &x);

    printf ("You entered %d...\n", x);

    return 0;
};
```

## 7.2.1 MSVC: x86

```
_DATA    SEGMENT
COMM     _x:DWORD
$SG2456  DB     'Enter X:', 0aH, 00H
$SG2457  DB     '%d', 00H
$SG2458  DB     'You entered %d...', 0aH, 00H
_DATA    ENDS
PUBLIC   _main
EXTRN   _scanf:PROC
EXTRN   _printf:PROC
; Function compile flags: /Odtp
_TEXT    SEGMENT
_main    PROC
    push  ebp
    mov   ebp, esp
    push  OFFSET $SG2456
    call  _printf
    add   esp, 4
    push  OFFSET _x
    push  OFFSET $SG2457
    call  _scanf
    add   esp, 8
    mov   eax, DWORD PTR _x
    push  eax
    push  OFFSET $SG2458
    call  _printf
    add   esp, 8
    xor   eax, eax
    pop   ebp
    ret   0
_main    ENDP
_TEXT    ENDS
```

In this case the `x` variable is defined in the `_DATA` segment and no memory is allocated in the local stack. It is accessed directly, not through the stack. Uninitialized global variables take no space in the executable file (indeed, why one needs to allocate space for variables initially set to zero?), but when someone accesses their address, the `OS` will allocate a block of zeroes there<sup>1</sup>.

Now let's explicitly assign a value to the variable:

```
int x=10; // default value
```

We got:

```
_DATA    SEGMENT
_x       DD     0aH
...

```

<sup>1</sup>That is how a `VM` behaves

Here we see a value 0xA of DWORD type (DD stands for DWORD = 32 bit) for this variable.

If you open the compiled .exe in [IDA](#), you can see the *x* variable placed at the beginning of the `._DATA` segment, and after it you can see text strings.

If you open the compiled .exe from the previous example in [IDA](#), where the value of *x* was not set, you would see something like this:

```
.data:0040FA80 _x          dd ?          ; DATA XREF: _main+10
.data:0040FA80          ; _main+22
.data:0040FA84 dword_40FA84  dd ?          ; DATA XREF: _memset+1E
.data:0040FA84          ; unknown_libname_1+28
.data:0040FA88 dword_40FA88  dd ?          ; DATA XREF: ___sbh_find_block+5
.data:0040FA88          ; ___sbh_free_block+2BC
.data:0040FA8C ; LPVOID lpMem
.data:0040FA8C lpMem        dd ?          ; DATA XREF: ___sbh_find_block+B
.data:0040FA8C          ; ___sbh_free_block+2CA
.data:0040FA90 dword_40FA90  dd ?          ; DATA XREF: _V6_HeapAlloc+13
.data:0040FA90          ; __calloc_impl+72
.data:0040FA94 dword_40FA94  dd ?          ; DATA XREF: ___sbh_free_block+2FE
```

`_x` is marked with `?` with the rest of the variables that do not need to be initialized. This implies that after loading the .exe to the memory, a space for all these variables is to be allocated and filled with zeroes [[ISO07](#), 6.7.8p10]. But in the .exe file these uninitialized variables do not occupy anything. This is convenient for large arrays, for example.

## 7.2.2 MSVC: x64

Listing 7.2: MSVC 2012 x64

```
_DATA SEGMENT
COMM  x:DWORD
$SG2924 DB      'Enter X:', 0aH, 00H
$SG2925 DB      '%d', 00H
$SG2926 DB      'You entered %d...', 0aH, 00H
_DATA ENDS

_TEXT SEGMENT
main  PROC
$LN3:
    sub     rsp, 40

    lea    rcx, OFFSET FLAT:$SG2924 ; 'Enter X:'
    call   printf
    lea    rdx, OFFSET FLAT:x
    lea    rcx, OFFSET FLAT:$SG2925 ; '%d'
    call   scanf
    mov    edx, DWORD PTR x
    lea    rcx, OFFSET FLAT:$SG2926 ; 'You entered %d...'
    call   printf

    ; return 0
    xor    eax, eax

    add    rsp, 40
    ret    0
main    ENDP
_TEXT ENDS
```

The code is almost the same as in x86. Please note that the address of the *x* variable is passed to `scanf()` using a LEA instruction, while the variable's value is passed to the second `printf()` using a MOV instruction. `DWORD PTR` is a part of the assembly language (no relation to the machine code), indicating that the variable data size is 32-bit and the MOV instruction has to be encoded accordingly.

## 7.3 scanf() result checking

As was noted before, it is slightly old-fashioned to use `scanf()` today. But if we have to, we need to at least check if `scanf()` finishes correctly without an error.

```
#include <stdio.h>

int main()
{
    int x;
    printf ("Enter X:\n");

    if (scanf ("%d", &x)==1)
        printf ("You entered %d...\n", x);
    else
        printf ("What you entered? Huh?\n");

    return 0;
};
```

By standard, the `scanf()`<sup>2</sup> function returns the number of fields it has successfully read.

In our case, if everything goes fine and the user enters a number `scanf()` returns 1, or in case of error (or `EOF`<sup>3</sup>) – 0.

Let's add some C code to check the `scanf()` return value and print error message in case of an error.

This works as expected:

```
C:\...>ex3.exe
Enter X:
123
You entered 123...

C:\...>ex3.exe
Enter X:
ouch
What you entered? Huh?
```

### 7.3.1 MSVC: x86

Here is what we get in the assembly output (MSVC 2010):

```
    lea    eax, DWORD PTR _x$[ebp]
    push  eax
    push  OFFSET $SG3833 ; '%d', 00H
    call  _scanf
    add   esp, 8
    cmp   eax, 1
    jne   SHORT $LN2@main
    mov   ecx, DWORD PTR _x$[ebp]
    push  ecx
    push  OFFSET $SG3834 ; 'You entered %d...', 0aH, 00H
    call  _printf
    add   esp, 8
    jmp   SHORT $LN1@main
$LN2@main:
    push  OFFSET $SG3836 ; 'What you entered? Huh?', 0aH, 00H
    call  _printf
    add   esp, 4
$LN1@main:
    xor   eax, eax
```

The `caller` function (`main()`) needs the `callee` function (`scanf()`) result, so the `callee` returns it in the EAX register.

We check it with the help of the instruction `CMP EAX, 1` (*CoMPare*). In other words, we compare the value in the EAX register with 1.

A JNE conditional jump follows the `CMP` instruction. JNE stands for *Jump if Not Equal*.

So, if the value in the EAX register is not equal to 1, the CPU will pass the execution to the address mentioned in the JNE operand, in our case `$LN2@main`. Passing the control to this address results in the CPU executing `printf()` with the

<sup>2</sup>`scanf`, `wscanf`: [MSDN](#)

<sup>3</sup>End of file

argument What you entered? Huh?. But if everything is fine, the conditional jump is not to be taken, and another `printf()` call is to be executed, with two arguments: 'You entered %d. . .' and the value of `x`.

Since in this case the second `printf()` has not to be executed, there is a `JMP` preceding it (unconditional jump). It passes the control to the point after the second `printf()` and just before the `XOR EAX, EAX` instruction, which implements `return 0`.

So, it could be said that comparing a value with another is *usually* implemented by `CMP/Jcc` instruction pair, where *cc* is *condition code*. `CMP` compares two values and sets processor flags<sup>4</sup>. `Jcc` checks those flags and decides to either pass the control to the specified address or not.

This could sound paradoxical, but the `CMP` instruction is in fact `SUB` (subtract). All arithmetic instructions set processor flags, not just `CMP`. If we compare 1 and 1,  $1 - 1$  is 0 so the `ZF` flag would be set (meaning that the last result was 0). In no other circumstances `ZF` can be set, except when the operands are equal. `JNE` checks only the `ZF` flag and jumps only if it is not set. `JNE` is in fact a synonym for `JNZ` (*Jump if Not Zero*). Assembler translates both `JNE` and `JNZ` instructions into the same opcode. So, the `CMP` instruction can be replaced with a `SUB` instruction and almost everything will be fine, with the difference that `SUB` alters the value of the first operand. `CMP` is *SUB without saving the result, but affecting flags*.

---

<sup>4</sup>x86 flags, see also: [wikipedia](https://en.wikipedia.org/wiki/x86_registers).

### 7.3.2 MSVC: x86 + Hiew

This can also be used as a simple example of executable file patching. We may try to patch the executable so the program would always print the input, no matter what we enter.

Assuming that the executable is compiled against external MSVCR\*.DLL (i.e., with /MD option)<sup>5</sup>, we see the `main()` function at the beginning of the `.text` section. Let's open the executable in Hiew and find the beginning of the `.text` section (Enter, F8, F6, Enter, Enter).

We can see this:

```

Hiew: ex3.exe
C:\Polygon\ollydbg\ex3.exe  FRO ----- a32 PE .00401000 Hiew 8.02 (c)SEN
.00401000: 55          push    ebp
.00401001: 8BEC       mov     ebp,esp
.00401003: 51        push    ecx
.00401004: 6800304000 push    000403000 ;'Enter X:' --1
.00401009: FF1594204000 call   printf
.0040100F: 83C404    add     esp,4
.00401012: 8D45FC    lea    eax,[ebp][-4]
.00401015: 50        push    eax
.00401016: 680C304000 push    00040300C --2
.0040101B: FF158C204000 call   scanf
.00401021: 83C408    add     esp,8
.00401024: 83F801    cmp     eax,1
.00401027: 7514     jnz    .0040103D --3
.00401029: 8B4DFC    mov     ecx,[ebp][-4]
.0040102C: 51        push    ecx
.0040102D: 6810304000 push    000403010 ;'You entered %d...' --4
.00401032: FF1594204000 call   printf
.00401038: 83C408    add     esp,8
.0040103B: EB0E     jmps   .0040104B --5
.0040103D: 6824304000 3push  000403024 ;'What you entered? Huh?' --6
.00401042: FF1594204000 call   printf
.00401048: 83C404    add     esp,4
.0040104B: 33C0     5xor    eax,eax
.0040104D: 8BE5     mov     esp,ebp
.0040104F: 5D        pop     ebp
.00401050: C3      retn   ; ^^^^
.00401051: B84D5A0000 mov     eax,000005A4D ;' ZM'
1Global 2FillBlk 3CryBlk 4Reload 5OrdLdr 6String 7Direct 8Table 9Ibyte 10Leave 11Naked 12AddNam

```

Figure 7.1: Hiew: `main()` function

Hiew finds `ASCIIZ`<sup>6</sup> strings and displays them, as it does with the imported functions' names.

<sup>5</sup>that's what also called "dynamic linking"

<sup>6</sup>ASCII Zero (null-terminated ASCII string)



```

main PROC
$LN5:
    sub     rsp, 56
    lea    rcx, OFFSET FLAT:$SG2924 ; 'Enter X:'
    call   printf
    lea    rdx, QWORD PTR x$[rsp]
    lea    rcx, OFFSET FLAT:$SG2926 ; '%d'
    call   scanf
    cmp    eax, 1
    jne    SHORT $LN2@main
    mov    edx, DWORD PTR x$[rsp]
    lea    rcx, OFFSET FLAT:$SG2927 ; 'You entered %d...'
    call   printf
    jmp    SHORT $LN1@main
$LN2@main:
    lea    rcx, OFFSET FLAT:$SG2929 ; 'What you entered? Huh?'
    call   printf
$LN1@main:
    ; return 0
    xor    eax, eax
    add    rsp, 56
    ret    0
main     ENDP
_TEXT   ENDS
END

```

## 7.4 Exercises

### 7.4.1 Exercise #1

This code, compiled in Linux x86-64 using GCC is crashing while execution (segmentation fault). However, it works in Windows environment compiled by MSVC 2010 x86. Why?

```

#include <string.h>
#include <stdio.h>

void alter_string(char *s)
{
    strcpy (s, "Goodbye!");
    printf ("Result: %s\n", s);
};

int main()
{
    alter_string ("Hello, world!\n");
};

```

Answer: ?? on page ??.

## Chapter 8

# Accessing passed arguments

Now we figured out that the [caller](#) function is passing arguments to the [callee](#) via the stack. But how does the [callee](#) access them?

Listing 8.1: simple example

```
#include <stdio.h>

int f (int a, int b, int c)
{
    return a*b+c;
};

int main()
{
    printf ("%d\n", f(1, 2, 3));
    return 0;
};
```

## 8.1 x86

### 8.1.1 MSVC

Here is what we get after compilation (MSVC 2010 Express):

Listing 8.2: MSVC 2010 Express

```
_TEXT SEGMENT
_a$ = 8 ; size = 4
_b$ = 12 ; size = 4
_c$ = 16 ; size = 4
_f PROC
    push ebp
    mov ebp, esp
    mov eax, DWORD PTR _a$[ebp]
    imul eax, DWORD PTR _b$[ebp]
    add eax, DWORD PTR _c$[ebp]
    pop ebp
    ret 0
_f ENDP

_main PROC
    push ebp
    mov ebp, esp
    push 3 ; 3rd argument
    push 2 ; 2nd argument
    push 1 ; 1st argument
    call _f
    add esp, 12
    push eax
    push OFFSET $SG2463 ; '%d', 0aH, 00H
```

```

    call    _printf
    add     esp, 8
    ; return 0
    xor     eax, eax
    pop     ebp
    ret     0
_main     ENDP

```

What we see is that the `main()` function pushes 3 numbers onto the stack and calls `f(int, int, int)`. Argument access inside `f()` is organized with the help of macros like: `_a$ = 8`, in the same way as local variables, but with positive offsets (addressed with *plus*). So, we are addressing the *outer* side of the [stack frame](#) by adding the `_a$` macro to the value in the EBP register.

Then the value of `a` is stored into EAX. After `IMUL` instruction execution, the value in EAX is a [product](#) of the value in EAX and the content of `_b`. After that, `ADD` adds the value in `_c` to EAX. The value in EAX does not need to be moved: it is already where it must be. On returning to [caller](#), it takes the EAX value and use it as an argument to `printf()`.

## 8.2 x64

The story is a bit different in x86-64. Function arguments (first 4 or first 6 of them) are passed in registers i.e. the [callee](#) reads them from registers instead of reading them from the stack.

### 8.2.1 MSVC

Optimizing MSVC:

Listing 8.3: Optimizing MSVC 2012 x64

```

$SG2997 DB    '%d', 0aH, 00H

main     PROC
        sub     rsp, 40
        mov     edx, 2
        lea    r8d, QWORD PTR [rdx+1] ; R8D=3
        lea    ecx, QWORD PTR [rdx-1] ; ECX=1
        call   f
        lea    rcx, OFFSET FLAT:$SG2997 ; '%d'
        mov     edx, eax
        call   printf
        xor     eax, eax
        add     rsp, 40
        ret     0
main     ENDP

f        PROC
        ; ECX - 1st argument
        ; EDX - 2nd argument
        ; R8D - 3rd argument
        imul   ecx, edx
        lea    eax, DWORD PTR [r8+rcx]
        ret     0
f        ENDP

```

As we can see, the compact function `f()` takes all its arguments from the registers. The `LEA` instruction here is used for addition, apparently the compiler considered it faster than `ADD`. `LEA` is also used in the `main()` function to prepare the first and third `f()` arguments. The compiler must have decided that this would work faster than the usual way of loading values into a register using `MOV` instruction.

Let's take a look at the non-optimizing MSVC output:

Listing 8.4: MSVC 2012 x64

```

f        proc near

; shadow space:
arg_0    = dword ptr  8
arg_8    = dword ptr 10h

```

```

arg_10      = dword ptr  18h

            ; ECX - 1st argument
            ; EDX - 2nd argument
            ; R8D - 3rd argument
mov     [rsp+arg_10], r8d
mov     [rsp+arg_8], edx
mov     [rsp+arg_0], ecx
mov     eax, [rsp+arg_0]
imul   eax, [rsp+arg_8]
add     eax, [rsp+arg_10]
retn
f
endp

main       proc near
sub     rsp, 28h
mov     r8d, 3 ; 3rd argument
mov     edx, 2 ; 2nd argument
mov     ecx, 1 ; 1st argument
call    f
mov     edx, eax
lea     rcx, $SG2931 ; "%d\n"
call    printf

            ; return 0
xor     eax, eax
add     rsp, 28h
retn
main      endp

```

It looks somewhat puzzling because all 3 arguments from the registers are saved to the stack for some reason. This is called “shadow space”<sup>1</sup>: every Win64 may (but is not required to) save all 4 register values there. This is done for two reasons: 1) it is too lavish to allocate a whole register (or even 4 registers) for an input argument, so it will be accessed via stack; 2) the debugger is always aware where to find the function arguments at a break<sup>2</sup>.

So, some large functions can save their input arguments in the “shadows space” if they need to use them during execution, but some small functions (like ours) may not do this.

It is a [caller](#) responsibility to allocate “shadow space” in the stack.

<sup>1</sup>MSDN

<sup>2</sup>MSDN

## Chapter 9

# More about results returning

In x86, the result of function execution is usually returned<sup>1</sup> in the EAX register. If it is byte type or a character (*char*), then the lowest part of register EAX (AL) is used. If a function returns a *float* number, the FPU register ST(0) is used instead.

### 9.1 Attempt to use the result of a function returning *void*

So, what if the `main()` function return value was declared of type *void* and not *int*?

The so-called startup-code is calling `main()` roughly as follows:

```
push envp
push argv
push argc
call main
push eax
call exit
```

In other words:

```
exit(main(argc, argv, envp));
```

If you declare `main()` as *void*, nothing is to be returned explicitly (using the *return* statement), then something random, that was stored in the EAX register at the end of `main()` becomes the sole argument of the `exit()` function. Most likely, there will be a random value, left from your function execution, so the exit code of program is pseudorandom.

We can illustrate this fact. Please note that here the `main()` function has a *void* return type:

```
#include <stdio.h>

void main()
{
    printf ("Hello, world!\n");
};
```

Let's compile it in Linux.

GCC 4.8.1 replaced `printf()` with `puts()`, but that's OK, since `puts()` returns the number of characters printed out, just like `printf()`. Please notice that EAX is not zeroed before `main()`'s end. This implies that the value of EAX at the end of `main()` contains what `puts()` has left there.

Listing 9.1: GCC 4.8.1

```
.LC0:
    .string "Hello, world!"
main:
    push    ebp
    mov     ebp, esp
    and     esp, -16
    sub     esp, 16
    mov     DWORD PTR [esp], OFFSET FLAT:.LC0
```

<sup>1</sup>See also: MSDN: Return Values (C++): [MSDN](#)

```
call    puts
leave
ret
```

Let's write a bash script that shows the exit status:

Listing 9.2: tst.sh

```
#!/bin/sh
./hello_world
echo $?
```

And run it:

```
$ tst.sh
Hello, world!
14
```

14 is the number of characters printed.

## 9.2 What if we do not use the function result?

`printf()` returns the count of characters successfully output, but the result of this function is rarely used in practice. It is also possible to call a function whose essence is in returning a value, and not use it:

```
int f()
{
    // skip first 3 random values
    rand();
    rand();
    rand();
    // and use 4th
    return rand();
};
```

The result of the `rand()` function is left in EAX, in all four cases. But in the first 3 cases, the value in EAX is just thrown away.

## Chapter 10

# GOTO operator

The GOTO operator is generally considered as anti-pattern. [Dij68], Nevertheless, it can be used reasonably [Knu74], [Yur13, p. 1.3.2].

Here is a very simple example:

```
#include <stdio.h>

int main()
{
    printf ("begin\n");
    goto exit;
    printf ("skip me!\n");
exit:
    printf ("end\n");
};
```

Here is what we have got in MSVC 2012:

Listing 10.1: MSVC 2012

```
$SG2934 DB      'begin', 0aH, 00H
$SG2936 DB      'skip me!', 0aH, 00H
$SG2937 DB      'end', 0aH, 00H

_main  PROC
        push    ebp
        mov     ebp, esp
        push    OFFSET $SG2934 ; 'begin'
        call   _printf
        add     esp, 4
        jmp     SHORT $exit$3
        push    OFFSET $SG2936 ; 'skip me!'
        call   _printf
        add     esp, 4
$exit$3:
        push    OFFSET $SG2937 ; 'end'
        call   _printf
        add     esp, 4
        xor     eax, eax
        pop     ebp
        ret     0
_main  ENDP
```

The *goto* statement has been simply replaced by a `JMP` instruction, which has the same effect: unconditional jump to another place.

The second `printf()` could be executed only with human intervention, by using a debugger or by patching the code.

## 10.1 Dead code

The second `printf()` call is also called “dead code” in compiler terms. This means that the code will never be executed. So when you compile this example with optimizations, the compiler removes “dead code”, leaving no trace of it:

Listing 10.2: Optimizing MSVC 2012

```
$SG2981 DB      'begin', 0aH, 00H
$SG2983 DB      'skip me!', 0aH, 00H
$SG2984 DB      'end', 0aH, 00H

_main  PROC
        push    OFFSET $SG2981 ; 'begin'
        call    _printf
        push    OFFSET $SG2984 ; 'end'
$exit$4:
        call    _printf
        add     esp, 8
        xor     eax, eax
        ret     0
_main  ENDP
```

However, the compiler forgot to remove the “skip me!” string.

# Chapter 11

## Conditional jumps

### 11.1 Simple example

```
#include <stdio.h>

void f_signed (int a, int b)
{
    if (a>b)
        printf ("a>b\n");
    if (a==b)
        printf ("a==b\n");
    if (a<b)
        printf ("a<b\n");
};

void f_unsigned (unsigned int a, unsigned int b)
{
    if (a>b)
        printf ("a>b\n");
    if (a==b)
        printf ("a==b\n");
    if (a<b)
        printf ("a<b\n");
};

int main()
{
    f_signed(1, 2);
    f_unsigned(1, 2);
    return 0;
};
```

#### 11.1.1 x86

##### x86 + MSVC

Here is how the `f_signed()` function looks like:

Listing 11.1: Non-optimizing MSVC 2010

```
_a$ = 8
_b$ = 12
_f_signed PROC
    push    ebp
    mov     ebp, esp
    mov     eax, DWORD PTR _a$[ebp]
    cmp     eax, DWORD PTR _b$[ebp]
    jle     SHORT $LN3@f_signed
    push    OFFSET $SG737      ; 'a>b'
    call   _printf
    add     esp, 4
```

```

$LN3@f_signed:
    mov     ecx, DWORD PTR _a$[ebp]
    cmp     ecx, DWORD PTR _b$[ebp]
    jne     SHORT $LN2@f_signed
    push   OFFSET $SG739      ; 'a==b'
    call   _printf
    add     esp, 4
$LN2@f_signed:
    mov     edx, DWORD PTR _a$[ebp]
    cmp     edx, DWORD PTR _b$[ebp]
    jge     SHORT $LN4@f_signed
    push   OFFSET $SG741      ; 'a<b'
    call   _printf
    add     esp, 4
$LN4@f_signed:
    pop     ebp
    ret     0
_f_signed ENDP

```

The first instruction, *JLE*, stands for *Jump if Less or Equal*. In other words, if the second operand is larger or equal to the first one, the control flow will be passed to the specified in the instruction address or label. If this condition does not trigger because the second operand is smaller than the first one, the control flow would not be altered and the first `printf()` would be executed. The second check is *JNE: Jump if Not Equal*. The control flow will not change if the operands are equal.

The third check is *JGE: Jump if Greater or Equal*—jump if the first operand is larger than the second or if they are equal. So, if all three conditional jumps are triggered, none of the `printf()` calls would be executed whatsoever. This is impossible without special intervention.

Now let's take a look at the `f_unsigned()` function. The `f_unsigned()` function is the same as `f_signed()`, with the exception that the *JBE* and *JAE* instructions are used instead of *JLE* and *JGE*, as follows:

Listing 11.2: GCC

```

_a$ = 8 ; size = 4
_b$ = 12 ; size = 4
_f_unsigned PROC
    push   ebp
    mov     ebp, esp
    mov     eax, DWORD PTR _a$[ebp]
    cmp     eax, DWORD PTR _b$[ebp]
    jbe     SHORT $LN3@f_unsigned
    push   OFFSET $SG2761      ; 'a>b'
    call   _printf
    add     esp, 4
$LN3@f_unsigned:
    mov     ecx, DWORD PTR _a$[ebp]
    cmp     ecx, DWORD PTR _b$[ebp]
    jne     SHORT $LN2@f_unsigned
    push   OFFSET $SG2763      ; 'a==b'
    call   _printf
    add     esp, 4
$LN2@f_unsigned:
    mov     edx, DWORD PTR _a$[ebp]
    cmp     edx, DWORD PTR _b$[ebp]
    jae     SHORT $LN4@f_unsigned
    push   OFFSET $SG2765      ; 'a<b'
    call   _printf
    add     esp, 4
$LN4@f_unsigned:
    pop     ebp
    ret     0
_f_unsigned ENDP

```

As already mentioned, the branch instructions are different: *JBE*—*Jump if Below or Equal* and *JAE*—*Jump if Above or Equal*. These instructions (*JA/JAE/JB/JBE*) differ from *JG/JGE/JL/JLE* in the fact that they work with unsigned numbers.

See also the section about signed number representations ([22 on page 105](#)). That is why if we see *JG/JL* in use instead of *JA/JB* or vice-versa, we can be almost sure that the variables are signed or unsigned, respectively.

Here is also the `main()` function, where there is nothing much new to us:

Listing 11.3: main()

```
_main PROC
    push    ebp
    mov     ebp, esp
    push    2
    push    1
    call    _f_signed
    add     esp, 8
    push    2
    push    1
    call    _f_unsigned
    add     esp, 8
    xor     eax, eax
    pop     ebp
    ret     0
_main ENDP
```

## x86 + MSVC + Hiew

We can try to patch the executable file in a way that the `f_unsigned()` function would always print “a==b”, no matter the input values. Here is how it looks in Hiew:

```

C:\Polygon\ollydbg\7_1.exe  FRO ----- a32 PE .00401000 Hiew 8.02 (c)SEN
.00401000: 55      push   ebp
.00401001: 8BEC    mov    ebp, esp
.00401003: 8B4508  mov    eax, [ebp+8]
.00401006: 3B450C  cmp    eax, [ebp+0C]
.00401009: 7E0D    jle    .00401018 --E1
.0040100B: 680B04000  push  00040B00 --E2
.00401010: E8AA000000  call  .004010BF --E3
.00401015: 83C404  add    esp, 4
.00401018: 8B4D08  mov    ecx, [ebp+8]
.0040101B: 3B4D0C  cmp    ecx, [ebp+0C]
.0040101E: 750D    jnz    .0040102D --E4
.00401020: 6808B04000  push  00040B008 ; 'a==b' --E5
.00401025: E895000000  call  .004010BF --E3
.0040102A: 83C404  add    esp, 4
.0040102D: 8B5508  mov    edx, [ebp+8]
.00401030: 3B550C  cmp    edx, [ebp+0C]
.00401033: 7D0D    jge    .00401042 --E6
.00401035: 6810B04000  push  00040B010 --E7
.0040103A: E880000000  call  .004010BF --E3
.0040103F: 83C404  add    esp, 4
.00401042: 5D      pop    ebp
.00401043: C3     retn ; ^.^.^.^.^.^.^.^.^.^.^.^.^.^.^.^
.00401044: CC     int    3
.00401045: CC     int    3
.00401046: CC     int    3
.00401047: CC     int    3
.00401048: CC     int    3
1Global 2FillBlk 3CryBlk 4Reload 5OrdLdr 6String 7Direct 8Table 9Ibyte 10Leave 11Naked 12AddNam

```

Figure 11.1: Hiew: `f_unsigned()` function

Essentially, we need to accomplish three tasks:

- force the first jump to always trigger;
- force the second jump to never trigger;
- force the third jump to always trigger.

Thus we can direct the code flow to always pass through the second `printf()`, and output “a==b”.

Three instructions (or bytes) has to be patched:

- The first jump becomes `JMP`, but the [jump offset](#) would remain the same.
- The second jump might be triggered sometimes, but in any case it will jump to the next instruction, because, we set the [jump offset](#) to 0. In these instructions the [jump offset](#) is added to the address for the next instruction. So if the offset is 0, the jump will transfer the control to the next instruction.
- The third jump we replace with `JMP` just as we do with the first one, so it will always trigger.

Here is the modified code:

```

C:\Polygon\ollydbg\7_1.exe  FWO EDITMODE  a32 PE  00000434 Hiew 8.02 (c)SEN
00000400: 55          push     ebp
00000401: 8BEC       mov     ebp,esp
00000403: 8B4508     mov     eax,[ebp+8]
00000406: 3B450C     cmp     eax,[ebp+00C]
00000409: EB0D      jumps   00000418
0000040B: 6800B04000 push    00040B000 ; '@'
00000410: E8AA000000 call    000004BF
00000415: 83C404     add     esp,4
00000418: 8B4D08     mov     ecx,[ebp+8]
0000041B: 3B4D0C     cmp     ecx,[ebp+00C]
0000041E: 7500      jnz    00000420
00000420: 6808B04000 push    00040B008 ; '@'
00000425: E895000000 call    000004BF
0000042A: 83C404     add     esp,4
0000042D: 8B5508     mov     edx,[ebp+8]
00000430: 3B550C     cmp     edx,[ebp+00C]
00000433: EB0D      jumps   00000442
00000435: 6810B04000 push    00040B010 ; '@'
0000043A: E880000000 call    000004BF
0000043F: 83C404     add     esp,4
00000442: 5D        pop     ebp
00000443: C3        retn   ; ^^^^
00000444: CC        int     3
00000445: CC        int     3
00000446: CC        int     3
00000447: CC        int     3
00000448: CC        int     3
  
```

Figure 11.2: Hiew: let's modify the `f_unsigned()` function

If we miss to change any of these jumps, then several `printf()` calls may execute, while we want to execute only one.

## 11.2 Calculating absolute value

A simple function:

```

int my_abs (int i)
{
    if (i<0)
        return -i;
    else
        return i;
};
  
```

### 11.2.1 Optimizing MSVC

This is how the code is usually generated:

Listing 11.4: Optimizing MSVC 2012 x64

```

i$ = 8
my_abs PROC
; ECX = input
    test    ecx, ecx
; check for sign of input value
; skip NEG instruction if sign is positive
  
```

```

    jns     SHORT $LN2@my_abs
; negate value
    neg     ecx
$LN2@my_abs:
; prepare result in EAX:
    mov     eax, ecx
    ret     0
my_abs    ENDP

```

## 11.3 Ternary conditional operator

The ternary conditional operator in C/C++ has the following syntax:

```
expression ? expression : expression
```

Here is an example:

```

const char* f (int a)
{
    return a==10 ? "it is ten" : "it is not ten";
};

```

### 11.3.1 x86

Old and non-optimizing compilers generate assembly code just as if an `if/else` statement was used:

Listing 11.5: Non-optimizing MSVC 2008

```

$SG746 DB    'it is ten', 00H
$SG747 DB    'it is not ten', 00H

tv65 = -4 ; this will be used as a temporary variable
_a$ = 8
_f     PROC
    push    ebp
    mov     ebp, esp
    push    ecx
; compare input value with 10
    cmp     DWORD PTR _a$[ebp], 10
; jump to $LN3@f if not equal
    jne     SHORT $LN3@f
; store pointer to the string into temporary variable:
    mov     DWORD PTR tv65[ebp], OFFSET $SG746 ; 'it is ten'
; jump to exit
    jmp     SHORT $LN4@f
$LN3@f:
; store pointer to the string into temporary variable:
    mov     DWORD PTR tv65[ebp], OFFSET $SG747 ; 'it is not ten'
$LN4@f:
; this is exit. copy pointer to the string from temporary variable to EAX.
    mov     eax, DWORD PTR tv65[ebp]
    mov     esp, ebp
    pop     ebp
    ret     0
_f     ENDP

```

Listing 11.6: Optimizing MSVC 2008

```

$SG792 DB    'it is ten', 00H
$SG793 DB    'it is not ten', 00H

_a$ = 8 ; size = 4
_f     PROC
; compare input value with 10
    cmp     DWORD PTR _a$[esp-4], 10
    mov     eax, OFFSET $SG792 ; 'it is ten'

```

```

; jump to $LN4@f if equal
    je     SHORT $LN4@f
    mov    eax, OFFSET $SG793 ; 'it is not ten'
$LN4@f:
    ret    0
_f      ENDP

```

Newer compilers are more concise:

Listing 11.7: Optimizing MSVC 2012 x64

```

$SG1355 DB    'it is ten', 00H
$SG1356 DB    'it is not ten', 00H

a$ = 8
f      PROC
; load pointers to the both strings
    lea    rdx, OFFSET FLAT:$SG1355 ; 'it is ten'
    lea    rax, OFFSET FLAT:$SG1356 ; 'it is not ten'
; compare input value with 10
    cmp    ecx, 10
; if equal, copy value from RDX ("it is ten")
; if not, do nothing. pointer to the string "it is not ten" is still in RAX as for now.
    cmov  rax, rdx
    ret    0
f      ENDP

```

Optimizing GCC 4.8 for x86 also uses the CMOVcc instruction, while the non-optimizing GCC 4.8 uses conditional jumps.

### 11.3.2 Let's rewrite it in an if/else way

```

const char* f (int a)
{
    if (a==10)
        return "it is ten";
    else
        return "it is not ten";
};

```

Interestingly, optimizing GCC 4.8 for x86 was also able to use CMOVcc in this case:

Listing 11.8: Optimizing GCC 4.8

```

.LC0:
    .string "it is ten"
.LC1:
    .string "it is not ten"
f:
.LFB0:
; compare input value with 10
    cmp    DWORD PTR [esp+4], 10
    mov    edx, OFFSET FLAT:.LC1 ; "it is not ten"
    mov    eax, OFFSET FLAT:.LC0 ; "it is ten"
; if comparison result is Not Equal, copy EDX value to EAX
; if not, do nothing
    cmovne eax, edx
    ret

```

But the optimizing MSVC 2012 is not that good (yet).

## 11.4 Getting minimal and maximal values

### 11.4.1 32-bit

```

int my_max(int a, int b)
{
    if (a>b)
        return a;
    else
        return b;
};

int my_min(int a, int b)
{
    if (a<b)
        return a;
    else
        return b;
};

```

Listing 11.9: Non-optimizing MSVC 2013

```

_a$ = 8
_b$ = 12
_my_min PROC
    push    ebp
    mov     ebp, esp
    mov     eax, DWORD PTR _a$[ebp]
; compare A and B:
    cmp     eax, DWORD PTR _b$[ebp]
; jump, if A is greater or equal to B:
    jge     SHORT $LN2@my_min
; reload A to EAX if otherwise and jump to exit
    mov     eax, DWORD PTR _a$[ebp]
    jmp     SHORT $LN3@my_min
    jmp     SHORT $LN3@my_min ; this is redundant JMP
$LN2@my_min:
; return B
    mov     eax, DWORD PTR _b$[ebp]
$LN3@my_min:
    pop     ebp
    ret     0
_my_min ENDP

_a$ = 8
_b$ = 12
_my_max PROC
    push    ebp
    mov     ebp, esp
    mov     eax, DWORD PTR _a$[ebp]
; compare A and B:
    cmp     eax, DWORD PTR _b$[ebp]
; jump if A is less or equal to B:
    jle     SHORT $LN2@my_max
; reload A to EAX if otherwise and jump to exit
    mov     eax, DWORD PTR _a$[ebp]
    jmp     SHORT $LN3@my_max
    jmp     SHORT $LN3@my_max ; this is redundant JMP
$LN2@my_max:
; return B
    mov     eax, DWORD PTR _b$[ebp]
$LN3@my_max:
    pop     ebp
    ret     0
_my_max ENDP

```

These two functions differ only in the conditional jump instruction: JGE (“Jump if Greater or Equal”) is used in the first one and JLE (“Jump if Less or Equal”) in the second.

There is one unneeded JMP instruction in each function, which MSVC probably left by mistake.

## 11.5 Conclusion

### 11.5.1 x86

Here's the rough skeleton of a conditional jump:

Listing 11.10: x86

```
CMP register, register/value
Jcc true ; cc=condition code
false:
... some code to be executed if comparison result is false ...
JMP exit
true:
... some code to be executed if comparison result is true ...
exit:
```

### 11.5.2 Branchless

If the body of a condition statement is very short, the conditional move instruction can be used: MOVcc in ARM (in ARM mode), CSEL in ARM64, CMOVcc in x86.

## Chapter 12

# switch()/case/default

### 12.1 Small number of cases

```
#include <stdio.h>

void f (int a)
{
    switch (a)
    {
        case 0: printf ("zero\n"); break;
        case 1: printf ("one\n"); break;
        case 2: printf ("two\n"); break;
        default: printf ("something unknown\n"); break;
    };
};

int main()
{
    f (2); // test
};
```

#### 12.1.1 x86

##### Non-optimizing MSVC

Result (MSVC 2010):

Listing 12.1: MSVC 2010

```
tv64 = -4 ; size = 4
_a$ = 8 ; size = 4
_f PROC
    push    ebp
    mov     ebp, esp
    push    ecx
    mov     eax, DWORD PTR _a$[ebp]
    mov     DWORD PTR tv64[ebp], eax
    cmp     DWORD PTR tv64[ebp], 0
    je      SHORT $LN4@f
    cmp     DWORD PTR tv64[ebp], 1
    je      SHORT $LN3@f
    cmp     DWORD PTR tv64[ebp], 2
    je      SHORT $LN2@f
    jmp     SHORT $LN1@f
$LN4@f:
    push    OFFSET $SG739 ; 'zero', 0aH, 00H
    call   _printf
    add     esp, 4
    jmp     SHORT $LN7@f
$LN3@f:
    push    OFFSET $SG741 ; 'one', 0aH, 00H
```

```

    call    _printf
    add     esp, 4
    jmp     SHORT $LN7@f
$LN2@f:
    push   OFFSET $SG743 ; 'two', 0aH, 00H
    call   _printf
    add     esp, 4
    jmp     SHORT $LN7@f
$LN1@f:
    push   OFFSET $SG745 ; 'something unknown', 0aH, 00H
    call   _printf
    add     esp, 4
$LN7@f:
    mov     esp, ebp
    pop     ebp
    ret     0
_f        ENDP

```

Our function with a few cases in `switch()` is in fact analogous to this construction:

```

void f (int a)
{
    if (a==0)
        printf ("zero\n");
    else if (a==1)
        printf ("one\n");
    else if (a==2)
        printf ("two\n");
    else
        printf ("something unknown\n");
};

```

If we work with `switch()` with a few cases it is impossible to be sure if it was a real `switch()` in the source code, or just a pack of `if()` statements. This implies that `switch()` is like syntactic sugar for a large number of nested `if()`s.

There is nothing especially new to us in the generated code, with the exception of the compiler moving input variable `a` to a temporary local variable `tv64`<sup>1</sup>.

If we compile this in GCC 4.4.1, we'll get almost the same result, even with maximal optimization turned on (`-O3` option).

### Optimizing MSVC

Now let's turn on optimization in MSVC (`/Ox`): `cl 1.c /Fa1.asm /Ox`

Listing 12.2: MSVC

```

_a$ = 8 ; size = 4
_f    PROC
    mov     eax, DWORD PTR _a$[esp-4]
    sub     eax, 0
    je      SHORT $LN4@f
    sub     eax, 1
    je      SHORT $LN3@f
    sub     eax, 1
    je      SHORT $LN2@f
    mov     DWORD PTR _a$[esp-4], OFFSET $SG791 ; 'something unknown', 0aH, 00H
    jmp     _printf
$LN2@f:
    mov     DWORD PTR _a$[esp-4], OFFSET $SG789 ; 'two', 0aH, 00H
    jmp     _printf
$LN3@f:
    mov     DWORD PTR _a$[esp-4], OFFSET $SG787 ; 'one', 0aH, 00H
    jmp     _printf
$LN4@f:
    mov     DWORD PTR _a$[esp-4], OFFSET $SG785 ; 'zero', 0aH, 00H
    jmp     _printf
_f    ENDP

```

<sup>1</sup>Local variables in stack are prefixed with `tv`—that's how MSVC names internal variables for its needs

Here we can see some dirty hacks.

First: the value of *a* is placed in EAX and 0 is subtracted from it. Sounds absurd, but it is done to check if the value in EAX was 0. If yes, the ZF flag is to be set (e.g. subtracting from 0 is 0) and the first conditional jump *JE* (*Jump if Equal* or synonym *JZ –Jump if Zero*) is to be triggered and control flow is to be passed to the `$LN4@f` label, where the 'zero' message is being printed. If the first jump doesn't get triggered, 1 is subtracted from the input value and if at some stage the result is 0, the corresponding jump is to be triggered.

And if no jump gets triggered at all, the control flow passes to `printf()` with string argument 'something unknown'.

Second: we see something unusual for us: a string pointer is placed into the *a* variable, and then `printf()` is called not via `CALL`, but via `JMP`. There is a simple explanation for that: the *caller* pushes a value to the stack and calls our function via `CALL`. `CALL` itself pushes the return address (*RA*<sup>2</sup>) to the stack and does an unconditional jump to our function address. Our function at any point of execution (since it do not contain any instruction that moves the stack pointer) has the following stack layout:

- ESP—points to *RA*
- ESP+4—points to the *a* variable

On the other side, when we need to call `printf()` here we need exactly the same stack layout, except for the first `printf()` argument, which needs to point to the string. And that is what our code does.

It replaces the function's first argument with the address of the string and jumps to `printf()`, as if we didn't call our function `f()`, but directly `printf()`. `printf()` prints a string to *stdout* and then executes the `RET` instruction, which `POPs` *RA* from the stack and control flow is returned not to `f()` but rather to `f()`'s *callee*, bypassing the end of the `f()` function.

All this is possible because `printf()` is called right at the end of the `f()` function in all cases. In some way, it is similar to the `longjmp()`<sup>3</sup> function. And of course, it is all done for the sake of speed.

### 12.1.2 Conclusion

A `switch()` with few cases is indistinguishable from an *if/else* construction, for example: listing.12.1.1.

## 12.2 A lot of cases

If a `switch()` statement contains a lot of cases, it is not very convenient for the compiler to emit too large code with a lot `JE/JNE` instructions.

```
#include <stdio.h>

void f (int a)
{
    switch (a)
    {
        case 0: printf ("zero\n"); break;
        case 1: printf ("one\n"); break;
        case 2: printf ("two\n"); break;
        case 3: printf ("three\n"); break;
        case 4: printf ("four\n"); break;
        default: printf ("something unknown\n"); break;
    };
};

int main()
{
    f (2); // test
};
```

### 12.2.1 x86

#### Non-optimizing MSVC

We get (MSVC 2010):

<sup>2</sup>Return Address

<sup>3</sup>wikipedia

## Listing 12.3: MSVC 2010

```

tv64 = -4 ; size = 4
_a$ = 8 ; size = 4
_f PROC
    push    ebp
    mov     ebp, esp
    push    ecx
    mov     eax, DWORD PTR _a$[ebp]
    mov     DWORD PTR tv64[ebp], eax
    cmp     DWORD PTR tv64[ebp], 4
    ja     SHORT $LN1@f
    mov     ecx, DWORD PTR tv64[ebp]
    jmp     DWORD PTR $LN11@f[ecx*4]
$LN6@f:
    push    OFFSET $SG739 ; 'zero', 0aH, 00H
    call    _printf
    add     esp, 4
    jmp     SHORT $LN9@f
$LN5@f:
    push    OFFSET $SG741 ; 'one', 0aH, 00H
    call    _printf
    add     esp, 4
    jmp     SHORT $LN9@f
$LN4@f:
    push    OFFSET $SG743 ; 'two', 0aH, 00H
    call    _printf
    add     esp, 4
    jmp     SHORT $LN9@f
$LN3@f:
    push    OFFSET $SG745 ; 'three', 0aH, 00H
    call    _printf
    add     esp, 4
    jmp     SHORT $LN9@f
$LN2@f:
    push    OFFSET $SG747 ; 'four', 0aH, 00H
    call    _printf
    add     esp, 4
    jmp     SHORT $LN9@f
$LN1@f:
    push    OFFSET $SG749 ; 'something unknown', 0aH, 00H
    call    _printf
    add     esp, 4
$LN9@f:
    mov     esp, ebp
    pop     ebp
    ret     0
    npad   2 ; align next label
$LN11@f:
    DD     $LN6@f ; 0
    DD     $LN5@f ; 1
    DD     $LN4@f ; 2
    DD     $LN3@f ; 3
    DD     $LN2@f ; 4
_f ENDP

```

What we see here is a set of `printf()` calls with various arguments. All they have not only addresses in the memory of the process, but also internal symbolic labels assigned by the compiler. All these labels are also mentioned in the `$LN11@f` internal table.

At the function start, if `a` is greater than 4, control flow is passed to label `$LN1@f`, where `printf()` with argument 'something unknown' is called.

But if the value of `a` is less or equals to 4, then it gets multiplied by 4 and added with the `$LN11@f` table address. That is how an address inside the table is constructed, pointing exactly to the element we need. For example, let's say `a` is equal to 2.  $2 * 4 = 8$  (all table elements are addresses in a 32-bit process and that is why all elements are 4 bytes wide). The address of the `$LN11@f` table + 8 is the table element where the `$LN4@f` label is stored. `JMP` fetches the `$LN4@f` address from the table and jumps to it.

This table is sometimes called *jumptable* or *branch table*<sup>4</sup>.

<sup>4</sup>The whole method was once called *computed GOTO* in early versions of FORTRAN: [wikipedia](https://en.wikipedia.org/wiki/Computed_goto). Not quite relevant these days, but what a term!

Then the corresponding `printf()` is called with argument 'two'. Literally, the `jmp DWORD PTR $LN11@f[ecx*4]` instruction implies *jump to the DWORD that is stored at address `$LN11@f + ecx * 4`.*

is assembly language macro that aligning the next label so that it is to be stored at an address aligned on a 4 byte (or 16 byte) boundary. This is very suitable for the processor since it is able to fetch 32-bit values from memory through the memory bus, cache memory, etc, in a more effective way if it is aligned.

## Non-optimizing GCC

Let's see what GCC 4.4.1 generates:

Listing 12.4: GCC 4.4.1

```

public f
f      proc near ; CODE XREF: main+10

var_18 = dword ptr -18h
arg_0  = dword ptr  8

        push    ebp
        mov     ebp, esp
        sub     esp, 18h
        cmp     [ebp+arg_0], 4
        ja     short loc_8048444
        mov     eax, [ebp+arg_0]
        shl     eax, 2
        mov     eax, ds:off_804855C[eax]
        jmp     eax

loc_80483FE: ; DATA XREF: .rodata:off_804855C
        mov     [esp+18h+var_18], offset aZero ; "zero"
        call   _puts
        jmp     short locret_8048450

loc_804840C: ; DATA XREF: .rodata:08048560
        mov     [esp+18h+var_18], offset aOne ; "one"
        call   _puts
        jmp     short locret_8048450

loc_804841A: ; DATA XREF: .rodata:08048564
        mov     [esp+18h+var_18], offset aTwo ; "two"
        call   _puts
        jmp     short locret_8048450

loc_8048428: ; DATA XREF: .rodata:08048568
        mov     [esp+18h+var_18], offset aThree ; "three"
        call   _puts
        jmp     short locret_8048450

loc_8048436: ; DATA XREF: .rodata:0804856C
        mov     [esp+18h+var_18], offset aFour ; "four"
        call   _puts
        jmp     short locret_8048450

loc_8048444: ; CODE XREF: f+A
        mov     [esp+18h+var_18], offset aSomethingUnkno ; "something unknown"
        call   _puts

locret_8048450: ; CODE XREF: f+26
                ; f+34...
        leave
        retn
f      endp

off_804855C dd offset loc_80483FE ; DATA XREF: f+12
            dd offset loc_804840C
            dd offset loc_804841A
            dd offset loc_8048428
            dd offset loc_8048436

```

It is almost the same, with a little nuance: argument `arg_0` is multiplied by 4 by shifting it to left by 2 bits (it is almost the same as multiplication by 4) ([15.2.1 on page 61](#)). Then the address of the label is taken from the `off_804855C` array, stored in `EAX`, and then `JMP EAX` does the actual jump.

## 12.2.2 Conclusion

Rough skeleton of `switch()`:

Listing 12.5: x86

```
MOV REG, input
CMP REG, 4 ; maximal number of cases
JA default
SHL REG, 2 ; find element in table. shift for 3 bits in x64.
MOV REG, jump_table[REG]
JMP REG

case1:
    ; do something
    JMP exit
case2:
    ; do something
    JMP exit
case3:
    ; do something
    JMP exit
case4:
    ; do something
    JMP exit
case5:
    ; do something
    JMP exit

default:
    ...

exit:
    ....

jump_table dd case1
           dd case2
           dd case3
           dd case4
           dd case5
```

The jump to the address in the jump table may also be implemented using this instruction: `JMP jump_table[REG*4]`. Or `JMP jump_table[REG*8]` in x64.

A *jumtable* is just array of pointers, like the one described later: [16.4 on page 68](#).

## 12.3 When there are several *case* statements in one block

Here is a very widespread construction: several *case* statements for a single block:

```
#include <stdio.h>

void f(int a)
{
    switch (a)
    {
        case 1:
        case 2:
        case 7:
        case 10:
            printf ("1, 2, 7, 10\n");
```

```

        break;
    case 3:
    case 4:
    case 5:
    case 6:
        printf ("3, 4, 5\n");
        break;
    case 8:
    case 9:
    case 20:
    case 21:
        printf ("8, 9, 21\n");
        break;
    case 22:
        printf ("22\n");
        break;
    default:
        printf ("default\n");
        break;
};

int main()
{
    f(4);
};

```

It's too wasteful to generate a block for each possible case, so what is usually done is to generate each block plus some kind of dispatcher.

### 12.3.1 MSVC

Listing 12.6: Optimizing MSVC 2010

```

1  $SG2798 DB      '1, 2, 7, 10', 0aH, 00H
2  $SG2800 DB      '3, 4, 5', 0aH, 00H
3  $SG2802 DB      '8, 9, 21', 0aH, 00H
4  $SG2804 DB      '22', 0aH, 00H
5  $SG2806 DB      'default', 0aH, 00H
6
7  _a$ = 8
8  _f      PROC
9          mov     eax, DWORD PTR _a$[esp-4]
10         dec     eax
11         cmp     eax, 21
12         ja      SHORT $LN1@f
13         movzx   eax, BYTE PTR $LN10@f[eax]
14         jmp     DWORD PTR $LN11@f[eax*4]
15 $LN5@f:
16         mov     DWORD PTR _a$[esp-4], OFFSET $SG2798 ; '1, 2, 7, 10'
17         jmp     DWORD PTR __imp__printf
18 $LN4@f:
19         mov     DWORD PTR _a$[esp-4], OFFSET $SG2800 ; '3, 4, 5'
20         jmp     DWORD PTR __imp__printf
21 $LN3@f:
22         mov     DWORD PTR _a$[esp-4], OFFSET $SG2802 ; '8, 9, 21'
23         jmp     DWORD PTR __imp__printf
24 $LN2@f:
25         mov     DWORD PTR _a$[esp-4], OFFSET $SG2804 ; '22'
26         jmp     DWORD PTR __imp__printf
27 $LN1@f:
28         mov     DWORD PTR _a$[esp-4], OFFSET $SG2806 ; 'default'
29         jmp     DWORD PTR __imp__printf
30         npad   2 ; align $LN11@f table on 16-byte boundary
31 $LN11@f:
32         DD     $LN5@f ; print '1, 2, 7, 10'
33         DD     $LN4@f ; print '3, 4, 5'
34         DD     $LN3@f ; print '8, 9, 21'
35         DD     $LN2@f ; print '22'

```

```

36         DD      $LN10@f ; print 'default'
37 $LN10@f:
38         DB      0 ; a=1
39         DB      0 ; a=2
40         DB      1 ; a=3
41         DB      1 ; a=4
42         DB      1 ; a=5
43         DB      1 ; a=6
44         DB      0 ; a=7
45         DB      2 ; a=8
46         DB      2 ; a=9
47         DB      0 ; a=10
48         DB      4 ; a=11
49         DB      4 ; a=12
50         DB      4 ; a=13
51         DB      4 ; a=14
52         DB      4 ; a=15
53         DB      4 ; a=16
54         DB      4 ; a=17
55         DB      4 ; a=18
56         DB      4 ; a=19
57         DB      2 ; a=20
58         DB      2 ; a=21
59         DB      3 ; a=22
60 _f      ENDP

```

We see two tables here: the first table (\$LN10@f) is an index table, and the second one (\$LN11@f) is an array of pointers to blocks.

First, the input value is used as an index in the index table (line 13).

Here is a short legend for the values in the table: 0 is the first *case* block (for values 1, 2, 7, 10), 1 is the second one (for values 3, 4, 5), 2 is the third one (for values 8, 9, 21), 3 is the fourth one (for value 22), 4 is for the default block.

There we get an index for the second table of code pointers and we jump to it (line 14).

What is also worth noting is that there is no case for input value 0. That's why we see the DEC instruction at line 10, and the table starts at  $a = 1$ , because there is no need to allocate a table element for  $a = 0$ .

This is a very widespread pattern.

So why is this economical? Why isn't it possible to make it as before ([12.2.1 on page 47](#)), just with one table consisting of block pointers? The reason is that the elements in index table are 8-bit, hence it's all more compact.

## 12.4 Fall-through

Another very popular usage of `switch()` is the fall-through. Here is a small example:

```

1 #define R 1
2 #define W 2
3 #define RW 3
4
5 void f(int type)
6 {
7     int read=0, write=0;
8
9     switch (type)
10    {
11    case RW:
12        read=1;
13    case W:
14        write=1;
15        break;
16    case R:
17        read=1;
18        break;
19    default:
20        break;
21    };
22    printf ("read=%d, write=%d\n", read, write);

```

If *type* = 1 (R), *read* is to be set to 1, if *type* = 2 (W), *write* is to be set to 2. In case of *type* = 3 (RW), both *read* and *write* is to be set to 1.

The code at line 14 is executed in two cases: if *type* = RW or if *type* = W. There is no “break” for “case RW”x and that’s OK.

### 12.4.1 MSVC x86

Listing 12.7: MSVC 2012

```

$SG1305 DB      'read=%d, write=%d', 0aH, 00H

_write$ = -12   ; size = 4
_read$   = -8   ; size = 4
tv64    = -4    ; size = 4
_type$   = 8    ; size = 4
_f      PROC
    push    ebp
    mov     ebp, esp
    sub     esp, 12
    mov     DWORD PTR _read$[ebp], 0
    mov     DWORD PTR _write$[ebp], 0
    mov     eax, DWORD PTR _type$[ebp]
    mov     DWORD PTR tv64[ebp], eax
    cmp     DWORD PTR tv64[ebp], 1 ; R
    je     SHORT $LN2@f
    cmp     DWORD PTR tv64[ebp], 2 ; W
    je     SHORT $LN3@f
    cmp     DWORD PTR tv64[ebp], 3 ; RW
    je     SHORT $LN4@f
    jmp     SHORT $LN5@f
$LN4@f: ; case RW:
    mov     DWORD PTR _read$[ebp], 1
$LN3@f: ; case W:
    mov     DWORD PTR _write$[ebp], 1
    jmp     SHORT $LN5@f
$LN2@f: ; case R:
    mov     DWORD PTR _read$[ebp], 1
$LN5@f: ; default
    mov     ecx, DWORD PTR _write$[ebp]
    push    ecx
    mov     edx, DWORD PTR _read$[ebp]
    push    edx
    push    OFFSET $SG1305 ; 'read=%d, write=%d'
    call    _printf
    add     esp, 12
    mov     esp, ebp
    pop     ebp
    ret     0
_f      ENDP

```

The code mostly resembles what is in the source. There are no jumps between labels \$LN4@f and \$LN3@f: so when code flow is at \$LN4@f, *read* is first set to 1, then *write*. This is why it’s called fall-through: code flow falls through one piece of code (setting *read*) to another (setting *write*). If *type* = W, we land at \$LN3@f, so no code setting *read* to 1 is executed.

# Chapter 13

## Loops

### 13.1 Simple example

#### 13.1.1 x86

There is a special LOOP instruction in x86 instruction set for checking the value in register ECX and if it is not 0, to [decrement](#) ECX and pass control flow to the label in the LOOP operand. Probably this instruction is not very convenient, and there are no any modern compilers which emit it automatically. So, if you see this instruction somewhere in code, it is most likely that this is a manually written piece of assembly code.

In C/C++ loops are usually constructed using `for()`, `while()` or `do/while()` statements.

Let's start with `for()`.

This statement defines loop initialization (set loop counter to initial value), loop condition (is the counter bigger than a limit?), what is done at each iteration ([increment/decrement](#)) and of course loop body.

```
for (initialization; condition; at each iteration)
{
    loop_body;
}
```

The generated code is consisting of four parts as well.

Let's start with a simple example:

```
#include <stdio.h>

void printing_function(int i)
{
    printf ("f(%d)\n", i);
};

int main()
{
    int i;

    for (i=2; i<10; i++)
        printing_function(i);

    return 0;
};
```

Result (MSVC 2010):

Listing 13.1: MSVC 2010

```
_i$ = -4
_main PROC
    push    ebp
    mov     ebp, esp
    push    ecx
    mov     DWORD PTR _i$[ebp], 2    ; loop initialization
    jmp     SHORT $LN3@main
```

```

$LN2@main:
    mov     eax, DWORD PTR _i$[ebp] ; here is what we do after each iteration:
    add     eax, 1                   ; add 1 to (i) value
    mov     DWORD PTR _i$[ebp], eax
$LN3@main:
    cmp     DWORD PTR _i$[ebp], 10  ; this condition is checked *before* each iteration
    jge     SHORT $LN1@main         ; if (i) is biggest or equals to 10, lets finish loop'
    mov     ecx, DWORD PTR _i$[ebp] ; loop body: call printing_function(i)
    push   ecx
    call   _printing_function
    add     esp, 4
    jmp     SHORT $LN2@main         ; jump to loop begin
$LN1@main:
    ; loop end
    xor     eax, eax
    mov     esp, ebp
    pop     ebp
    ret     0
_main     ENDP

```

As we see, nothing special.

Listing 13.2: Optimizing MSVC

```

_main     PROC
    push   esi
    mov     esi, 2
$LL3@main:
    push   esi
    call   _printing_function
    inc     esi
    add     esp, 4
    cmp     esi, 10                ; 0000000aH
    jl     SHORT $LL3@main
    xor     eax, eax
    pop     esi
    ret     0
_main     ENDP

```

What happens here is that space for the *i* variable is not allocated in the local stack anymore, but uses an individual register for it, ESI. This is possible in such small functions where there aren't many local variables.

One very important thing is that the `f()` function must not change the value in ESI. Our compiler is sure here. And if the compiler decides to use the ESI register in `f()` too, its value would have to be saved at the function's prologue and restored at the function's epilogue, almost like in our listing: please note `PUSH ESI/POP ESI` at the function start and end.

### 13.1.2 One more thing

In the generated code we can see: after initializing *i*, the body of the loop is not to be executed, as the condition for *i* is checked first, and only after that loop body can be executed. And that is correct. Because, if the loop condition is not met at the beginning, the body of the loop must not be executed. This is possible in the following case:

```

for (i=0; i<total_entries_to_process; i++)
    loop_body;

```

If `total_entries_to_process` is 0, the body of the loop must not be executed at all. This is why the condition is checked before the execution.

However, an optimizing compiler may swap the condition check and loop body, if it is sure that the situation described here is not possible (like in the case of our very simple example and Keil, Xcode (LLVM), MSVC in optimization mode).

## 13.2 Memory blocks copying routine

Real-world memory copy routines may copy 4 or 8 bytes at each iteration, use `SIMD`<sup>1</sup>, vectorization, etc. But for the sake of simplicity, this example is the simplest possible.

<sup>1</sup>Single instruction, multiple data

```
#include <stdio.h>

void my_memcpy (unsigned char* dst, unsigned char* src, size_t cnt)
{
    size_t i;
    for (i=0; i<cnt; i++)
        dst[i]=src[i];
};
```

### 13.2.1 Straight-forward implementation

Listing 13.3: GCC 4.9 x64 optimized for size (-Os)

```
my_memcpy:
; RDI = destination address
; RSI = source address
; RDX = size of block

; initialize counter (i) at 0
xor    eax, eax
.L2:
; all bytes copied? exit then:
cmp    rax, rdx
je     .L5
; load byte at RSI+i:
mov    cl, BYTE PTR [rsi+rax]
; store byte at RDI+i:
mov    BYTE PTR [rdi+rax], cl
inc    rax ; i++
jmp    .L2
.L5:
ret
```

## 13.3 Conclusion

Rough skeleton of loop from 2 to 9 inclusive:

Listing 13.4: x86

```
mov [counter], 2 ; initialization
jmp check
body:
; loop body
; do something here
; use counter variable in local stack
add [counter], 1 ; increment
check:
cmp [counter], 9
jle body
```

The increment operation may be represented as 3 instructions in non-optimized code:

Listing 13.5: x86

```
MOV [counter], 2 ; initialization
JMP check
body:
; loop body
; do something here
; use counter variable in local stack
MOV REG, [counter] ; increment
INC REG
MOV [counter], REG
check:
CMP [counter], 9
JLE body
```

If the body of the loop is short, a whole register can be dedicated to the counter variable:

Listing 13.6: x86

```

MOV EBX, 2 ; initialization
JMP check
body:
; loop body
; do something here
; use counter in EBX, but do not modify it!
INC EBX ; increment
check:
CMP EBX, 9
JLE body

```

Some parts of the loop may be generated by compiler in different order:

Listing 13.7: x86

```

MOV [counter], 2 ; initialization
JMP label_check
label_increment:
ADD [counter], 1 ; increment
label_check:
CMP [counter], 10
JGE exit
; loop body
; do something here
; use counter variable in local stack
JMP label_increment
exit:

```

Usually the condition is checked *before* loop body, but the compiler may rearrange it in a way that the condition is checked *after* loop body. This is done when the compiler is sure that the condition is always *true* on the first iteration, so the body of the loop is to be executed at least once:

Listing 13.8: x86

```

MOV REG, 2 ; initialization
body:
; loop body
; do something here
; use counter in REG, but do not modify it!
INC REG ; increment
CMP REG, 10
JL body

```

Using the LOOP instruction. This is rare, compilers are not using it. When you see it, it's a sign that this piece of code is hand-written:

Listing 13.9: x86

```

; count from 10 to 1
MOV ECX, 10
body:
; loop body
; do something here
; use counter in ECX, but do not modify it!
LOOP body

```

## Chapter 14

# Simple C-strings processing

### 14.1 strlen()

Let's talk about loops one more time. Often, the `strlen()` function<sup>1</sup> is implemented using a `while()` statement. Here is how it is done in the MSVC standard libraries:

```
int my_strlen (const char * str)
{
    const char *eos = str;

    while( *eos++ );

    return( eos - str - 1 );
}

int main()
{
    // test
    return my_strlen("hello!");
};
```

#### 14.1.1 x86

##### Non-optimizing MSVC

Let's compile:

```
_eos$ = -4 ; size = 4
_str$ = 8 ; size = 4
_strlen PROC
    push    ebp
    mov     ebp, esp
    push    ecx
    mov     eax, DWORD PTR _str$[ebp] ; place pointer to string from "str"
    mov     DWORD PTR _eos$[ebp], eax ; place it to local variable "eos"
$LN2@strlen_:
    mov     ecx, DWORD PTR _eos$[ebp] ; ECX=eos

    ; take 8-bit byte from address in ECX and place it as 32-bit value to EDX with sign extension

    movsx  edx, BYTE PTR [ecx]
    mov     eax, DWORD PTR _eos$[ebp] ; EAX=eos
    add     eax, 1 ; increment EAX
    mov     DWORD PTR _eos$[ebp], eax ; place EAX back to "eos"
    test   edx, edx ; EDX is zero?
    je     SHORT $LN1@strlen_ ; yes, then finish loop
    jmp    SHORT $LN2@strlen_ ; continue loop
$LN1@strlen_:
```

<sup>1</sup>counting the characters in a string in the C language

```

; here we calculate the difference between two pointers

mov     eax, DWORD PTR _eos$[ebp]
sub     eax, DWORD PTR _str$[ebp]
sub     eax, 1                ; subtract 1 and return result
mov     esp, ebp
pop     ebp
ret     0
_strlen_ ENDP

```

We get two new instructions here: `MOVSX` and `TEST`.

The first one—`MOVSX`—takes a byte from an address in memory and stores the value in a 32-bit register. `MOVSX` stands for *MOV with Sign-Extend*. `MOVSX` sets the rest of the bits, from the 8th to the 31st, to 1 if the source byte is *negative* or to 0 if is *positive*.

And here is why.

By default, the *char* type is signed in MSVC and GCC. If we have two values of which one is *char* and the other is *int*, (*int* is signed too), and if the first value contain -2 (coded as 0xFE) and we just copy this byte into the *int* container, it makes 0x000000FE, and this from the point of signed *int* view is 254, but not -2. In signed *int*, -2 is coded as 0xFFFFFFF. So if we need to transfer 0xFE from a variable of *char* type to *int*, we need to identify its sign and extend it. That is what `MOVSX` does.

You can also read about it in “*Signed number representations*” section ( [22 on page 105](#)).

It’s hard to say if the compiler needs to store a *char* variable in EDX, it could just take a 8-bit register part (for example DL). Apparently, the compiler’s [register allocator](#) works like that.

Then we see `TEST EDX, EDX`. You can read more about the `TEST` instruction in the section about bit fields ( [17 on page 75](#)). Here this instruction just checks if the value in EDX equals to 0.

## Optimizing MSVC

Now let’s compile all this in MSVC 2012, with optimizations turned on (/Ox):

Listing 14.1: Optimizing MSVC 2012 /Ob0

```

_str$ = 8                ; size = 4
_strlen PROC
    mov     edx, DWORD PTR _str$[esp-4] ; EDX -> pointer to the string
    mov     eax, edx                ; move to EAX
$LL2@strlen:
    mov     cl, BYTE PTR [eax]      ; CL = *EAX
    inc     eax                    ; EAX++
    test    cl, cl                 ; CL==0?
    jne     SHORT $LL2@strlen      ; no, continue loop
    sub     eax, edx               ; calculate pointers difference
    dec     eax                    ; decrement EAX
    ret     0
_strlen ENDP

```

Now it is all simpler. Needless to say, the compiler could use registers with such efficiency only in small functions with a few local variables.

`INC/DEC`— are [increment/decrement](#) instructions, in other words: add or subtract 1 to/from a variable.

## Chapter 15

# Replacing arithmetic instructions to other ones

In the pursuit of optimization, one instruction may be replaced by another, or even with a group of instructions. For example, ADD and SUB can replace each other: line 18 in listing.??.

### 15.1 Multiplication

#### 15.1.1 Multiplication using addition

Here is a simple example:

Listing 15.1: Optimizing MSVC 2010

```
unsigned int f(unsigned int a)
{
    return a*8;
};
```

Multiplication by 8 is replaced by 3 addition instructions, which do the same. Apparently, MSVC's optimizer decided that this code can be faster.

```
_TEXT SEGMENT
_a$ = 8 ; size = 4
_f PROC
; File c:\polygon\c\2.c
    mov     eax, DWORD PTR _a$[esp-4]
    add     eax, eax
    add     eax, eax
    add     eax, eax
    ret     0
_f ENDP
_TEXT ENDS
END
```

#### 15.1.2 Multiplication using shifting

Multiplication and division instructions by a numbers that's a power of 2 are often replaced by shift instructions.

```
unsigned int f(unsigned int a)
{
    return a*4;
};
```

Listing 15.2: Non-optimizing MSVC 2010

```
_a$ = 8 ; size = 4
_f PROC
    push   ebp
    mov    ebp, esp
    mov    eax, DWORD PTR _a$[ebp]
```

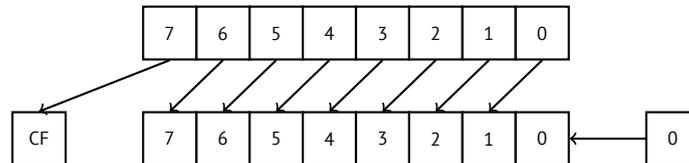
```

    shl     eax, 2
    pop     ebp
    ret     0
_f       ENDP

```

Multiplication by 4 is just shifting the number to the left by 2 bits and inserting 2 zero bits at the right (as the last two bits). It is just like multiplying 3 by 100 –we need to just add two zeroes at the right.

That's how the shift left instruction works:



The added bits at right are always zeroes.

### 15.1.3 Multiplication using shifting, subtracting, and adding

It's still possible to get rid of the multiplication operation when you multiply by numbers like 7 or 17 again by using shifting. The mathematics used here is relatively easy.

#### 32-bit

```

#include <stdint.h>

int f1(int a)
{
    return a*7;
};

int f2(int a)
{
    return a*28;
};

int f3(int a)
{
    return a*17;
};

```

#### x86

Listing 15.3: Optimizing MSVC 2012

```

; a*7
_a$ = 8
_f1   PROC
    mov     ecx, DWORD PTR _a$[esp-4]
; ECX=a
    lea    eax, DWORD PTR [ecx*8]
; EAX=ECX*8
    sub    eax, ecx
; EAX=EAX-ECX=ECX*8-ECX=ECX*7=a*7
    ret    0
_f1   ENDP

; a*28
_a$ = 8
_f2   PROC
    mov     ecx, DWORD PTR _a$[esp-4]
; ECX=a
    lea    eax, DWORD PTR [ecx*8]
; EAX=ECX*8

```

```

    sub    eax, ecx
; EAX=EAX-ECX=ECX*8-ECX=ECX*7=a*7
    shl    eax, 2
; EAX=EAX<<2=(a*7)*4=a*28
    ret    0
_f2     ENDP

; a*17
_a$ = 8
_f3     PROC
    mov    eax, DWORD PTR _a$[esp-4]
; EAX=a
    shl    eax, 4
; EAX=EAX<<4=EAX*16=a*16
    add    eax, DWORD PTR _a$[esp-4]
; EAX=EAX+a=a*16+a=a*17
    ret    0
_f3     ENDP

```

### 64-bit

```

#include <stdint.h>

int64_t f1(int64_t a)
{
    return a*7;
};

int64_t f2(int64_t a)
{
    return a*28;
};

int64_t f3(int64_t a)
{
    return a*17;
};

```

### x64

Listing 15.4: Optimizing MSVC 2012

```

; a*7
f1:
    lea    rax, [0+rdi*8]
; RAX=RDI*8=a*8
    sub    rax, rdi
; RAX=RAX-RDI=a*8-a=a*7
    ret

; a*28
f2:
    lea    rax, [0+rdi*4]
; RAX=RDI*4=a*4
    sal    rdi, 5
; RDI=RDI<<5=RDI*32=a*32
    sub    rdi, rax
; RDI=RDI-RAX=a*32-a*4=a*28
    mov    rax, rdi
    ret

; a*17
f3:
    mov    rax, rdi
    sal    rax, 4
; RAX=RAX<<4=a*16

```

```

add    rax, rdi
; RAX=a*16+a=a*17
ret

```

## 15.2 Division

### 15.2.1 Division using shifts

Example of division by 4:

```

unsigned int f(unsigned int a)
{
    return a/4;
};

```

We get (MSVC 2010):

Listing 15.5: MSVC 2010

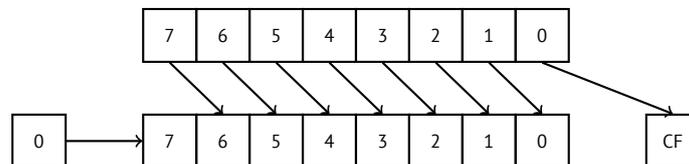
```

_a$ = 8                                ; size = 4
_f   PROC
    mov     eax, DWORD PTR _a$[esp-4]
    shr     eax, 2
    ret     0
_f   ENDP

```

The SHR (*SHift Right*) instruction in this example is shifting a number by 2 bits to the right. The two freed bits at left (e.g., two most significant bits) are set to zero. The two least significant bits are dropped. In fact, these two dropped bits are the division operation remainder.

The SHR instruction works just like SHL, but in the other direction.



It is easy to understand if you imagine the number 23 in the decimal numeral system. 23 can be easily divided by 10 just by dropping last digit (3—division remainder). 2 is left after the operation as a [quotient](#).

So the remainder is dropped, but that's OK, we work on integer values anyway, these are not a [real numbers](#)!

# Chapter 16

## Arrays

An array is just a set of variables in memory that lie next to each other and that have the same type<sup>1</sup>.

### 16.1 Simple example

```
#include <stdio.h>

int main()
{
    int a[20];
    int i;

    for (i=0; i<20; i++)
        a[i]=i*2;

    for (i=0; i<20; i++)
        printf ("a[%d]=%d\n", i, a[i]);

    return 0;
};
```

#### 16.1.1 x86

##### MSVC

Let's compile:

Listing 16.1: MSVC 2008

```
_TEXT    SEGMENT
_i$ = -84                ; size = 4
_a$ = -80                ; size = 80
_main    PROC
    push    ebp
    mov     ebp, esp
    sub     esp, 84        ; 00000054H
    mov     DWORD PTR _i$[ebp], 0
    jmp     SHORT $LN6@main
$LN5@main:
    mov     eax, DWORD PTR _i$[ebp]
    add     eax, 1
    mov     DWORD PTR _i$[ebp], eax
$LN6@main:
    cmp     DWORD PTR _i$[ebp], 20    ; 00000014H
    jge     SHORT $LN4@main
    mov     ecx, DWORD PTR _i$[ebp]
    shl     ecx, 1
```

<sup>1</sup>AKA<sup>2</sup> "homogeneous container"

```

    mov     edx, DWORD PTR _i$[ebp]
    mov     DWORD PTR _a$[ebp+edx*4], ecx
    jmp     SHORT $LN5@main
$LN4@main:
    mov     DWORD PTR _i$[ebp], 0
    jmp     SHORT $LN3@main
$LN2@main:
    mov     eax, DWORD PTR _i$[ebp]
    add     eax, 1
    mov     DWORD PTR _i$[ebp], eax
$LN3@main:
    cmp     DWORD PTR _i$[ebp], 20      ; 00000014H
    jge     SHORT $LN1@main
    mov     ecx, DWORD PTR _i$[ebp]
    mov     edx, DWORD PTR _a$[ebp+ecx*4]
    push   edx
    mov     eax, DWORD PTR _i$[ebp]
    push   eax
    push   OFFSET $SG2463
    call   _printf
    add     esp, 12                    ; 0000000cH
    jmp     SHORT $LN2@main
$LN1@main:
    xor     eax, eax
    mov     esp, ebp
    pop     ebp
    ret     0
_main     ENDP

```

Nothing very special, just two loops: the first is a filling loop and second is a printing loop. The `shl ecx, 1` instruction is used for value multiplication by 2 in ECX, more about below [15.2.1 on page 61](#).

80 bytes are allocated on the stack for the array, 20 elements of 4 bytes.

## 16.2 Buffer overflow

### 16.2.1 Reading outside array bounds

So, array indexing is just `array[index]`. If you study the generated code closely, you'll probably note the missing index bounds checking, which could check *if it is less than 20*. What if the index is 20 or greater? That's the one C/C++ feature it is often blamed for.

Here is a code that successfully compiles and works:

```

#include <stdio.h>

int main()
{
    int a[20];
    int i;

    for (i=0; i<20; i++)
        a[i]=i*2;

    printf ("a[20]=%d\n", a[20]);

    return 0;
};

```

Compilation results (MSVC 2008):

Listing 16.2: Non-optimizing MSVC 2008

```

$SG2474 DB     'a[20]=%d', 0aH, 00H

_i$ = -84 ; size = 4
_a$ = -80 ; size = 80
_main PROC

```

```

push    ebp
mov     ebp, esp
sub     esp, 84
mov     DWORD PTR _i$[ebp], 0
jmp     SHORT $LN3@main
$LN2@main:
mov     eax, DWORD PTR _i$[ebp]
add     eax, 1
mov     DWORD PTR _i$[ebp], eax
$LN3@main:
cmp     DWORD PTR _i$[ebp], 20
jge     SHORT $LN1@main
mov     ecx, DWORD PTR _i$[ebp]
shl     ecx, 1
mov     edx, DWORD PTR _i$[ebp]
mov     DWORD PTR _a$[ebp+edx*4], ecx
jmp     SHORT $LN2@main
$LN1@main:
mov     eax, DWORD PTR _a$[ebp+80]
push    eax
push    OFFSET $SG2474 ; 'a[20]=%d'
call   DWORD PTR __imp__printf
add     esp, 8
xor     eax, eax
mov     esp, ebp
pop     ebp
ret     0
_main   ENDP
_TEXT   ENDS
END

```

The code produced this result:

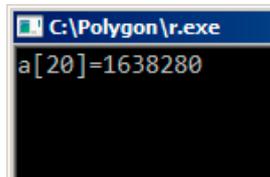


Figure 16.1: OllyDbg: console output

It is just *something* that was lying in the stack near to the array, 80 bytes away from its first element.

## 16.2.2 Writing beyond array bounds

OK, we read some values from the stack *illegally*, but what if we could write something to it?

Here is what we have got:

```

#include <stdio.h>

int main()
{
    int a[20];
    int i;

    for (i=0; i<30; i++)
        a[i]=i;

    return 0;
};

```

### MSVC

And what we get:

Listing 16.3: Non-optimizing MSVC 2008

```
_TEXT    SEGMENT
_i$ = -84 ; size = 4
_a$ = -80 ; size = 80
_main   PROC
push    ebp
mov     ebp, esp
sub     esp, 84
mov     DWORD PTR _i$[ebp], 0
jmp     SHORT $LN3@main
$LN2@main:
mov     eax, DWORD PTR _i$[ebp]
add     eax, 1
mov     DWORD PTR _i$[ebp], eax
$LN3@main:
cmp     DWORD PTR _i$[ebp], 30 ; 0000001eH
jge     SHORT $LN1@main
mov     ecx, DWORD PTR _i$[ebp]
mov     edx, DWORD PTR _i$[ebp] ; that instruction is obviously redundant
mov     DWORD PTR _a$[ebp+ecx*4], edx ; ECX could be used as second operand here instead
jmp     SHORT $LN2@main
$LN1@main:
xor     eax, eax
mov     esp, ebp
pop     ebp
ret     0
_main   ENDP
```

The compiled program crashes after running. No wonder. Let's see where exactly does it is crash.

Let's load it into OllyDbg, and trace until all 30 elements are written:

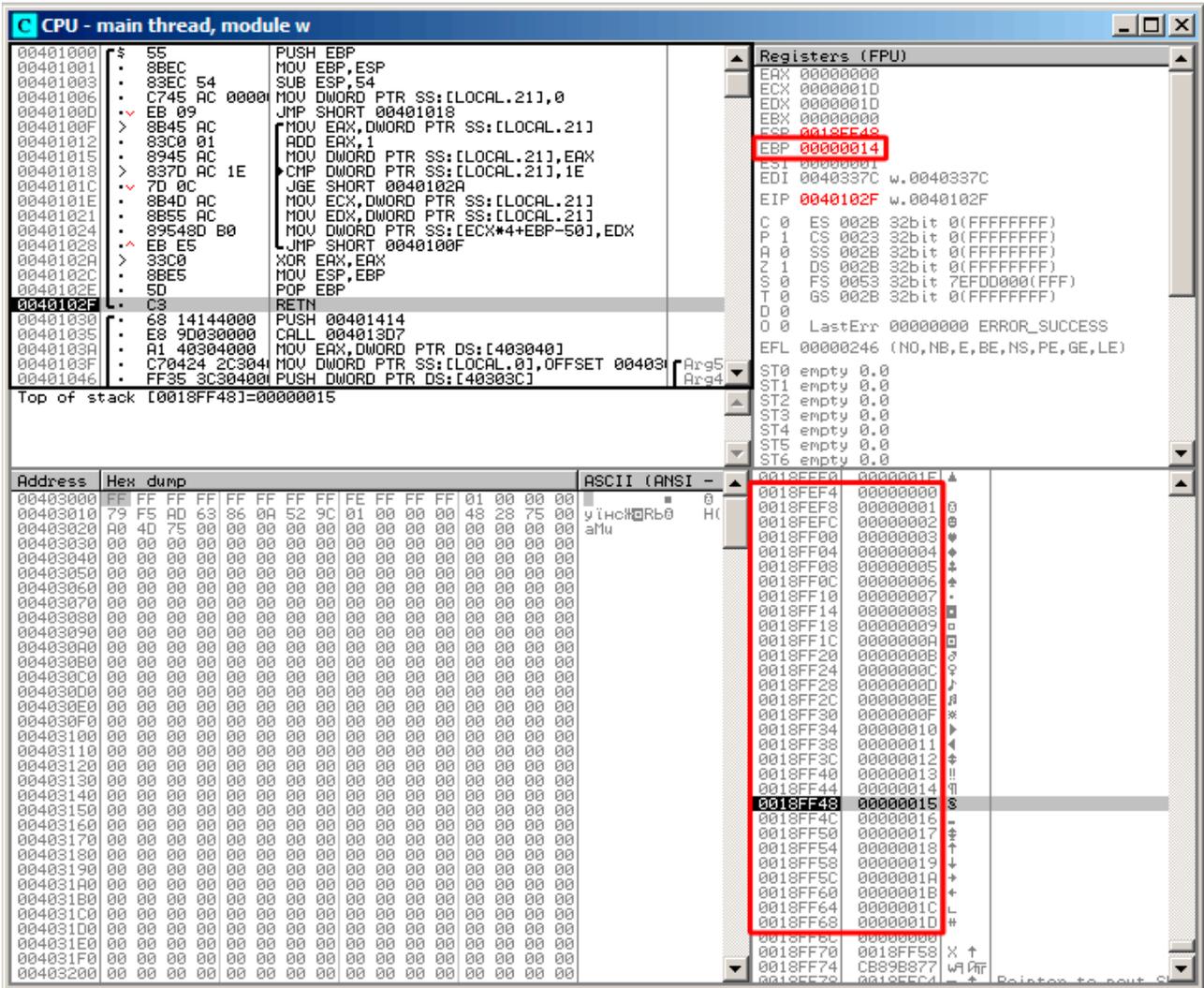


Figure 16.2: OllyDbg: after restoring the value of EBP

Trace until the function end:

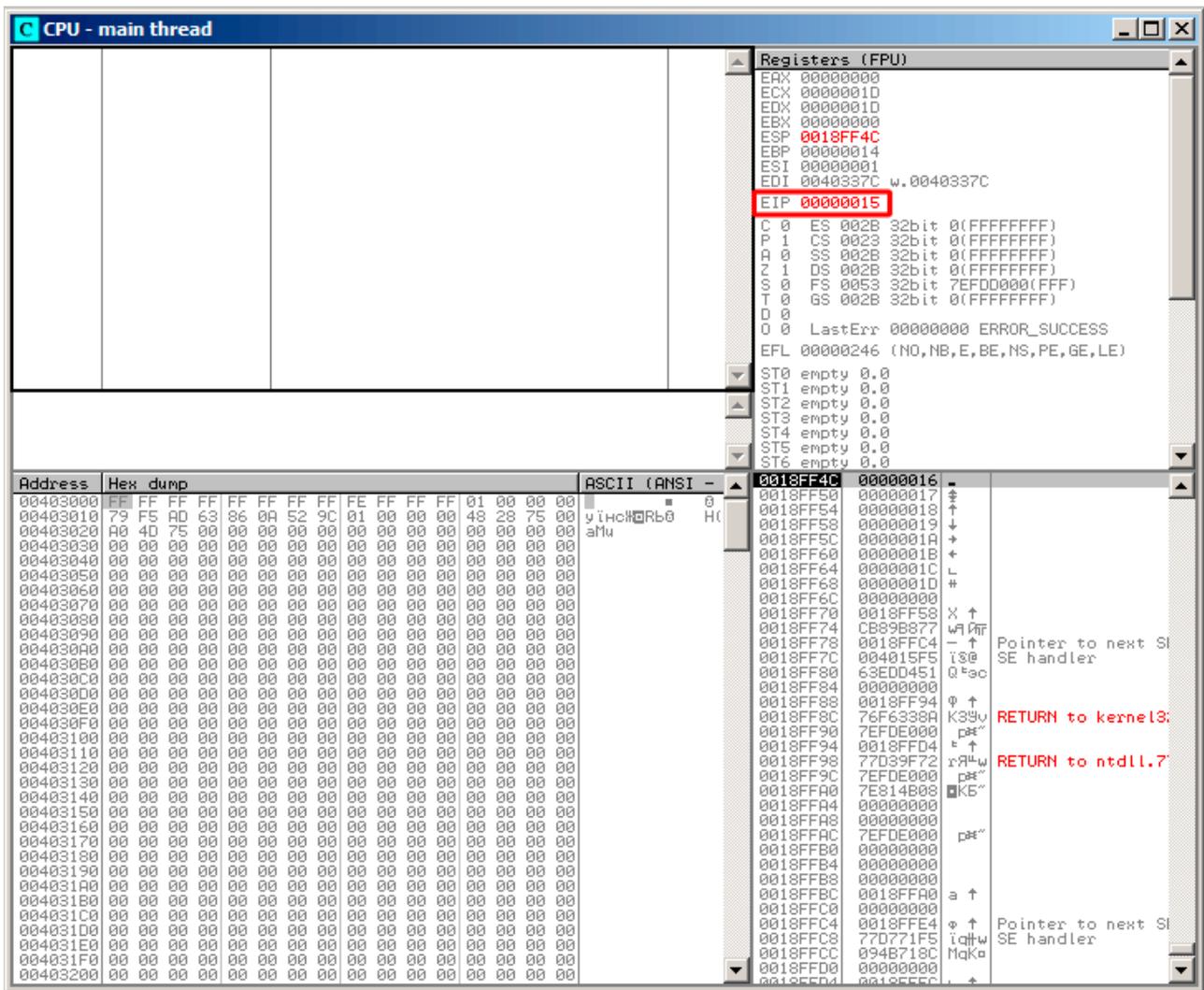


Figure 16.3: OllyDbg: EIP was restored, but OllyDbg can't disassemble at 0x15

Now please keep your eyes on the registers.

EIP is 0x15 now. It is not a legal address for code—at least for win32 code! We got there somehow against our will. It is also interesting that the EBP register contain 0x14, ECX and EDX—0x1D.

Let's study stack layout a bit more.

After the control flow was passed to main(), the value in the EBP register was saved on the stack. Then, 84 bytes were allocated for the array and the i variable. That's (20+1)\*sizeof(int). ESP now points to the \_i variable in the local stack and after the execution of the next PUSH something, something is appearing next to \_i.

That's the stack layout while the control is in main():

ESP	4 bytes allocated for i variable
ESP+4	80 bytes allocated for a[20] array
ESP+84	saved EBP value
ESP+88	return address

a[19]=something statement writes the last int in the bounds of the array (in bounds so far!)

a[20]=something statement writes something to the place where the value of EBP is saved.

Please take a look at the register state at the moment of the crash. In our case, 20 was written in the 20th element. At the function end, the function epilogue restores the original EBP value. (20 in decimal is 0x14 in hexadecimal). Then RET gets executed, which is effectively equivalent to POP EIP instruction.

The RET instruction takes the return address from the stack (that is the address in CRT), which was called main(), and 21 is stored there (0x15 in hexadecimal). The CPU traps at address 0x15, but there is no executable code there, so exception gets raised.

Welcome! It is called a *buffer overflow*<sup>3</sup>.

Replace the *int* array with a string (*char* array), create a long string deliberately and pass it to the program, to the function, which doesn't check the length of the string and copies it in a short buffer, and you'll be able to point the program to an address to which it must jump. It's not that simple in reality, but that is how it emerged<sup>4</sup>

## 16.3 One more word about arrays

Now we understand why it is impossible to write something like this in C/C++ code:

```
void f(int size)
{
    int a[size];
    ...
};
```

That's just because the compiler must know the exact array size to allocate space for it in the local stack layout on at the compiling stage.

If you need an array of arbitrary size, allocate it by using `malloc()`, then access the allocated memory block as an array of variables of the type you need.

Or use the C99 standard feature [ISO07, pp. 6.7.5/2], and it works like `alloca()` (5.2.4 on page 11) internally.

It's also possible to use garbage collecting libraries for C. And there are also libraries supporting smart pointers for C++.

## 16.4 Array of pointers to strings

Here is an example for an array of pointers.

Listing 16.4: Get month name

```
#include <stdio.h>

const char* month1[]=
{
    "January",
    "February",
    "March",
    "April",
    "May",
    "June",
    "July",
    "August",
    "September",
    "October",
    "November",
    "December"
};

// in 0..11 range
const char* get_month1 (int month)
{
    return month1[month];
};
```

### 16.4.1 x64

Listing 16.5: Optimizing MSVC 2013 x64

_DATA	SEGMENT	
month1	DQ	FLAT:\$SG3122
	DQ	FLAT:\$SG3123

<sup>3</sup>[wikipedia](#)

<sup>4</sup>Classic article about it: [\[One96\]](#).

```

DQ    FLAT:$SG3124
DQ    FLAT:$SG3125
DQ    FLAT:$SG3126
DQ    FLAT:$SG3127
DQ    FLAT:$SG3128
DQ    FLAT:$SG3129
DQ    FLAT:$SG3130
DQ    FLAT:$SG3131
DQ    FLAT:$SG3132
DQ    FLAT:$SG3133
$SG3122 DB    'January', 00H
$SG3123 DB    'February', 00H
$SG3124 DB    'March', 00H
$SG3125 DB    'April', 00H
$SG3126 DB    'May', 00H
$SG3127 DB    'June', 00H
$SG3128 DB    'July', 00H
$SG3129 DB    'August', 00H
$SG3130 DB    'September', 00H
$SG3156 DB    '%s', 0aH, 00H
$SG3131 DB    'October', 00H
$SG3132 DB    'November', 00H
$SG3133 DB    'December', 00H
_DATA  ENDS

month$ = 8
get_month1 PROC
    movsxd    rax, ecx
    lea      rcx, OFFSET FLAT:month1
    mov      rax, QWORD PTR [rcx+rax*8]
    ret      0
get_month1 ENDP

```

The code is very simple:

- The first `MOVSXD` instruction copies a 32-bit value from `ECX` (where *month* argument is passed) to `RAX` with sign-extension (because the *month* argument is of type *int*). The reason for the sign extension is that this 32-bit value is to be used in calculations with other 64-bit values. Hence, it has to be promoted to 64-bit<sup>5</sup>.
- Then the address of the pointer table is loaded into `RCX`.
- Finally, the input value (*month*) is multiplied by 8 and added to the address. Indeed: we are in a 64-bit environment and all address (or pointers) require exactly 64 bits (or 8 bytes) for storage. Hence, each table element is 8 bytes wide. And that's why to pick a specific element, *month* \* 8 bytes has to be skipped from the start. That's what `MOV` does. In addition, this instruction also loads the element at this address. For 1, an element would be a pointer to a string that contains "February", etc.

Optimizing GCC 4.9 can do the job even better<sup>6</sup>:

Listing 16.6: Optimizing GCC 4.9 x64

```

movsx    rdi, edi
mov      rax, QWORD PTR month1[0+rdi*8]
ret

```

### 32-bit MSVC

Let's also compile it in the 32-bit MSVC compiler:

Listing 16.7: Optimizing MSVC 2013 x86

```

_month$ = 8
_get_month1 PROC
    mov      eax, DWORD PTR _month$[esp-4]
    mov      eax, DWORD PTR _month1[eax*4]
    ret      0
_get_month1 ENDP

```

<sup>5</sup>It is somewhat weird, but negative array index could be passed here as *month*. And if this happens, the negative input value of *int* type is sign-extended correctly and the corresponding element before table is picked. It is not going to work correctly without sign-extension.

<sup>6</sup>"0+" was left in the listing because GCC assembler output is not tidy enough to eliminate it. It's *displacement*, and it's zero here.

The input value does not need to be extended to 64-bit value, so it is used as is. And it's multiplied by 4, because the table elements are 32-bit (or 4 bytes) wide.

## 16.5 Multidimensional arrays

Internally, a multidimensional array is essentially the same thing as a linear array. Since the computer memory is linear, it is an one-dimensional array. For convenience, this multi-dimensional array can be easily represented as one-dimensional.

For example, this is how the elements of the 3x4 array are placed in one-dimensional array of 12 cells:

Offset in memory	array element
0	[0][0]
1	[0][1]
2	[0][2]
3	[0][3]
4	[1][0]
5	[1][1]
6	[1][2]
7	[1][3]
8	[2][0]
9	[2][1]
10	[2][2]
11	[2][3]

Table 16.1: Two-dimensional array represented in memory as one-dimensional

Here is how each cell of 3\*4 array are placed in memory:

0	1	2	3
4	5	6	7
8	9	10	11

Table 16.2: Memory addresses of each cell of two-dimensional array

So, in order to calculate the address of the element we need, we first multiply the first index by 4 (array width) and then add the second index. That's called *row-major order*, and this method of array and matrix representation is used in at least C/C++ and Python. The term *row-major order* in plain English language means: "first, write the elements of the first row, then the second row ...and finally the elements of the last row".

Another method for representation is called *column-major order* (the array indices are used in reverse order) and it is used at least in FORTRAN, MATLAB and R. *column-major order* term in plain English language means: "first, write the elements of the first column, then the second column ...and finally the elements of the last column".

Which method is better? In general, in terms of performance and cache memory, the best scheme for data organization is the one, in which the elements are accessed sequentially. So if your function accesses data per row, *row-major order* is better, and vice versa.

### 16.5.1 Two-dimensional array example

We are going to work with an array of type *char*, which implies that each element requires only one byte in memory.

#### Row filling example

Let's fill the second row with these values 0..3:

Listing 16.8: Row filling example

```
#include <stdio.h>

char a[3][4];

int main()
{
```

```

int x, y;

// clear array
for (x=0; x<3; x++)
    for (y=0; y<4; y++)
        a[x][y]=0;

// fill second row by 0..3:
for (y=0; y<4; y++)
    a[1][y]=y;
};

```

All three rows are marked with red. We see that second row now has values 0, 1, 2 and 3:

Address	Hex dump
00C33370	00 00 00 00 00 01 02 03 00 00 00 00 00 00 00 00
00C33380	02 00 00 00 C3 66 47 4E C3 66 47 4E 00 00 00 00
00C33390	00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
00C333A0	00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
00C333B0	00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00

Figure 16.4: OllyDbg: array is filled

### Column filling example

Let's fill the third column with values: 0..2:

Listing 16.9: Column filling example

```

#include <stdio.h>

char a[3][4];

int main()
{
    int x, y;

    // clear array
    for (x=0; x<3; x++)
        for (y=0; y<4; y++)
            a[x][y]=0;

    // fill third column by 0..2:
    for (x=0; x<3; x++)
        a[x][2]=x;
};

```

The three rows are also marked in red here. We see that in each row, at third position these values are written: 0, 1 and 2.

Address	Hex dump
01033380	00 00 00 00 00 00 01 00 00 00 02 00 02 00 00 00
01033390	00 00 00 00 1E AA EF 31 1E AA EF 31 00 00 00 00
010333A0	00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
010333B0	00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00

Figure 16.5: OllyDbg: array is filled

## 16.5.2 Access two-dimensional array as one-dimensional

We can be easily assured that it's possible to access a two-dimensional array as one-dimensional array in at least two ways:

```

#include <stdio.h>

char a[3][4];

```

```

char get_by_coordinates1 (char array[3][4], int a, int b)
{
    return array[a][b];
};

char get_by_coordinates2 (char *array, int a, int b)
{
    // treat input array as one-dimensional
    // 4 is array width here
    return array[a*4+b];
};

char get_by_coordinates3 (char *array, int a, int b)
{
    // treat input array as pointer,
    // calculate address, get value at it
    // 4 is array width here
    return *(array+a*4+b);
};

int main()
{
    a[2][3]=123;
    printf ("%d\n", get_by_coordinates1(a, 2, 3));
    printf ("%d\n", get_by_coordinates2(a, 2, 3));
    printf ("%d\n", get_by_coordinates3(a, 2, 3));
};

```

Compile and run it: it shows correct values.

What MSVC 2013 did is fascinating, all three routines are just the same!

Listing 16.10: Optimizing MSVC 2013 x64

```

array$ = 8
a$ = 16
b$ = 24
get_by_coordinates3 PROC
; RCX=address of array
; RDX=a
; R8=b
    movsxd rax, r8d
; EAX=b
    movsxd r9, edx
; R9=a
    add rax, rcx
; RAX=b+address of array
    movzx eax, BYTE PTR [rax+r9*4]
; AL=load byte at address RAX+R9*4=b+address of array+a*4=address of array+a*4+b
    ret 0
get_by_coordinates3 ENDP

array$ = 8
a$ = 16
b$ = 24
get_by_coordinates2 PROC
    movsxd rax, r8d
    movsxd r9, edx
    add rax, rcx
    movzx eax, BYTE PTR [rax+r9*4]
    ret 0
get_by_coordinates2 ENDP

array$ = 8
a$ = 16
b$ = 24
get_by_coordinates1 PROC
    movsxd rax, r8d
    movsxd r9, edx
    add rax, rcx

```

```

    movzx    eax, BYTE PTR [rax+r9*4]
    ret     0
get_by_coordinates1 ENDP

```

### 16.5.3 Three-dimensional array example

It's thing in multidimensional arrays. Now we are going to work with an array of type *int*: each element requires 4 bytes in memory.

Let's see:

Listing 16.11: simple example

```

#include <stdio.h>

int a[10][20][30];

void insert(int x, int y, int z, int value)
{
    a[x][y][z]=value;
};

```

#### x86

We get (MSVC 2010):

Listing 16.12: MSVC 2010

```

_DATA    SEGMENT
COMM    _a:DWORD:01770H
_DATA    ENDS
PUBLIC  _insert
_TEXT    SEGMENT
_x$ = 8          ; size = 4
_y$ = 12         ; size = 4
_z$ = 16         ; size = 4
_value$ = 20     ; size = 4
_insert    PROC
    push    ebp
    mov     ebp, esp
    mov     eax, DWORD PTR _x$[ebp]
    imul   eax, 2400          ; eax=600*4*x
    mov     ecx, DWORD PTR _y$[ebp]
    imul   ecx, 120          ; ecx=30*4*y
    lea    edx, DWORD PTR _a[edx+ecx] ; edx=a + 600*4*x + 30*4*y
    mov     eax, DWORD PTR _z$[ebp]
    mov     ecx, DWORD PTR _value$[ebp]
    mov     DWORD PTR [edx+eax*4], ecx ; *(edx+z*4)=value
    pop     ebp
    ret     0
_insert    ENDP
_TEXT    ENDS

```

Nothing special. For index calculation, three input arguments are used in the formula  $address = 600 \cdot 4 \cdot x + 30 \cdot 4 \cdot y + 4z$ , to represent the array as multidimensional. Do not forget that the *int* type is 32-bit (4 bytes), so all coefficients must be multiplied by 4.

Listing 16.13: GCC 4.4.1

```

insert    public insert
          proc near

x         = dword ptr 8
y         = dword ptr 0Ch
z         = dword ptr 10h
value    = dword ptr 14h

          push    ebp

```

```

mov     ebp, esp
push   ebx
mov     ebx, [ebp+x]
mov     eax, [ebp+y]
mov     ecx, [ebp+z]
lea     edx, [eax+eax]           ; edx=y*2
mov     eax, edx                ; eax=y*2
shl     eax, 4                  ; eax=(y*2)<<4 = y*2*16 = y*32
sub     eax, edx                ; eax=y*32 - y*2=y*30
imul   edx, ebx, 600           ; edx=x*600
add     eax, edx                ; eax=eax+edx=y*30 + x*600
lea     edx, [eax+ecx]         ; edx=y*30 + x*600 + z
mov     eax, [ebp+value]
mov     dword ptr ds:a[edx*4], eax ; *(a+edx*4)=value
pop     ebx
pop     ebp
retn
insert endp

```

The GCC compiler does it differently. For one of the operations in the calculation  $(30y)$ , GCC produces code without multiplication instructions. This is how it done:  $(y + y) \ll 4 - (y + y) = (2y) \ll 4 - 2y = 2 \cdot 16 \cdot y - 2y = 32y - 2y = 30y$ . Thus, for the  $30y$  calculation, only one addition operation, one bitwise shift operation and one subtraction operation are used. This works faster.

## 16.6 Conclusion

An array is a pack of values in memory located adjacently. It's true for any element type, including structures. Access to a specific array element is just a calculation of its address.

## Chapter 17

# Manipulating specific bit(s)

A lot of functions define their input arguments as flags in bit fields. Of course, they could be substituted by a set of *bool*-typed variables, but it is not frugally.

### 17.1 Specific bit checking

#### 17.1.1 x86

Win32 API example:

```
HANDLE fh;

fh=CreateFile ("file", GENERIC_WRITE | GENERIC_READ, FILE_SHARE_READ, NULL, OPEN_ALWAYS,
FILE_ATTRIBUTE_NORMAL, NULL);
```

We get (MSVC 2010):

Listing 17.1: MSVC 2010

```
push    0
push    128                ; 00000080H
push    4
push    0
push    1
push    -1073741824       ; c0000000H
push    OFFSET $SG78813
call    DWORD PTR __imp__CreateFileA@28
mov     DWORD PTR _fh$[ebp], eax
```

Let's take a look in WinNT.h:

Listing 17.2: WinNT.h

```
#define GENERIC_READ      (0x80000000L)
#define GENERIC_WRITE     (0x40000000L)
#define GENERIC_EXECUTE   (0x20000000L)
#define GENERIC_ALL       (0x10000000L)
```

Everything is clear,  $\text{GENERIC\_READ} \mid \text{GENERIC\_WRITE} = 0x80000000 \mid 0x40000000 = 0xC0000000$ , and that value is used as the second argument for the `CreateFile()`<sup>1</sup> function.

How would `CreateFile()` check these flags? If we look in `KERNEL32.DLL` in Windows XP SP3 x86, we'll find this fragment of code in `CreateFileW`:

Listing 17.3: KERNEL32.DLL (Windows XP SP3 x86)

```
.text:7C83D429    test    byte ptr [ebp+dwDesiredAccess+3], 40h
.text:7C83D42D    mov     [ebp+var_8], 1
.text:7C83D434    jz     short loc_7C83D417
.text:7C83D436    jmp    loc_7C810817
```

<sup>1</sup>[msdn.microsoft.com/en-us/library/aa363858\(VS.85\).aspx](http://msdn.microsoft.com/en-us/library/aa363858(VS.85).aspx)

Here we see the TEST instruction, however it doesn't take the whole second argument, but only the most significant byte (`ebp+dwDesiredAccess+3`) and checks it for flag 0x40 (which implies the GENERIC\_WRITE flag here) TEST is basically the same instruction as AND, but without saving the result (recall the fact CMP is merely the same as SUB, but without saving the result (7.3.1 on page 23)).

The logic of this code fragment is as follows:

```
if ((dwDesiredAccess&0x40000000) == 0) goto loc_7C83D417
```

If AND instruction leaves this bit, the ZF flag is to be cleared and the JZ conditional jump is not to be triggered. The conditional jump is triggered only if the 0x40000000 bit is absent in `dwDesiredAccess` variable –then the result of AND is 0, ZF is to be set and the conditional jump is to be triggered.

## 17.2 Setting and clearing specific bits

For example:

```
#include <stdio.h>

#define IS_SET(flag, bit)      ((flag) & (bit))
#define SET_BIT(var, bit)     ((var) |= (bit))
#define REMOVE_BIT(var, bit) ((var) &= ~(bit))

int f(int a)
{
    int rt=a;

    SET_BIT (rt, 0x4000);
    REMOVE_BIT (rt, 0x200);

    return rt;
};

int main()
{
    f(0x12340678);
};
```

### 17.2.1 x86

#### Non-optimizing MSVC

We get (MSVC 2010):

Listing 17.4: MSVC 2010

```
_rt$ = -4          ; size = 4
_a$ = 8           ; size = 4
_f PROC
    push    ebp
    mov     ebp, esp
    push    ecx
    mov     eax, DWORD PTR _a$[ebp]
    mov     DWORD PTR _rt$[ebp], eax
    mov     ecx, DWORD PTR _rt$[ebp]
    or      ecx, 16384          ; 00004000H
    mov     DWORD PTR _rt$[ebp], ecx
    mov     edx, DWORD PTR _rt$[ebp]
    and     edx, -513          ; ffffffffH
    mov     DWORD PTR _rt$[ebp], edx
    mov     eax, DWORD PTR _rt$[ebp]
    mov     esp, ebp
    pop     ebp
    ret     0
_f ENDP
```

The OR instruction sets one bit to value while ignoring the rest.

AND resets one bit. It can be said that AND just copies all bits except one. Indeed, in the second AND operand only the bits that need to be saved are set, just the one do not want to copy is not (which is 0 in the bitmask). It is the easier way to memorize the logic.

### Optimizing MSVC

If we compile it in MSVC with optimization turned on (/Ox), the code is even shorter:

Listing 17.5: Optimizing MSVC

```

_a$ = 8                ; size = 4
_f  PROC
    mov     eax, DWORD PTR _a$[esp-4]
    and     eax, -513    ; fffffdffH
    or      eax, 16384   ; 00004000H
    ret     0
_f  ENDP

```

## 17.3 Shifts

Bit shifts in C/C++ are implemented using << and >> operators.

The x86 ISA has the SHL (SHift Left) and SHR (SHift Right) instructions for this.

Shift instructions are often used in division and multiplications by powers of two:  $2^n$  (e.g., 1, 2, 4, 8, etc): [15.1.2 on page 58](#), [15.2.1 on page 61](#).

Shifting operations are also so important because they are often used for specific bit isolation or for constructing a value of several scattered bits.

## 17.4 Counting bits set to 1

Here is a simple example of a function that calculates the number of bits set in the input value.

This operation is also called “population count”<sup>2</sup>.

```

#include <stdio.h>

#define IS_SET(flag, bit)      ((flag) & (bit))

int f(unsigned int a)
{
    int i;
    int rt=0;

    for (i=0; i<32; i++)
        if (IS_SET(a, 1<<i))
            rt++;

    return rt;
};

int main()
{
    f(0x12345678); // test
};

```

In this loop, the iteration count value  $i$  is counting from 0 to 31, so the  $1 \ll i$  statement is counting from 1 to  $0x80000000$ . Describing this operation in natural language, we would say *shift 1 by  $n$  bits left*. In other words,  $1 \ll i$  statement consequently produces all possible bit positions in a 32-bit number. The freed bit at right is always cleared.

Here is a table of all possible  $1 \ll i$  for  $i = 0 \dots 31$ :

<sup>2</sup>modern x86 CPUs (supporting SSE4) even have a POPCNT instruction for it

C/C++ expression	Power of two	Decimal form	Hexadecimal form
$1 \ll 0$	1	1	1
$1 \ll 1$	$2^1$	2	2
$1 \ll 2$	$2^2$	4	4
$1 \ll 3$	$2^3$	8	8
$1 \ll 4$	$2^4$	16	0x10
$1 \ll 5$	$2^5$	32	0x20
$1 \ll 6$	$2^6$	64	0x40
$1 \ll 7$	$2^7$	128	0x80
$1 \ll 8$	$2^8$	256	0x100
$1 \ll 9$	$2^9$	512	0x200
$1 \ll 10$	$2^{10}$	1024	0x400
$1 \ll 11$	$2^{11}$	2048	0x800
$1 \ll 12$	$2^{12}$	4096	0x1000
$1 \ll 13$	$2^{13}$	8192	0x2000
$1 \ll 14$	$2^{14}$	16384	0x4000
$1 \ll 15$	$2^{15}$	32768	0x8000
$1 \ll 16$	$2^{16}$	65536	0x10000
$1 \ll 17$	$2^{17}$	131072	0x20000
$1 \ll 18$	$2^{18}$	262144	0x40000
$1 \ll 19$	$2^{19}$	524288	0x80000
$1 \ll 20$	$2^{20}$	1048576	0x100000
$1 \ll 21$	$2^{21}$	2097152	0x200000
$1 \ll 22$	$2^{22}$	4194304	0x400000
$1 \ll 23$	$2^{23}$	8388608	0x800000
$1 \ll 24$	$2^{24}$	16777216	0x1000000
$1 \ll 25$	$2^{25}$	33554432	0x2000000
$1 \ll 26$	$2^{26}$	67108864	0x4000000
$1 \ll 27$	$2^{27}$	134217728	0x8000000
$1 \ll 28$	$2^{28}$	268435456	0x10000000
$1 \ll 29$	$2^{29}$	536870912	0x20000000
$1 \ll 30$	$2^{30}$	1073741824	0x40000000
$1 \ll 31$	$2^{31}$	2147483648	0x80000000

These constant numbers (bit masks) very often appear in code and a practicing reverse engineer must be able to spot them quickly. You probably haven't to memorize the decimal numbers, but the hexadecimal ones are very easy to remember.

These constants are very often used for mapping flags to specific bits. For example, here is excerpt from `ssl_private.h` from Apache 2.4.6 source code:

```
/**
 * Define the SSL options
 */
#define SSL_OPT_NONE          (0)
#define SSL_OPT_RELSET       (1<<0)
#define SSL_OPT_STDENVVARS  (1<<1)
#define SSL_OPT_EXPORTCERTDATA (1<<3)
#define SSL_OPT_FAKEBASICAUTH (1<<4)
#define SSL_OPT_STRICTREQUIRE (1<<5)
#define SSL_OPT_OPTRENEGOTIATE (1<<6)
#define SSL_OPT_LEGACYDNFORMAT (1<<7)
```

Let's get back to our example.

The `IS_SET` macro checks bit presence in *a*. The `IS_SET` macro is in fact the logical AND operation (*AND*) and it returns 0 if the specific bit is absent there, or the bit mask, if the bit is present. *The if()* operator in C/C++ triggers if the expression in it is not zero, it might be even 123456, that is why it always works correctly.

## 17.4.1 x86

### MSVC

Let's compile (MSVC 2010):

Listing 17.6: MSVC 2010

```

_rt$ = -8          ; size = 4
_i$ = -4          ; size = 4
_a$ = 8           ; size = 4
_f PROC
    push    ebp
    mov     ebp, esp
    sub     esp, 8
    mov     DWORD PTR _rt$[ebp], 0
    mov     DWORD PTR _i$[ebp], 0
    jmp     SHORT $LN4@f
$LN3@f:
    mov     eax, DWORD PTR _i$[ebp] ; increment of i
    add     eax, 1
    mov     DWORD PTR _i$[ebp], eax
$LN4@f:
    cmp     DWORD PTR _i$[ebp], 32 ; 00000020H
    jge     SHORT $LN2@f          ; loop finished?
    mov     edx, 1
    mov     ecx, DWORD PTR _i$[ebp]
    shl     edx, cl                ; EDX=EDX<<CL
    and     edx, DWORD PTR _a$[ebp]
    je      SHORT $LN1@f          ; result of AND instruction was 0?
                                        ; then skip next instructions
    mov     eax, DWORD PTR _rt$[ebp] ; no, not zero
    add     eax, 1                ; increment rt
    mov     DWORD PTR _rt$[ebp], eax
$LN1@f:
    jmp     SHORT $LN3@f
$LN2@f:
    mov     eax, DWORD PTR _rt$[ebp]
    mov     esp, ebp
    pop     ebp
    ret     0
_f ENDP

```

## 17.4.2 x64

Let's modify the example slightly to extend it to 64-bit:

```

#include <stdio.h>
#include <stdint.h>

#define IS_SET(flag, bit)      ((flag) & (bit))

int f(uint64_t a)
{
    uint64_t i;
    int rt=0;

    for (i=0; i<64; i++)
        if (IS_SET(a, 1ULL<<i))
            rt++;

    return rt;
};

```

## Optimizing MSVC 2010

Listing 17.7: MSVC 2010

```

a$ = 8
f PROC
; RCX = input value
    xor     eax, eax
    mov     edx, 1
    lea     r8d, QWORD PTR [rax+64]

```

```

; R8D=64
    npad    5
$LL4@f:
    test    rdx, rcx
; there are no such bit in input value?
; skip the next INC instruction then.
    je     SHORT $LN3@f
    inc    eax    ; rt++
$LN3@f:
    rol    rdx, 1 ; RDX=RDX<<1
    dec    r8     ; R8--
    jne    SHORT $LL4@f
    fatret 0
f      ENDP

```

Here the ROL instruction is used instead of SHL, which is in fact “rotate left” instead of “shift left”, but in this example it works just as SHL.

R8 here is counting from 64 to 0. It’s just like an inverted *i*.

Here is a table of some registers during the execution:

RDX	R8
0x0000000000000001	64
0x0000000000000002	63
0x0000000000000004	62
0x0000000000000008	61
...	...
0x4000000000000000	2
0x8000000000000000	1

## Optimizing MSVC 2012

Listing 17.8: MSVC 2012

```

a$ = 8
f    PROC
; RCX = input value
    xor    eax, eax
    mov    edx, 1
    lea   r8d, QWORD PTR [rax+32]
; EDX = 1, R8D = 32
    npad    5
$LL4@f:
; pass 1 -----
    test    rdx, rcx
    je     SHORT $LN3@f
    inc    eax    ; rt++
$LN3@f:
    rol    rdx, 1 ; RDX=RDX<<1
; -----
; pass 2 -----
    test    rdx, rcx
    je     SHORT $LN11@f
    inc    eax    ; rt++
$LN11@f:
    rol    rdx, 1 ; RDX=RDX<<1
; -----
    dec    r8     ; R8--
    jne    SHORT $LL4@f
    fatret 0
f      ENDP

```

Optimizing MSVC 2012 does almost the same job as optimizing MSVC 2010, but somehow, it generates two identical loop bodies and the loop count is now 32 instead of 64. To be honest, it’s not possible to say why. Some optimization trick? Maybe it’s better for the loop body to be slightly longer? Anyway, such code is relevant here to show that sometimes the compiler output may be really weird and illogical, but perfectly working.

## 17.5 Conclusion

Analogous to the C/C++ shifting operators  $\ll$  and  $\gg$ , the shift instructions in x86 are SHR/SHL (for unsigned values) and SAR/SHL (for signed values).

The shift instructions in ARM are LSR/LSL (for unsigned values) and ASR/LSL (for signed values). It's also possible to add shift suffix to some instructions (which are called "data processing instructions").

### 17.5.1 Check for specific bit (known at compile stage)

Test if the 1000000 bit (0x40) is present in the register's value:

Listing 17.9: C/C++

```
if (input&0x40)
    ...
```

Listing 17.10: x86

```
TEST REG, 40h
JNZ is_set
; bit is not set
```

Listing 17.11: x86

```
TEST REG, 40h
JZ is_cleared
; bit is set
```

Sometimes, AND is used instead of TEST, but the flags that are set are the same.

### 17.5.2 Check for specific bit (specified at runtime)

This is usually done by this C/C++ code snippet (shift value by  $n$  bits right, then cut off lowest bit):

Listing 17.12: C/C++

```
if ((value>>n)&1)
    ....
```

This is usually implemented in x86 code as:

Listing 17.13: x86

```
; REG=input_value
; CL=n
SHR REG, CL
AND REG, 1
```

Or (shift 1 bit  $n$  times left, isolate this bit in input value and check if it's not zero):

Listing 17.14: C/C++

```
if (value & (1<<n))
    ....
```

This is usually implemented in x86 code as:

Listing 17.15: x86

```
; CL=n
MOV REG, 1
SHL REG, CL
AND input_value, REG
```

**17.5.3 Set specific bit (known at compile stage)**

Listing 17.16: C/C++

```
value=value|0x40;
```

Listing 17.17: x86

```
OR REG, 40h
```

**17.5.4 Set specific bit (specified at runtime)**

Listing 17.18: C/C++

```
value=value|(1<<n);
```

This is usually implemented in x86 code as:

Listing 17.19: x86

```
; CL=n
MOV REG, 1
SHL REG, CL
OR input_value, REG
```

**17.5.5 Clear specific bit (known at compile stage)**

Just apply AND operation with the inverted value:

Listing 17.20: C/C++

```
value=value&(~0x40);
```

Listing 17.21: x86

```
AND REG, 0FFFFFFBFh
```

Listing 17.22: x64

```
AND REG, 0FFFFFFFFFFFFFFBFh
```

This is actually leaving all bits set except one.

**17.5.6 Clear specific bit (specified at runtime)**

Listing 17.23: C/C++

```
value=value&(~(1<<n));
```

Listing 17.24: x86

```
; CL=n
MOV REG, 1
SHL REG, CL
NOT REG
AND input_value, REG
```

## Chapter 18

# Linear congruential generator as pseudorandom number generator

The linear congruential generator is probably the simplest possible way to generate random numbers. It's not in favour in modern times<sup>1</sup>, but it's so simple (just one multiplication, one addition and one AND operation), we can use it as an example.

```
#include <stdint.h>

// constants from the Numerical Recipes book
#define RNG_a 1664525
#define RNG_c 1013904223

static uint32_t rand_state;

void my_srand (uint32_t init)
{
    rand_state=init;
}

int my_rand ()
{
    rand_state=rand_state*RNG_a;
    rand_state=rand_state+RNG_c;
    return rand_state & 0x7fff;
}
```

There are two functions: the first one is used to initialize the internal state, and the second one is called to generate pseudorandom numbers.

We see that two constants are used in the algorithm. They are taken from [Pre+07]. Let's define them using a `#define` C/C++ statement. It's a macro. The difference between a C/C++ macro and a constant is that all macros are replaced with their value by C/C++ preprocessor, and they don't take any memory, unlike variables. In contrast, a constant is a read-only variable. It's possible to take a pointer (or address) of a constant variable, but impossible to do so with a macro.

The last AND operation is needed because by C-standard `my_rand()` has to return a value in the 0..32767 range. If you want to get 32-bit pseudorandom values, just omit the last AND operation.

### 18.1 x86

Listing 18.1: Optimizing MSVC 2013

```
_BSS SEGMENT
_rand_state DD 01H DUP (?)
_BSS ENDS

_init$ = 8
_srand PROC
    mov     eax, DWORD PTR _init$[esp-4]
    mov     DWORD PTR _rand_state, eax
```

<sup>1</sup>Mersenne twister is better

```

ret    0
_srand ENDP

_TEXT SEGMENT
_rand PROC
    imul    eax, DWORD PTR _rand_state, 1664525
    add     eax, 1013904223    ; 3c6ef35fH
    mov     DWORD PTR _rand_state, eax
    and     eax, 32767        ; 00007fffH
    ret     0
_rand    ENDP
_TEXT    ENDS

```

Here we see it: both constants are embedded into the code. There is no memory allocated for them. The `my_srand()` function just copies its input value into the internal `rand_state` variable.

`my_rand()` takes it, calculates the next `rand_state`, cuts it and leaves it in the EAX register.

The non-optimized version is more verbose:

Listing 18.2: Non-optimizing MSVC 2013

```

_BSS    SEGMENT
_rand_state DD  01H DUP (?)
_BSS    ENDS

_init$ = 8
_srand  PROC
    push    ebp
    mov     ebp, esp
    mov     eax, DWORD PTR _init$[ebp]
    mov     DWORD PTR _rand_state, eax
    pop     ebp
    ret     0
_srand  ENDP

_TEXT  SEGMENT
_rand  PROC
    push    ebp
    mov     ebp, esp
    imul   eax, DWORD PTR _rand_state, 1664525
    mov     DWORD PTR _rand_state, eax
    mov     ecx, DWORD PTR _rand_state
    add     ecx, 1013904223    ; 3c6ef35fH
    mov     DWORD PTR _rand_state, ecx
    mov     eax, DWORD PTR _rand_state
    and     eax, 32767        ; 00007fffH
    pop     ebp
    ret     0
_rand    ENDP
_TEXT    ENDS

```

## 18.2 x64

The x64 version is mostly the same and uses 32-bit registers instead of 64-bit ones (because we are working with *int* values here). But `my_srand()` takes its input argument from the ECX register rather than from stack:

Listing 18.3: Optimizing MSVC 2013 x64

```

_BSS    SEGMENT
rand_state DD  01H DUP (?)
_BSS    ENDS

init$ = 8
my_srand PROC
; ECX = input argument
    mov     DWORD PTR rand_state, ecx

```

```
    ret    0
my_srand ENDP

_TEXT SEGMENT
my_rand PROC
    imul  eax, DWORD PTR rand_state, 1664525    ; 0019660dH
    add   eax, 1013904223                       ; 3c6ef35fH
    mov   DWORD PTR rand_state, eax
    and   eax, 32767                             ; 00007fffH
    ret   0
my_rand ENDP

_TEXT ENDS
```

# Chapter 19

## Structures

A C/C++ structure, with some assumptions, is just a set of variables, always stored in memory together, not necessary of the same type <sup>1</sup>.

### 19.1 MSVC: SYSTEMTIME example

Let's take the SYSTEMTIME<sup>2</sup> win32 structure that describes time.

This is how it's defined:

Listing 19.1: WinBase.h

```
typedef struct _SYSTEMTIME {
    WORD wYear;
    WORD wMonth;
    WORD wDayOfWeek;
    WORD wDay;
    WORD wHour;
    WORD wMinute;
    WORD wSecond;
    WORD wMilliseconds;
} SYSTEMTIME, *PSYSTEMTIME;
```

Let's write a C function to get the current time:

```
#include <windows.h>
#include <stdio.h>

void main()
{
    SYSTEMTIME t;
    GetSystemTime (&t);

    printf ("%04d-%02d-%02d %02d:%02d:%02d\n",
            t.wYear, t.wMonth, t.wDay,
            t.wHour, t.wMinute, t.wSecond);

    return;
};
```

We get (MSVC 2010):

Listing 19.2: MSVC 2010 /GS-

```
_t$ = -16 ; size = 16
_main PROC
    push    ebp
    mov     ebp, esp
    sub     esp, 16
    lea    eax, DWORD PTR _t$[ebp]
```

<sup>1</sup>AKA "heterogeneous container"

<sup>2</sup>MSDN: [SYSTEMTIME structure](#)

```

push    eax
call    DWORD PTR __imp__GetSystemTime@4
movzx   ecx, WORD PTR _t$[ebp+12] ; wSecond
push    ecx
movzx   edx, WORD PTR _t$[ebp+10] ; wMinute
push    edx
movzx   eax, WORD PTR _t$[ebp+8] ; wHour
push    eax
movzx   ecx, WORD PTR _t$[ebp+6] ; wDay
push    ecx
movzx   edx, WORD PTR _t$[ebp+2] ; wMonth
push    edx
movzx   eax, WORD PTR _t$[ebp] ; wYear
push    eax
push    OFFSET $SG78811 ; '%04d-%02d-%02d %02d:%02d:%02d', 0aH, 00H
call    _printf
add     esp, 28
xor     eax, eax
mov     esp, ebp
pop     ebp
ret     0
_main   ENDP

```

16 bytes are allocated for this structure in the local stack –that is exactly `sizeof(WORD)*8` (there are 8 WORD variables in the structure).

Pay attention to the fact that the structure begins with the `wYear` field. It can be said that a pointer to the `SYSTEMTIME` structure is passed to the `GetSystemTime()`<sup>3</sup>, but it is also can be said that a pointer to the `wYear` field is passed, and that is the same! `GetSystemTime()` writes the current year to the WORD pointer pointing to, then shifts 2 bytes ahead, writes current month, etc, etc.

### 19.1.1 Replacing the structure with array

The fact that the structure fields are just variables located side-by-side, can be easily demonstrated by doing the following. Keeping in mind the `SYSTEMTIME` structure description, it's possible to rewrite this simple example like this:

```

#include <windows.h>
#include <stdio.h>

void main()
{
    WORD array[8];
    GetSystemTime (array);

    printf ("%04d-%02d-%02d %02d:%02d:%02d\n",
           array[0] /* wYear */, array[1] /* wMonth */, array[3] /* wDay */,
           array[4] /* wHour */, array[5] /* wMinute */, array[6] /* wSecond */);

    return;
};

```

The compiler grumbles a bit:

```

systemtime2.c(7) : warning C4133: 'function' : incompatible types - from 'WORD [8]' to 'LPSYSTEMTIME'

```

But nevertheless, it produces this code:

Listing 19.3: Non-optimizing MSVC 2010

```

$SG78573 DB      '%04d-%02d-%02d %02d:%02d:%02d', 0aH, 00H

_array$ = -16   ; size = 16
_main   PROC
        push    ebp
        mov     ebp, esp
        sub     esp, 16

```

<sup>3</sup>MSDN: [SYSTEMTIME structure](#)

```

lea    eax, DWORD PTR _array$[ebp]
push   eax
call   DWORD PTR __imp__GetSystemTime@4
movzx  ecx, WORD PTR _array$[ebp+12] ; wSecond
push   ecx
movzx  edx, WORD PTR _array$[ebp+10] ; wMinute
push   edx
movzx  eax, WORD PTR _array$[ebp+8] ; wHour
push   eax
movzx  ecx, WORD PTR _array$[ebp+6] ; wDay
push   ecx
movzx  edx, WORD PTR _array$[ebp+2] ; wMonth
push   edx
movzx  eax, WORD PTR _array$[ebp] ; wYear
push   eax
push   OFFSET $SG78573
call   _printf
add    esp, 28
xor    eax, eax
mov    esp, ebp
pop    ebp
ret    0
_main  ENDP

```

And it works just as the same!

It is very interesting that the result in assembly form cannot be distinguished from the result of the previous compilation. So by looking at this code, one cannot say for sure if there was a structure declared, or an array.

Nevertheless, no sane person would do it, as it is not convenient. Also the structure fields may be changed by developers, swapped, etc.

## 19.2 Let's allocate space for a structure using malloc()

Sometimes it is simpler to place structures not the in local stack, but in the [heap](#):

```

#include <windows.h>
#include <stdio.h>

void main()
{
    SYSTEMTIME *t;

    t=(SYSTEMTIME *)malloc (sizeof (SYSTEMTIME));

    GetSystemTime (t);

    printf ("%04d-%02d-%02d %02d:%02d:%02d\n",
           t->wYear, t->wMonth, t->wDay,
           t->wHour, t->wMinute, t->wSecond);

    free (t);

    return;
};

```

Let's compile it now with optimization (/Ox) so it would be easy see what we need.

Listing 19.4: Optimizing MSVC

```

_main  PROC
push   esi
push   16
call   _malloc
add    esp, 4
mov    esi, eax
push   esi
call   DWORD PTR __imp__GetSystemTime@4
movzx  eax, WORD PTR [esi+12] ; wSecond

```

```

movzx ecx, WORD PTR [esi+10] ; wMinute
movzx edx, WORD PTR [esi+8] ; wHour
push  eax
movzx  eax, WORD PTR [esi+6] ; wDay
push  ecx
movzx  ecx, WORD PTR [esi+2] ; wMonth
push  edx
movzx  edx, WORD PTR [esi] ; wYear
push  eax
push  ecx
push  edx
push  OFFSET $SG78833
call  _printf
push  esi
call  _free
add   esp, 32
xor   eax, eax
pop   esi
ret   0
_main ENDP

```

So, `sizeof(SYSTEMTIME) = 16` and that is exact number of bytes to be allocated by `malloc()`. It returns a pointer to a freshly allocated memory block in the EAX register, which is then moved into the ESI register. `GetSystemTime()` win32 function takes care of saving value in ESI, and that is why it is not saved here and continues to be used after the `GetSystemTime()` call.

New instruction – `MOVZX (Move with Zero eXtend)`. It may be used in most cases as `MOVSX`, but it sets the remaining bits to 0. That's because `printf()` requires a 32-bit `int`, but we got a `WORD` in the structure – that is 16-bit unsigned type. That's why by copying the value from a `WORD` into `int`, bits from 16 to 31 must be cleared, because a random noise may be there, which is left from the previous operations on the register(s).

In this example, it's possible to represent the structure as an array of 8 `WORDS`:

```

#include <windows.h>
#include <stdio.h>

void main()
{
    WORD *t;

    t=(WORD *)malloc (16);

    GetSystemTime (t);

    printf ("%04d-%02d-%02d %02d:%02d:%02d\n",
           t[0] /* wYear */, t[1] /* wMonth */, t[3] /* wDay */,
           t[4] /* wHour */, t[5] /* wMinute */, t[6] /* wSecond */);

    free (t);

    return;
};

```

We get:

Listing 19.5: Optimizing MSVC

```

$SG78594 DB      '%04d-%02d-%02d %02d:%02d:%02d', 0aH, 00H

_main  PROC
        push    esi
        push    16
        call   _malloc
        add     esp, 4
        mov     esi, eax
        push   esi
        call   DWORD PTR __imp__GetSystemTime@4
        movzx  eax, WORD PTR [esi+12]
        movzx  ecx, WORD PTR [esi+10]
        movzx  edx, WORD PTR [esi+8]
        push   eax

```

```

    movzx    eax, WORD PTR [esi+6]
    push     ecx
    movzx    ecx, WORD PTR [esi+2]
    push     edx
    movzx    edx, WORD PTR [esi]
    push     eax
    push     ecx
    push     edx
    push     OFFSET $SG78594
    call     _printf
    push     esi
    call     _free
    add     esp, 32
    xor     eax, eax
    pop     esi
    ret     0
_main     ENDP

```

Again, we got the code cannot be distinguished from the previous one. And again it should be noted, you haven't to do this in practice, unless you really know what you are doing.

## 19.3 Fields packing in structure

One important thing is fields packing in structures<sup>4</sup>.

Let's take a simple example:

```

#include <stdio.h>

struct s
{
    char a;
    int b;
    char c;
    int d;
};

void f(struct s s)
{
    printf ("a=%d; b=%d; c=%d; d=%d\n", s.a, s.b, s.c, s.d);
};

int main()
{
    struct s tmp;
    tmp.a=1;
    tmp.b=2;
    tmp.c=3;
    tmp.d=4;
    f(tmp);
};

```

As we see, we have two *char* fields (each is exactly one byte) and two more –*int* (each – 4 bytes).

### 19.3.1 x86

This compiles to:

Listing 19.6: MSVC 2012 /GS- /Ob0

```

1  _tmp$ = -16
2  _main PROC
3      push    ebp
4      mov     ebp, esp
5      sub     esp, 16

```

<sup>4</sup>See also: [Wikipedia: Data structure alignment](#)

```

6   mov     BYTE PTR _tmp$[ebp], 1    ; set field a
7   mov     DWORD PTR _tmp$[ebp+4], 2 ; set field b
8   mov     BYTE PTR _tmp$[ebp+8], 3  ; set field c
9   mov     DWORD PTR _tmp$[ebp+12], 4 ; set field d
10  sub     esp, 16                    ; allocate place for temporary structure
11  mov     eax, esp
12  mov     ecx, DWORD PTR _tmp$[ebp] ; copy our structure to the temporary one
13  mov     DWORD PTR [eax], ecx
14  mov     edx, DWORD PTR _tmp$[ebp+4]
15  mov     DWORD PTR [eax+4], edx
16  mov     ecx, DWORD PTR _tmp$[ebp+8]
17  mov     DWORD PTR [eax+8], ecx
18  mov     edx, DWORD PTR _tmp$[ebp+12]
19  mov     DWORD PTR [eax+12], edx
20  call    _f
21  add     esp, 16
22  xor     eax, eax
23  mov     esp, ebp
24  pop     ebp
25  ret     0
26 _main   ENDP
27
28 _s$ = 8 ; size = 16
29 ?f@@YAXUs@@@Z PROC ; f
30   push   ebp
31   mov    ebp, esp
32   mov    eax, DWORD PTR _s$[ebp+12]
33   push  eax
34   movsx ecx, BYTE PTR _s$[ebp+8]
35   push  ecx
36   mov    edx, DWORD PTR _s$[ebp+4]
37   push  edx
38   movsx eax, BYTE PTR _s$[ebp]
39   push  eax
40   push  OFFSET $SG3842
41   call  _printf
42   add   esp, 20
43   pop   ebp
44   ret   0
45 ?f@@YAXUs@@@Z ENDP ; f
46 _TEXT   ENDS

```

We pass the structure as a whole, but in fact, as we can see, the structure is being copied to a temporary one (a place in stack is allocated in line 10 for it, and then all 4 fields, one by one, are copied in lines 12 ... 19), and then its pointer (address) is to be passed. The structure is copied because it's not known whether the `f()` function going to modify the structure or not. If it gets changed, then the structure in `main()` has to remain as it was. We could use C/C++ pointers, and the resulting code will be almost the same, but without the copying.

As we can see, each field's address is aligned on a 4-byte boundary. That's why each `char` occupies 4 bytes here (like `int`). Why? Because it is easier for the CPU to access memory at aligned addresses and to cache data from it.

However, it is not very economical.

Let's try to compile it with option (`/Zp1`) (`/Zp[n]` pack structures on *n*-byte boundary).

Listing 19.7: MSVC 2012 /GS- /Zp1

```

1  _main   PROC
2   push  ebp
3   mov   ebp, esp
4   sub   esp, 12
5   mov   BYTE PTR _tmp$[ebp], 1    ; set field a
6   mov   DWORD PTR _tmp$[ebp+1], 2 ; set field b
7   mov   BYTE PTR _tmp$[ebp+5], 3  ; set field c
8   mov   DWORD PTR _tmp$[ebp+6], 4 ; set field d
9   sub   esp, 12                    ; allocate place for temporary structure
10  mov   eax, esp
11  mov   ecx, DWORD PTR _tmp$[ebp] ; copy 10 bytes
12  mov   DWORD PTR [eax], ecx
13  mov   edx, DWORD PTR _tmp$[ebp+4]
14  mov   DWORD PTR [eax+4], edx

```

```

15     mov     cx, WORD PTR _tmp$[ebp+8]
16     mov     WORD PTR [eax+8], cx
17     call    _f
18     add     esp, 12
19     xor     eax, eax
20     mov     esp, ebp
21     pop     ebp
22     ret     0
23 _main     ENDP
24
25 _TEXT     SEGMENT
26 _s$ = 8 ; size = 10
27 ?f@@YAXUs@@@Z PROC     ; f
28     push   ebp
29     mov     ebp, esp
30     mov     eax, DWORD PTR _s$[ebp+6]
31     push   eax
32     movsx  ecx, BYTE PTR _s$[ebp+5]
33     push   ecx
34     mov     edx, DWORD PTR _s$[ebp+1]
35     push   edx
36     movsx  eax, BYTE PTR _s$[ebp]
37     push   eax
38     push   OFFSET $SG3842
39     call   _printf
40     add     esp, 20
41     pop     ebp
42     ret     0
43 ?f@@YAXUs@@@Z ENDP     ; f

```

Now the structure takes only 10 bytes and each *char* value takes 1 byte. What does it give to us? Size economy. And as drawback –the CPU accessing these fields slower than it could.

The structure is also copied in `main()`. Not field-by-field, but directly 10 bytes, using three pairs of `MOV`. Why not 4? The compiler decided that it's better to copy 10 bytes using 3 `MOV` pairs than to copy two 32-bit words and two bytes using 4 `MOV` pairs.

As it can be easily guessed, if the structure is used in many source and object files, all these must be compiled with the same convention about structures packing.

Aside from `MSVC /Zp` option which sets how to align each structure field, there is also the `#pragma pack` compiler option, which can be defined right in the source code. It is available in both `MSVC`<sup>5</sup> and `GCC`<sup>6</sup>.

Let's get back to the `SYSTEMTIME` structure that consists of 16-bit fields. How does our compiler know to pack them on 1-byte alignment boundary?

`WinNT.h` file has this:

Listing 19.8: `WinNT.h`

```
#include "pshpack1.h"
```

And this:

Listing 19.9: `WinNT.h`

```
#include "pshpack4.h" // 4 byte packing is the default
```

The file `PshPack1.h` looks like:

Listing 19.10: `PshPack1.h`

```

#if ! (defined(lint) || defined(RC_INVOKED))
#if ( _MSC_VER >= 800 && !defined(_M_I86)) || defined(_PUSHPOP_SUPPORTED)
#pragma warning(disable:4103)
#if !(defined( MIDL_PASS )) || defined( __midl )
#pragma pack(push,1)
#else
#pragma pack(1)
#endif
#endif

```

<sup>5</sup>MSDN: Working with Packing Structures

<sup>6</sup>Structure-Packing Pragma

```
#else
#pragma pack(1)
#endif
#endif /* ! (defined(lint) || defined(RC_INVOKED)) */
```

This tells the compiler how to pack the structures defined after `#pragma pack`.

### 19.3.2 One more word

Passing a structure as a function argument (instead of passing a pointer to structure) is the same as passing all structure fields one by one. If the structure fields are packed by default, the `f()` function can be rewritten as:

```
void f(char a, int b, char c, int d)
{
    printf ("a=%d; b=%d; c=%d; d=%d\n", a, b, c, d);
};
```

And that leads to the same code.

## 19.4 Nested structures

Now what about situations when one structure is defined inside of another?

```
#include <stdio.h>

struct inner_struct
{
    int a;
    int b;
};

struct outer_struct
{
    char a;
    int b;
    struct inner_struct c;
    char d;
    int e;
};

void f(struct outer_struct s)
{
    printf ("a=%d; b=%d; c.a=%d; c.b=%d; d=%d; e=%d\n",
           s.a, s.b, s.c.a, s.c.b, s.d, s.e);
};

int main()
{
    struct outer_struct s;
    s.a=1;
    s.b=2;
    s.c.a=100;
    s.c.b=101;
    s.d=3;
    s.e=4;
    f(s);
};
```

... in this case, both `inner_struct` fields are to be placed between the `a,b` and `d,e` fields of the `outer_struct`.

Let's compile (MSVC 2010):

Listing 19.11: Optimizing MSVC 2010 /Ob0

```
$SG2802 DB      'a=%d; b=%d; c.a=%d; c.b=%d; d=%d; e=%d', 0aH, 00H
_TEXT SEGMENT
```

```

_s$ = 8
_f PROC
    mov     eax, DWORD PTR _s$[esp+16]
    movsx  ecx, BYTE PTR _s$[esp+12]
    mov     edx, DWORD PTR _s$[esp+8]
    push   eax
    mov     eax, DWORD PTR _s$[esp+8]
    push   ecx
    mov     ecx, DWORD PTR _s$[esp+8]
    push   edx
    movsx  edx, BYTE PTR _s$[esp+8]
    push   eax
    push   ecx
    push   edx
    push   OFFSET $SG2802 ; 'a=%d; b=%d; c.a=%d; c.b=%d; d=%d; e=%d'
    call   _printf
    add    esp, 28
    ret    0
_f ENDP

_s$ = -24
_main PROC
    sub    esp, 24
    push   ebx
    push   esi
    push   edi
    mov    ecx, 2
    sub    esp, 24
    mov    eax, esp
    mov    BYTE PTR _s$[esp+60], 1
    mov    ebx, DWORD PTR _s$[esp+60]
    mov    DWORD PTR [eax], ebx
    mov    DWORD PTR [eax+4], ecx
    lea   edx, DWORD PTR [ecx+98]
    lea   esi, DWORD PTR [ecx+99]
    lea   edi, DWORD PTR [ecx+2]
    mov    DWORD PTR [eax+8], edx
    mov    BYTE PTR _s$[esp+76], 3
    mov    ecx, DWORD PTR _s$[esp+76]
    mov    DWORD PTR [eax+12], esi
    mov    DWORD PTR [eax+16], ecx
    mov    DWORD PTR [eax+20], edi
    call  _f
    add    esp, 24
    pop    edi
    pop    esi
    xor    eax, eax
    pop    ebx
    add    esp, 24
    ret    0
_main ENDP

```

One curious thing here is that by looking onto this assembly code, we do not even see that another structure was used inside of it! Thus, we would say, nested structures are unfolded into *linear* or *one-dimensional* structure.

Of course, if we replace the `struct inner_struct c;` declaration with `struct inner_struct *c;` (thus making a pointer here) the situation will be quite different.

## 19.5 Bit fields in a structure

### 19.5.1 CPUID example

The C/C++ language allows to define the exact number of bits for each structure field. It is very useful if one needs to save memory space. For example, one bit is enough for a *bool* variable. But of course, it is not rational if speed is important.

Let's consider the CPUID<sup>7</sup> instruction example. This instruction returns information about the current CPU and its features.

<sup>7</sup>[wikipedia](#)

If the EAX is set to 1 before the instruction's execution, CPUID returning this information packed into the EAX register:

3:0 (4 bits)	Stepping
7:4 (4 bits)	Model
11:8 (4 bits)	Family
13:12 (2 bits)	Processor Type
19:16 (4 bits)	Extended Model
27:20 (8 bits)	Extended Family

MSVC 2010 has CPUID macro, but GCC 4.4.1 does not. So let's make this function by ourselves for GCC with the help of its built-in assembler<sup>8</sup>.

```
#include <stdio.h>

#ifdef __GNUC__
static inline void cpuid(int code, int *a, int *b, int *c, int *d) {
    asm volatile("cpuid":"=a"(*a),"=b"(*b),"=c"(*c),"=d"(*d):"a"(code));
}
#endif

#ifdef _MSC_VER
#include <intrin.h>
#endif

struct CPUID_1_EAX
{
    unsigned int stepping:4;
    unsigned int model:4;
    unsigned int family_id:4;
    unsigned int processor_type:2;
    unsigned int reserved1:2;
    unsigned int extended_model_id:4;
    unsigned int extended_family_id:8;
    unsigned int reserved2:4;
};

int main()
{
    struct CPUID_1_EAX *tmp;
    int b[4];

#ifdef _MSC_VER
    __cpuid(b,1);
#endif

#ifdef __GNUC__
    cpuid (1, &b[0], &b[1], &b[2], &b[3]);
#endif

    tmp=(struct CPUID_1_EAX *)&b[0];

    printf ("stepping=%d\n", tmp->stepping);
    printf ("model=%d\n", tmp->model);
    printf ("family_id=%d\n", tmp->family_id);
    printf ("processor_type=%d\n", tmp->processor_type);
    printf ("extended_model_id=%d\n", tmp->extended_model_id);
    printf ("extended_family_id=%d\n", tmp->extended_family_id);

    return 0;
};
```

After CPUID fills EAX/EBX/ECX/EDX, these registers are to be written in the b[] array. Then, we have a pointer to the CPUID\_1\_EAX structure and we point it to the value in EAX from the b[] array.

In other words, we treat a 32-bit *int* value as a structure. Then we read specific bits from the structure.

<sup>8</sup>[More about internal GCC assembler](#)

**MSVC**

Let's compile it in MSVC 2008 with /Ox option:

Listing 19.12: Optimizing MSVC 2008

```

_b$ = -16 ; size = 16
_main PROC
    sub     esp, 16
    push   ebx

    xor     ecx, ecx
    mov     eax, 1
    cpuid
    push   esi
    lea    esi, DWORD PTR _b$[esp+24]
    mov    DWORD PTR [esi], eax
    mov    DWORD PTR [esi+4], ebx
    mov    DWORD PTR [esi+8], ecx
    mov    DWORD PTR [esi+12], edx

    mov    esi, DWORD PTR _b$[esp+24]
    mov    eax, esi
    and    eax, 15
    push  eax
    push  OFFSET $SG15435 ; 'stepping=%d', 0aH, 00H
    call  _printf

    mov    ecx, esi
    shr    ecx, 4
    and    ecx, 15
    push  ecx
    push  OFFSET $SG15436 ; 'model=%d', 0aH, 00H
    call  _printf

    mov    edx, esi
    shr    edx, 8
    and    edx, 15
    push  edx
    push  OFFSET $SG15437 ; 'family_id=%d', 0aH, 00H
    call  _printf

    mov    eax, esi
    shr    eax, 12
    and    eax, 3
    push  eax
    push  OFFSET $SG15438 ; 'processor_type=%d', 0aH, 00H
    call  _printf

    mov    ecx, esi
    shr    ecx, 16
    and    ecx, 15
    push  ecx
    push  OFFSET $SG15439 ; 'extended_model_id=%d', 0aH, 00H
    call  _printf

    shr    esi, 20
    and    esi, 255
    push  esi
    push  OFFSET $SG15440 ; 'extended_family_id=%d', 0aH, 00H
    call  _printf
    add    esp, 48
    pop   esi

    xor    eax, eax
    pop   ebx

    add    esp, 16
    ret   0
_main ENDP

```

The SHR instruction shifting the value in EAX by the number of bits that must be *skipped*, e.g., we ignore some bits *at the right side*.

The AND instruction clears the unneeded bits *on the left*, or, in other words, leaves only those bits in the EAX register we need.

## Chapter 20

# 64-bit values in 32-bit environment

### 20.1 Returning of 64-bit value

```
#include <stdint.h>

uint64_t f ()
{
    return 0x1234567890ABCDEF;
};
```

#### 20.1.1 x86

In a 32-bit environment, 64-bit values are returned from functions in the EDX:EAX register pair.

Listing 20.1: Optimizing MSVC 2010

```
_f    PROC
      mov     eax, -1867788817      ; 90abcdefH
      mov     edx, 305419896       ; 12345678H
      ret     0
_f    ENDP
```

### 20.2 Arguments passing, addition, subtraction

```
#include <stdint.h>

uint64_t f_add (uint64_t a, uint64_t b)
{
    return a+b;
};

void f_add_test ()
{
#ifdef __GNUC__
    printf ("%lld\n", f_add(12345678901234, 23456789012345));
#else
    printf ("%I64d\n", f_add(12345678901234, 23456789012345));
#endif
};

uint64_t f_sub (uint64_t a, uint64_t b)
{
    return a-b;
};
```

**20.2.1 x86**

Listing 20.2: Optimizing MSVC 2012 /Ob1

```

_a$ = 8      ; size = 8
_b$ = 16     ; size = 8
_f_add PROC
    mov     eax, DWORD PTR _a$[esp-4]
    add     eax, DWORD PTR _b$[esp-4]
    mov     edx, DWORD PTR _a$[esp]
    adc     edx, DWORD PTR _b$[esp]
    ret     0
_f_add ENDP

_f_add_test PROC
    push   5461          ; 00001555H
    push   1972608889   ; 75939f79H
    push   2874         ; 00000b3aH
    push   1942892530   ; 73ce2ff_subH
    call   _f_add
    push   edx
    push   eax
    push   OFFSET $SG1436 ; '%I64d', 0aH, 00H
    call   _printf
    add    esp, 28
    ret    0
_f_add_test ENDP

_f_sub PROC
    mov     eax, DWORD PTR _a$[esp-4]
    sub     eax, DWORD PTR _b$[esp-4]
    mov     edx, DWORD PTR _a$[esp]
    sbb    edx, DWORD PTR _b$[esp]
    ret     0
_f_sub ENDP

```

We can see in the `f_add_test()` function that each 64-bit value is passed using two 32-bit values, high part first, then low part.

Addition and subtraction occur in pairs as well.

In addition, the low 32-bit part are added first. If carry was occurred while adding, the CF flag is set. The following ADC instruction adds the high parts of the values, and also adds 1 if  $CF = 1$ .

Subtraction also occurs in pairs. The first SUB may also turn on the CF flag, which is to be checked in the subsequent SBB instruction: if the carry flag is on, then 1 is also to be subtracted from the result.

It is easy to see how the `f_add()` function result is then passed to `printf()`.

**20.3 Multiplication, division**

```

#include <stdint.h>

uint64_t f_mul (uint64_t a, uint64_t b)
{
    return a*b;
};

uint64_t f_div (uint64_t a, uint64_t b)
{
    return a/b;
};

uint64_t f_rem (uint64_t a, uint64_t b)
{
    return a % b;
};

```

};

### 20.3.1 x86

Listing 20.3: Optimizing MSVC 2013 /Ob1

```

_a$ = 8 ; size = 8
_b$ = 16 ; size = 8
_f_mul PROC
    push    ebp
    mov     ebp, esp
    mov     eax, DWORD PTR _b$[ebp+4]
    push    eax
    mov     ecx, DWORD PTR _b$[ebp]
    push    ecx
    mov     edx, DWORD PTR _a$[ebp+4]
    push    edx
    mov     eax, DWORD PTR _a$[ebp]
    push    eax
    call    __allmul ; long long multiplication
    pop     ebp
    ret     0
_f_mul ENDP

_a$ = 8 ; size = 8
_b$ = 16 ; size = 8
_f_div PROC
    push    ebp
    mov     ebp, esp
    mov     eax, DWORD PTR _b$[ebp+4]
    push    eax
    mov     ecx, DWORD PTR _b$[ebp]
    push    ecx
    mov     edx, DWORD PTR _a$[ebp+4]
    push    edx
    mov     eax, DWORD PTR _a$[ebp]
    push    eax
    call    __aulldiv ; unsigned long long division
    pop     ebp
    ret     0
_f_div ENDP

_a$ = 8 ; size = 8
_b$ = 16 ; size = 8
_f_rem PROC
    push    ebp
    mov     ebp, esp
    mov     eax, DWORD PTR _b$[ebp+4]
    push    eax
    mov     ecx, DWORD PTR _b$[ebp]
    push    ecx
    mov     edx, DWORD PTR _a$[ebp+4]
    push    edx
    mov     eax, DWORD PTR _a$[ebp]
    push    eax
    call    __aullrem ; unsigned long long remainder
    pop     ebp
    ret     0
_f_rem ENDP

```

Multiplication and division are more complex operations, so usually the compiler embeds calls to a library functions doing that.

## 20.4 Shifting right

```
#include <stdint.h>

uint64_t f (uint64_t a)
{
    return a>>7;
};
```

### 20.4.1 x86

Listing 20.4: Optimizing MSVC 2012 /Ob1

```
_a$ = 8      ; size = 8
_f          PROC
            mov     eax, DWORD PTR _a$[esp-4]
            mov     edx, DWORD PTR _a$[esp]
            shrd   eax, edx, 7
            shr    edx, 7
            ret    0
_f          ENDP
```

Shifting also occurs in two passes: first the lower part is shifted, then the higher part. But the lower part is shifted with the help of the SHRD instruction, it shifts the value of EDX by 7 bits, but pulls new bits from EAX, i.e., from the higher part. The higher part is shifted using the more popular SHR instruction: indeed, the freed bits in the higher part must be filled with zeroes.

## 20.5 Converting 32-bit value into 64-bit one

```
#include <stdint.h>

int64_t f (int32_t a)
{
    return a;
};
```

### 20.5.1 x86

Listing 20.5: Optimizing MSVC 2012

```
_a$ = 8
_f          PROC
            mov     eax, DWORD PTR _a$[esp-4]
            cdq
            ret    0
_f          ENDP
```

Here we also run into necessity to extend a 32-bit signed value into a 64-bit signed one. Unsigned values are converted straightforwardly: all bits in the higher part must be set to 0. But this is not appropriate for signed data types: the sign has to be copied into the higher part of the resulting number. The CDQ instruction does that here, it takes its input value in EAX, extends it to 64-bit and leaves it in the EDX:EAX register pair. In other words, CDQ gets the number sign from EAX (by getting the most significant bit in EAX), and depending of it, sets all 32 bits in EDX to 0 or 1. Its operation is somewhat similar to the MOVSBX instruction.

# Chapter 21

## 64 bits

### 21.1 x86-64

It is a 64-bit extension to the x86 architecture.

From the reverse engineer's perspective, the most important changes are:

- Almost all registers (except FPU and SIMD) were extended to 64 bits and got a R- prefix. 8 additional registers were added. Now **GPR's** are: RAX, RBX, RCX, RDX, RBP, RSP, RSI, RDI, R8, R9, R10, R11, R12, R13, R14, R15.

It is still possible to access the *older* register parts as usual. For example, it is possible to access the lower 32-bit part of the RAX register using EAX:

7th (byte number)	6th	5th	4th	3rd	2nd	1st	0th
RAX <sup>x64</sup>							
						EAX	
						AX	
						AH	AL

The new R8-R15 registers also have their *lower parts*: R8D-R15D (lower 32-bit parts), R8W-R15W (lower 16-bit parts), R8L-R15L (lower 8-bit parts).

7th (byte number)	6th	5th	4th	3rd	2nd	1st	0th
R8							
						R8D	
						R8W	
						R8L	

The number of SIMD registers was doubled from 8 to 16: XMM0-XMM15.

- In Win64, the function calling convention is slightly different, somewhat resembling `fastcall`. The first 4 arguments are stored in the RCX, RDX, R8, R9 registers, the rest –in the stack. The **caller** function must also allocate 32 bytes so the **callee** may save there 4 first arguments and use these registers for its own needs. Short functions may use arguments just from registers, but larger ones may save their values on the stack.

System V AMD64 ABI (Linux, \*BSD, Mac OS X)[[Mit13](#)] also somewhat resembles `fastcall`, it uses 6 registers RDI, RSI, RDX, RCX, R8, R9 for the first 6 arguments. All the rest are passed via the stack.

- The C/C++ *int* type is still 32-bit for compatibility.
- All pointers are 64-bit now.

This provokes irritation sometimes: now one needs twice as much memory for storing pointers, including cache memory, despite the fact that x64 CPUs can address only 48 bits of external [RAM](#)<sup>1</sup>.

Since now the number of registers is doubled, the compilers have more space for maneuvering called **register allocation**. For us this implies that the emitted code containing less number of local variables.

By the way, there are CPUs with much more **GPR's**, e.g. Itanium (128 registers).

<sup>1</sup>Random-access memory

## **Part II**

# **Important fundamentals**



## Chapter 22

# Signed number representations

There are several methods for representing signed numbers<sup>1</sup>, but “two’s complement” is the most popular one in computers. Here is a table for some byte values:

binary	hexadecimal	unsigned	signed (2’s complement)
01111111	0x7f	127	127
01111110	0x7e	126	126
...			
00000110	0x6	6	6
00000101	0x5	5	5
00000100	0x4	4	4
00000011	0x3	3	3
00000010	0x2	2	2
00000001	0x1	1	1
00000000	0x0	0	0
11111111	0xff	255	-1
11111110	0xfe	254	-2
11111101	0xfd	253	-3
11111100	0xfc	252	-4
11111011	0xfb	251	-5
11111010	0xfa	250	-6
...			
10000010	0x82	130	-126
10000001	0x81	129	-127
10000000	0x80	128	-128

The difference between signed and unsigned numbers is that if we represent 0xFFFFFFFF and 0x00000002 as unsigned, then the first number (4294967294) is bigger than the second one (2). If we represent them both as signed, the first one is to be -2, and it is smaller than the second (2). That is the reason why conditional jumps ( [11 on page 34](#)) are present both for signed (e.g. JG, JL) and unsigned (JA, JB) operations.

For the sake of simplicity, that is what one need to know:

- Numbers can be signed or unsigned.
- C/C++ signed types:
  - `int64_t` (-9,223,372,036,854,775,808..9,223,372,036,854,775,807) (- 9.2.. 9.2 quintillions) or 0x8000000000000000..0x7FFFFFFFFFFFFFFF),
  - `int` (-2,147,483,648..2,147,483,647 (- 2.15.. 2.15Gb) or 0x80000000..0x7FFFFFFF),
  - `char` (-128..127 or 0x80..0x7F),
  - `ssize_t`.

Unsigned:

- `uint64_t` (0..18,446,744,073,709,551,615 ( 18 quintillions) or 0..0xFFFFFFFFFFFFFFFF),
- `unsigned int` (0..4,294,967,295 ( 4.3Gb) or 0..0xFFFFFFFF),
- `unsigned char` (0..255 or 0..0xFF),

<sup>1</sup>wikipedia

---

- `size_t`.

- Signed types have the sign in the most significant bit: 1 mean “minus”, 0 mean “plus”.
- Promoting to a larger data types is simple: [20.5 on page 101](#).
- Negation is simple: just invert all bits and add 1. We can remember that a number of inverse sign is located on the opposite side at the same proximity from zero. The addition of one is needed because zero is present in the middle.
- The addition and subtraction operations work well for both signed and unsigned values. But for multiplication and division operations, x86 has different instructions: `IDIV/IMUL` for signed and `DIV/MUL` for unsigned.

## Chapter 23

# Memory

There are 3 main types of memory:

- Global memory. AKA “static memory allocation”. No need to allocate explicitly, the allocation is done just by declaring variables/arrays globally. These are global variables, residing in the data or constant segments. They are available globally (hence, considered as an [anti-pattern](#)). Not convenient for buffers/arrays, because they must have a fixed size. Buffer overflows that occur here usually overwrite variables or buffers reside next to them in memory. There’s an example in this book: [7.2 on page 19](#).
- Stack. AKA “allocate on stack”. The allocation is done just by declaring variables/arrays locally in the function. These are usually local variables for the function. Sometimes these local variables are also available to descending functions (to [callee](#) functions, if caller passes a pointer to a variable to the [callee](#) to be executed). Allocation and deallocation are very fast, it’s just [SP](#) needs to be shifted. But they’re also not convenient for buffers/arrays, because the buffer size has to be fixed, unless `alloca()` ([5.2.4 on page 11](#)) (or a variable-length array) is used. Buffer overflows usually overwrite important stack structures: [16.2 on page 63](#).
- Heap. AKA “dynamic memory allocation”. Allocation is done by calling `malloc()/free()` or `new/delete` in C++. This is the most convenient method: the block size may be set at runtime. Resizing is possible (using `realloc()`), but can be slow. This is the slowest way to allocate memory: the memory allocator must support and update all control structures while allocating and deallocating. Buffer overflows usually overwrite these structures. Heap allocations are also source of memory leak problems: each memory block has to be deallocated explicitly, but one may forget about it, or do it incorrectly. Another problem is the “use after free”—using a memory block after `free()` was called on it, which is very dangerous. Example in this book: [19.2 on page 88](#).

## **Part III**

# **Finding important/interesting stuff in the code**

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Minimalism it is not a prominent feature of modern software.

But not because the programmers are writing a lot, but because a lot of libraries are commonly linked statically to executable files. If all external libraries were shifted into an external DLL files, the world would be different. (Another reason for C++ are the STL and other template libraries.)

Thus, it is very important to determine the origin of a function, if it is from standard library or well-known library (like Boost<sup>1</sup>, libpng<sup>2</sup>), or if it is related to what we are trying to find in the code.

It is just absurd to rewrite all code in C/C++ to find what we're looking for.

One of the primary tasks of a reverse engineer is to find quickly the code he/she needs.

The IDA disassembler allow us to search among text strings, byte sequences and constants. It is even possible to export the code to .lst or .asm text files and then use `grep`, `awk`, etc.

When you try to understand what some code is doing, this easily could be some open-source library like libpng. So when you see some constants or text strings which look familiar, it is always worth to *google* them. And if you find the opensource project where they are used, then it's enough just to compare the functions. It may solve some part of the problem.

For example, if a program uses XML files, the first step may be determining which XML library is used for processing, since the standard (or well-known) libraries are usually used instead of self-made one.

For example, author of these lines once tried to understand how the compression/decompression of network packets worked in SAP 6.0. It is a huge software, but a detailed .PDB with debugging information is present, and that is convenient. He finally came to the idea that one of the functions, that was called CsDecomprLZC, was doing the decompression of network packets. Immediately he tried to google its name and he quickly found the function was used in MaxDB (it is an open-source SAP project) .

<http://www.google.com/search?q=CsDecomprLZC>

Astoundingly, MaxDB and SAP 6.0 software shared likewise code for the compression/decompression of network packets.

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<sup>1</sup><http://go.yurichev.com/17036>

<sup>2</sup><http://go.yurichev.com/17037>

## Chapter 24

# Communication with the outer world (win32)

Sometimes it's enough to observe some function's inputs and outputs in order to understand what it does. That way you can save time.

Files and registry access: for the very basic analysis, Process Monitor<sup>1</sup> utility from SysInternals can help.

For the basic analysis of network accesses, Wireshark<sup>2</sup> can be useful.

But then you will have to look inside anyway.

The first thing to look for is which functions from the OS's API<sup>3</sup>s and standard libraries are used.

If the program is divided into a main executable file and a group of DLL files, sometimes the names of the functions in these DLLs can help.

If we are interested in exactly what can lead to a call to `MessageBox()` with specific text, we can try to find this text in the data segment, find the references to it and find the points from which the control may be passed to the `MessageBox()` call we're interested in.

If we are talking about a video game and we're interested in which events are more or less random in it, we may try to find the `rand()` function or its replacements (like the Mersenne twister algorithm) and find the places from which those functions are called, and more importantly, how are the results used.

But if it is not a game, and `rand()` is still used, it is also interesting to know why. There are cases of unexpected `rand()` usage in data compression algorithms (for encryption imitation): [blog.yurichev.com](http://blog.yurichev.com).

## 24.1 Often used functions in the Windows API

These functions may be among the imported. It is worth to note that not every function might be used in the code that was written by the programmer. A lot of functions might be called from library functions and CRT code.

- Registry access (advapi32.dll): `RegEnumKeyEx`<sup>4 5</sup>, `RegEnumValue`<sup>6 5</sup>, `RegGetValue`<sup>7 5</sup>, `RegOpenKeyEx`<sup>8 5</sup>, `RegQueryValueEx`<sup>9 5</sup>.
- Access to text .ini-files (kernel32.dll): `GetPrivateProfileString`<sup>10 5</sup>.
- Dialog boxes (user32.dll): `MessageBox`<sup>11 5</sup>, `MessageBoxEx`<sup>12 5</sup>, `SetDlgItemText`<sup>13 5</sup>, `GetDlgItemText`<sup>14 5</sup>.
- Resources access : (user32.dll): `LoadMenu`<sup>15 5</sup>.

<sup>1</sup><http://go.yurichev.com/17301>

<sup>2</sup><http://go.yurichev.com/17303>

<sup>3</sup>Application programming interface

<sup>4</sup>MSDN

<sup>5</sup>May have the -A suffix for the ASCII version and -W for the Unicode version

<sup>6</sup>MSDN

<sup>7</sup>MSDN

<sup>8</sup>MSDN

<sup>9</sup>MSDN

<sup>10</sup>MSDN

<sup>11</sup>MSDN

<sup>12</sup>MSDN

<sup>13</sup>MSDN

<sup>14</sup>MSDN

<sup>15</sup>MSDN

- TCP/IP networking (ws2\_32.dll): WSARcv<sup>16</sup>, WSARecv<sup>17</sup>.
- File access (kernel32.dll): CreateFile<sup>18</sup>, ReadFile<sup>19</sup>, ReadFileEx<sup>20</sup>, WriteFile<sup>21</sup>, WriteFileEx<sup>22</sup>.
- High-level access to the Internet (wininet.dll): WinHttpOpen<sup>23</sup>.
- Checking the digital signature of an executable file (wintrust.dll): WinVerifyTrust<sup>24</sup>.
- The standard MSVC library (if it's linked dynamically) (msvcrt.dll): assert, itoa, ltoa, open, printf, read, strcmp, atol, atoi, fopen, fread, fwrite, memcmp, rand, strlen, strstr, strchr.

## 24.2 tracer: Intercepting all functions in specific module

There are INT3 breakpoints in the `tracer`, that are triggered only once, however, they can be set for all functions in a specific DLL.

```
--one-time-INT3-bp:somedll.dll!.*
```

Or, let's set INT3 breakpoints on all functions with the `xml` prefix in their name:

```
--one-time-INT3-bp:somedll.dll!xml.*
```

On the other side of the coin, such breakpoints are triggered only once.

Tracer will show the call of a function, if it happens, but only once. Another drawback—it is impossible to see the function's arguments.

Nevertheless, this feature is very useful when you know that the program uses a DLL, but you do not know which functions are actually used. And there are a lot of functions.

For example, let's see, what does the `uptime` utility from `cygwin` use:

```
tracer -l:uptime.exe --one-time-INT3-bp:cygwin1.dll!.*
```

Thus we may see all that `cygwin1.dll` library functions that were called at least once, and where from:

```
One-time INT3 breakpoint: cygwin1.dll!__main (called from uptime.exe!OEP+0x6d (0x40106d))
One-time INT3 breakpoint: cygwin1.dll!_geteuid32 (called from uptime.exe!OEP+0xba3 (0x401ba3))
One-time INT3 breakpoint: cygwin1.dll!_getuid32 (called from uptime.exe!OEP+0xbaa (0x401baa))
One-time INT3 breakpoint: cygwin1.dll!_getegid32 (called from uptime.exe!OEP+0xcb7 (0x401cb7))
One-time INT3 breakpoint: cygwin1.dll!_getgid32 (called from uptime.exe!OEP+0xcbe (0x401cbe))
One-time INT3 breakpoint: cygwin1.dll!_sysconf (called from uptime.exe!OEP+0x735 (0x401735))
One-time INT3 breakpoint: cygwin1.dll!_setlocale (called from uptime.exe!OEP+0x7b2 (0x4017b2))
One-time INT3 breakpoint: cygwin1.dll!_open64 (called from uptime.exe!OEP+0x994 (0x401994))
One-time INT3 breakpoint: cygwin1.dll!_lseek64 (called from uptime.exe!OEP+0x7ea (0x4017ea))
One-time INT3 breakpoint: cygwin1.dll!read (called from uptime.exe!OEP+0x809 (0x401809))
One-time INT3 breakpoint: cygwin1.dll!_sscanf (called from uptime.exe!OEP+0x839 (0x401839))
One-time INT3 breakpoint: cygwin1.dll!uname (called from uptime.exe!OEP+0x139 (0x401139))
One-time INT3 breakpoint: cygwin1.dll!time (called from uptime.exe!OEP+0x22e (0x40122e))
One-time INT3 breakpoint: cygwin1.dll!localtime (called from uptime.exe!OEP+0x236 (0x401236))
One-time INT3 breakpoint: cygwin1.dll!sprintf (called from uptime.exe!OEP+0x25a (0x40125a))
One-time INT3 breakpoint: cygwin1.dll!setutent (called from uptime.exe!OEP+0x3b1 (0x4013b1))
One-time INT3 breakpoint: cygwin1.dll!getutent (called from uptime.exe!OEP+0x3c5 (0x4013c5))
One-time INT3 breakpoint: cygwin1.dll!endutent (called from uptime.exe!OEP+0x3e6 (0x4013e6))
One-time INT3 breakpoint: cygwin1.dll!puts (called from uptime.exe!OEP+0x4c3 (0x4014c3))
```

<sup>16</sup>MSDN

<sup>17</sup>MSDN

<sup>18</sup>MSDN

<sup>19</sup>MSDN

<sup>20</sup>MSDN

<sup>21</sup>MSDN

<sup>22</sup>MSDN

<sup>23</sup>MSDN

<sup>24</sup>MSDN

# Chapter 25

## Strings

### 25.1 Text strings

#### 25.1.1 C/C++

The normal C strings are zero-terminated (ASCIIZ-strings).

The reason why the C string format is as it is (zero-terminated) is apparently historical. In [Rit79] we read:

A minor difference was that the unit of I/O was the word, not the byte, because the PDP-7 was a word-addressed machine. In practice this meant merely that all programs dealing with character streams ignored null characters, because null was used to pad a file to an even number of characters.

In Hiew or FAR Manager these strings looks like this:

```
int main()
{
    printf ("Hello, world!\n");
};
```

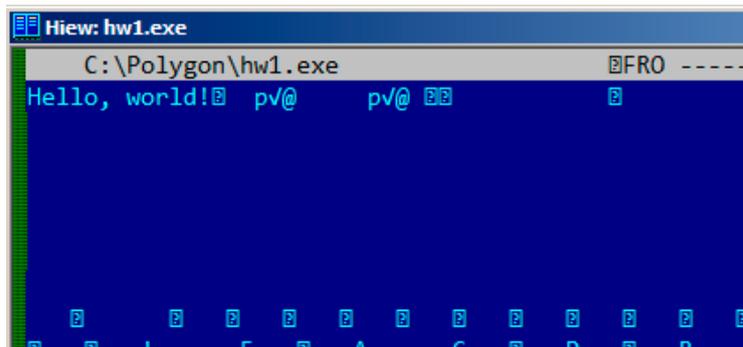


Figure 25.1: Hiew

#### 25.1.2 Borland Delphi

The string in Pascal and Borland Delphi is preceded by an 8-bit or 32-bit string length.

For example:

Listing 25.1: Delphi

```
CODE:00518AC8          dd 19h
CODE:00518ACC aLoading__Plea db 'Loading... , please wait.',0
...
CODE:00518AFC          dd 10h
CODE:00518B00 aPreparingRun__ db 'Preparing run... ',0
```

### 25.1.3 Unicode

Often, what is called Unicode is a methods for encoding strings where each character occupies 2 bytes or 16 bits. This is a common terminological mistake. Unicode is a standard for assigning a number to each character in the many writing systems of the world, but does not describe the encoding method.

The most popular encoding methods are: UTF-8 (is widespread in Internet and \*NIX systems) and UTF-16LE (is used in Windows).

#### UTF-8

UTF-8 is one of the most successful methods for encoding characters. All Latin symbols are encoded just like in ASCII, and the symbols beyond the ASCII table are encoded using several bytes. 0 is encoded as before, so all standard C string functions work with UTF-8 strings just like any other string.

Let's see how the symbols in various languages are encoded in UTF-8 and how it looks like in FAR, using the 437 codepage <sup>1</sup>:

```
How much? 100€?

(English) I can eat glass and it doesn't hurt me.
(Greek) Μπορώ να φάω σπασμένα γυαλιά χωρίς να πάθω τίποτα.
(Hungarian) Meg tudom enni az üveget, nem lesz tőle bajom.
(Icelandic) Ég get etið gler án þess að meiða mig.
(Polish) Mogę jeść szkło i mi nie szkodzi.
(Russian) Я могу есть стекло, оно мне не вредит.
(Arabic): أنا قادر على أكل الزجاج و هذا لا يؤلمني.
(Hebrew): אני יכול לאכול זכוכית וזה לא מזיק לי.
(Chinese) 我能吞下玻璃而不伤身体。
(Japanese) 私はガラスを食べられます。それは私を傷つけません。
(Hindi) मैं काँच खा सकता हूँ और मुझे उससे कोई चोट नहीं पहुंचती.
```

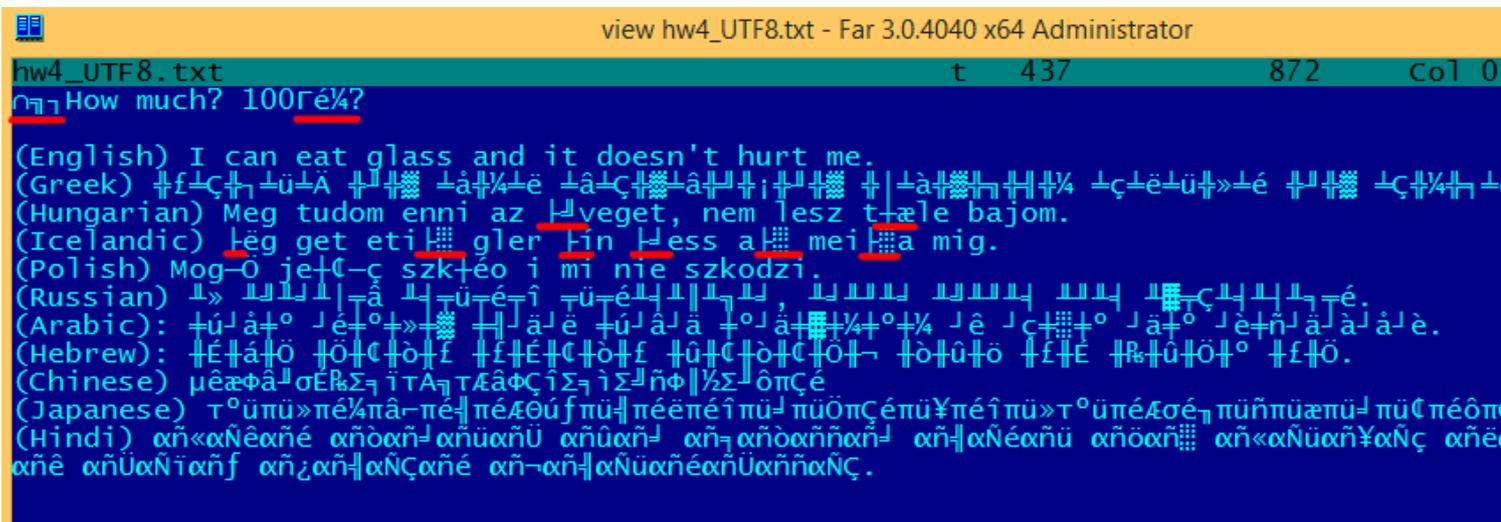


Figure 25.2: FAR: UTF-8

As you can see, the English language string looks the same as it is in ASCII. The Hungarian language uses some Latin symbols plus symbols with diacritic marks. These symbols are encoded using several bytes, these are underscored with red. It's the same story with the Icelandic and Polish languages. There is also the “Euro” currency symbol at the start, which is encoded with 3 bytes. The rest of the writing systems here have no connection with Latin. At least in Russian, Arabic, Hebrew and Hindi we can see some recurring bytes, and that is not surprise: all symbols from a writing system are usually located in the same Unicode table, so their code begins with the same numbers.

At the beginning, before the “How much?” string we see 3 bytes, which are in fact the BOM<sup>2</sup>. The BOM defines the encoding system to be used.

<sup>1</sup>The example and translations was taken from here: <http://go.yurichev.com/17304>

<sup>2</sup>Byte order mark

**UTF-16LE**

Many win32 functions in Windows have the suffixes `-A` and `-W`. The first type of functions works with normal strings, the other with UTF-16LE strings (*wide*). In the second case, each symbol is usually stored in a 16-bit value of type *short*.

The Latin symbols in UTF-16 strings look in Hiew or FAR like they are interleaved with zero byte:

```
int wmain()
{
    wprintf (L"Hello, world!\n");
};
```

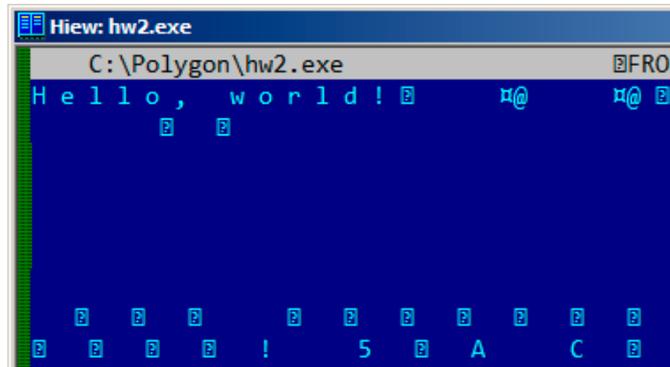


Figure 25.3: Hiew

We can see this often in [Windows NT](#) system files:

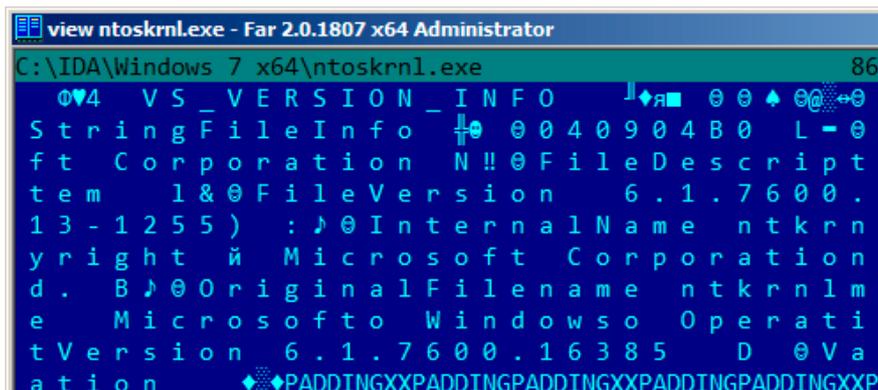


Figure 25.4: Hiew

Strings with characters that occupy exactly 2 bytes are called “Unicode” in [IDA](#):

```
.data:0040E000 aHelloWorld:
.data:0040E000          unicode 0, <Hello, world!>
.data:0040E000          dw 0Ah, 0
```

Here is how the Russian language string is encoded in UTF-16LE:

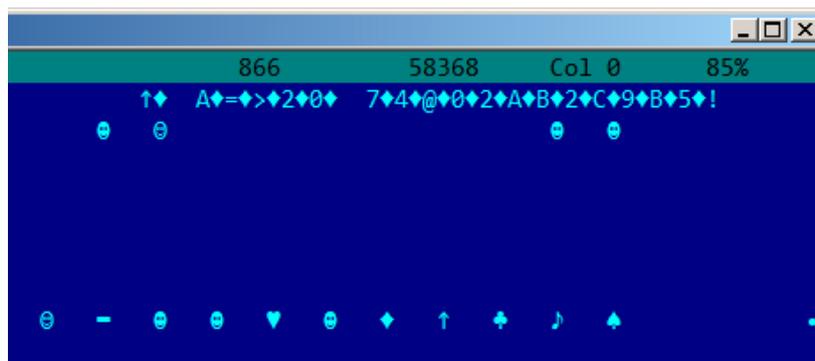


Figure 25.5: Hiew: UTF-16LE



## 25.2 Error/debug messages

Debugging messages are very helpful if present. In some sense, the debugging messages are reporting what's going on in the program right now. Often these are `printf()`-like functions, which write to log-files, or sometimes do not writing anything but the calls are still present since the build is not a debug one but *release* one. If local or global variables are dumped in debug messages, it might be helpful as well since it is possible to get at least the variable names. For example, one of such function in Oracle RDBMS is `ksdwrt()`.

Meaningful text strings are often helpful. The [IDA](#) disassembler may show from which function and from which point this specific string is used. Funny cases sometimes happen<sup>4</sup>.

The error messages may help us as well. In Oracle RDBMS, errors are reported using a group of functions. You can read more about them here: [blog.yurichev.com](http://blog.yurichev.com).

It is possible to find quickly which functions report errors and in which conditions. By the way, this is often the reason for copy-protection systems to inarticulate cryptic error messages or just error numbers. No one is happy when the software cracker quickly understand why the copy-protection is triggered just by the error message.

## 25.3 Suspicious magic strings

Some magic strings which are usually used in backdoors looks pretty suspicious. For example, there was a backdoor in the TP-Link WR740 home router<sup>5</sup>. The backdoor was activated using the following URL:

[http://192.168.0.1/userRpmNatDebugRpm26525557/start\\_art.html](http://192.168.0.1/userRpmNatDebugRpm26525557/start_art.html).

Indeed, the "userRpmNatDebugRpm26525557" string is present in the firmware. This string was not googleable until the wide disclosure of information about the backdoor. You would not find this in any [RFC](#)<sup>6</sup>. You would not find any computer science algorithm which uses such strange byte sequences. And it doesn't look like an error or debugging message. So it's a good idea to inspect the usage of such weird strings.

Sometimes, such strings are encoded using base64. So it's a good idea to decode them all and to scan them visually, even a glance should be enough.

More precise, this method of hiding backdoors is called "security through obscurity".

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<sup>4</sup>[blog.yurichev.com](http://blog.yurichev.com)

<sup>5</sup><http://sekurak.pl/tp-link-httpftp-backdoor/>

<sup>6</sup>Request for Comments

## Chapter 26

# Calls to assert()

Sometimes the presence of the `assert()` macro is useful too: commonly this macro leaves source file name, line number and condition in the code.

The most useful information is contained in the `assert`'s condition, we can deduce variable names or structure field names from it. Another useful piece of information are the file names—we can try to deduce what type of code is there. Also it is possible to recognize well-known open-source libraries by the file names.

Listing 26.1: Example of informative `assert()` calls

```
.text:107D4B29 mov dx, [ecx+42h]
.text:107D4B2D cmp edx, 1
.text:107D4B30 jz short loc_107D4B4A
.text:107D4B32 push 1ECh
.text:107D4B37 push offset aWrite_c ; "write.c"
.text:107D4B3C push offset aTdTd_planarcon ; "td->td_planarconfig == PLANARCONFIG_CON"...
.text:107D4B41 call ds:_assert

...

.text:107D52CA mov edx, [ebp-4]
.text:107D52CD and edx, 3
.text:107D52D0 test edx, edx
.text:107D52D2 jz short loc_107D52E9
.text:107D52D4 push 58h
.text:107D52D6 push offset aDumpmode_c ; "dumpmode.c"
.text:107D52DB push offset aN30 ; "(n & 3) == 0"
.text:107D52E0 call ds:_assert

...

.text:107D6759 mov cx, [eax+6]
.text:107D675D cmp ecx, 0Ch
.text:107D6760 jle short loc_107D677A
.text:107D6762 push 2D8h
.text:107D6767 push offset aLzw_c ; "lzw.c"
.text:107D676C push offset aSpLzw_nbitsBit ; "sp->lzw_nbits <= BITS_MAX"
.text:107D6771 call ds:_assert
```

It is advisable to “google” both the conditions and file names, which can lead us to an open-source library. For example, if we “google” “`sp->lzw_nbits <= BITS_MAX`”, this predictably gives us some open-source code that’s related to the LZW compression.

## Chapter 27

# Constants

Humans, including programmers, often use round numbers like 10, 100, 1000, in real life as well as in the code.

The practicing reverse engineer usually know them well in hexadecimal representation: 10=0xA, 100=0x64, 1000=0x3E8, 10000=0x2710.

The constants 0xAAAAAAAA (10101010101010101010101010101010) and 0x55555555 (01010101010101010101010101010101) are also popular—those are composed of alternating bits. That may help to distinguish some signal from the signal where all bits are turned on (1111 ...) or off (0000 ...). For example, the 0x55AA constant is used at least in the boot sector, [MBR](#)<sup>1</sup>, and in the [ROM](#)<sup>2</sup> of IBM-compatible extension cards.

Some algorithms, especially cryptographical ones use distinct constants, which are easy to find in code using [IDA](#).

For example, the MD5<sup>3</sup> algorithm initializes its own internal variables like this:

```
var int h0 := 0x67452301
var int h1 := 0xEFCDAB89
var int h2 := 0x98BADCFE
var int h3 := 0x10325476
```

If you find these four constants used in the code in a row, it is very highly probable that this function is related to MD5.

Another example are the CRC16/CRC32 algorithms, whose calculation algorithms often use precomputed tables like this one:

Listing 27.1: linux/lib/crc16.c

```
/** CRC table for the CRC-16. The poly is 0x8005 (x^16 + x^15 + x^2 + 1) */
u16 const crc16_table[256] = {
    0x0000, 0xC0C1, 0xC181, 0x0140, 0xC301, 0x03C0, 0x0280, 0xC241,
    0xC601, 0x06C0, 0x0780, 0xC741, 0x0500, 0xC5C1, 0xC481, 0x0440,
    0xCC01, 0x0CC0, 0x0D80, 0xCD41, 0x0F00, 0xCFC1, 0xCE81, 0x0E40,
    ...
}
```

### 27.1 Magic numbers

A lot of file formats define a standard file header where a *magic number(s)*<sup>4</sup> is used, single one or even several.

For example, all Win32 and MS-DOS executables start with the two characters “MZ”<sup>5</sup>.

At the beginning of a MIDI file the “MThd” signature must be present. If we have a program which uses MIDI files for something, it’s very likely that it must check the file for validity by checking at least the first 4 bytes.

This could be done like this:

(*buf* points to the beginning of the loaded file in memory)

```
cmp [buf], 0x6468544D ; "MThd"
jnz _error_not_a_MIDI_file
```

<sup>1</sup>Master Boot Record

<sup>2</sup>Read-only memory

<sup>3</sup>[wikipedia](#)

<sup>4</sup>[wikipedia](#)

<sup>5</sup>[wikipedia](#)

...or by calling a function for comparing memory blocks like `memcmp()` or any other equivalent code up to a `CMPSB` instruction.

When you find such point you already can say where the loading of the MIDI file starts, also, we could see the location of the buffer with the contents of the MIDI file, what is used from the buffer, and how.

### 27.1.1 DHCP

This applies to network protocols as well. For example, the DHCP protocol's network packets contains the so-called *magic cookie*: `0x63538263`. Any code that generates DHCP packets somewhere must embed this constant into the packet. If we find it in the code we may find where this happens and, not only that. Any program which can receive DHCP packet must verify the *magic cookie*, comparing it with the constant.

For example, let's take the `dhcpcore.dll` file from Windows 7 x64 and search for the constant. And we can find it, twice: it seems that the constant is used in two functions with descriptive names like `DhcpExtractOptionsForValidation()` and `DhcpExtractFullOptions()`:

Listing 27.2: `dhcpcore.dll` (Windows 7 x64)

```
.rdata:000007FF6483CBE8 dword_7FF6483CBE8 dd 63538263h ; DATA XREF: ↗
↳ DhcpExtractOptionsForValidation+79
.rdata:000007FF6483CBEC dword_7FF6483CBEC dd 63538263h ; DATA XREF: ↗
↳ DhcpExtractFullOptions+97
```

And here are the places where these constants are accessed:

Listing 27.3: `dhcpcore.dll` (Windows 7 x64)

```
.text:000007FF6480875F mov     eax, [rsi]
.text:000007FF64808761 cmp     eax, cs:dword_7FF6483CBE8
.text:000007FF64808767 jnz    loc_7FF64817179
```

And:

Listing 27.4: `dhcpcore.dll` (Windows 7 x64)

```
.text:000007FF648082C7 mov     eax, [r12]
.text:000007FF648082CB cmp     eax, cs:dword_7FF6483CBEC
.text:000007FF648082D1 jnz    loc_7FF648173AF
```

## 27.2 Searching for constants

It is easy in [IDA](#): Alt-B or Alt-I. And for searching for a constant in a big pile of files, or for searching in non-executable files, there is a small utility called *binary grep*<sup>6</sup>.

<sup>6</sup>[GitHub](#)

## Chapter 28

# Finding the right instructions

If the program is utilizing FPU instructions and there are very few of them in the code, one can try to check each one manually with a debugger.

For example, we may be interested how Microsoft Excel calculates the formulae entered by user. For example, the division operation.

If we load excel.exe (from Office 2010) version 14.0.4756.1000 into [IDA](#), make a full listing and to find every FDIV instruction (except the ones which use constants as a second operand—obviously, they do not suit us):

```
cat EXCEL.lst | grep fdiv | grep -v dbl_ > EXCEL.fdiv
```

...then we see that there are 144 of them.

We can enter a string like  $= (1/3)$  in Excel and check each instruction.

By checking each instruction in a debugger or [tracer](#) (one may check 4 instruction at a time), we get lucky and the sought-for instruction is just the 14th:

```
.text:3011E919 DC 33                                fdiv    qword ptr [ebx]
```

```
PID=13944|TID=28744|(0) 0x2f64e919 (Excel.exe!BASE+0x11e919)
EAX=0x02088006 EBX=0x02088018 ECX=0x00000001 EDX=0x00000001
ESI=0x02088000 EDI=0x00544804 EBP=0x0274FA3C ESP=0x0274F9F8
EIP=0x2F64E919
FLAGS=PF IF
FPU ControlWord=IC RC=NEAR PC=64bits PM UM OM ZM DM IM
FPU StatusWord=
FPU ST(0): 1.000000
```

ST(0) holds the first argument (1) and second one is in [EBX].

The instruction after FDIV (FSTP) writes the result in memory:

```
.text:3011E91B DD 1E                                fstp    qword ptr [esi]
```

If we set a breakpoint on it, we can see the result:

```
PID=32852|TID=36488|(0) 0x2f40e91b (Excel.exe!BASE+0x11e91b)
EAX=0x00598006 EBX=0x00598018 ECX=0x00000001 EDX=0x00000001
ESI=0x00598000 EDI=0x00294804 EBP=0x026CF93C ESP=0x026CF8F8
EIP=0x2F40E91B
FLAGS=PF IF
FPU ControlWord=IC RC=NEAR PC=64bits PM UM OM ZM DM IM
FPU StatusWord=C1 P
FPU ST(0): 0.333333
```

Also as a practical joke, we can modify it on the fly:

```
tracer -l:excel.exe bpx=excel.exe!BASE+0x11E91B,set(st0,666)
```

```

PID=36540|TID=24056|(0) 0x2f40e91b (Excel.exe!BASE+0x11e91b)
EAX=0x00680006 EBX=0x00680018 ECX=0x00000001 EDX=0x00000001
ESI=0x00680000 EDI=0x00395404 EBP=0x0290FD9C ESP=0x0290FD58
EIP=0x2F40E91B
FLAGS=PF IF
FPU ControlWord=IC RC=NEAR PC=64bits PM UM OM ZM DM IM
FPU StatusWord=C1 P
FPU ST(0): 0.333333
Set ST0 register to 666.000000

```

Excel shows 666 in the cell, finally convincing us that we have found the right point.

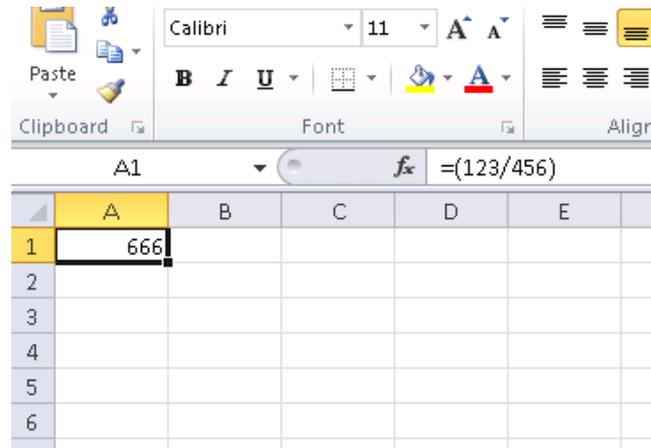


Figure 28.1: The practical joke worked

If we try the same Excel version, but in x64, we will find only 12 FDIV instructions there, and the one we looking for is the third one.

```
tracer.exe -l:excel.exe bpx=excel.exe!BASE+0x1B7FCC,set(st0,666)
```

It seems that a lot of division operations of *float* and *double* types, were replaced by the compiler with SSE instructions like DIVSD (DIVSD is present 268 times in total).

## Chapter 29

# Suspicious code patterns

### 29.1 XOR instructions

Instructions like `XOR op, op` (for example, `XOR EAX, EAX`) are usually used for setting the register value to zero, but if the operands are different, the “exclusive or” operation is executed. This operation is rare in common programming, but widespread in cryptography, including amateur one. It’s especially suspicious if the second operand is a big number. This may point to encrypting/decrypting, checksum computing, etc.

This AWK script can be used for processing [IDA](#) listing (.lst) files:

```
gawk -e '$2=="xor" { tmp=substr($3, 0, length($3)-1); if (tmp!=$4) if($4!="esp") if ($4!="ebp") ↵
  ↵ { print $1, $2, tmp, ",", $4 } }' filename.lst
```

### 29.2 Hand-written assembly code

Modern compilers do not emit the `LOOP` and `RCL` instructions. On the other hand, these instructions are well-known to coders who like to code directly in assembly language. If you spot these, it can be said that there is a high probability that this fragment of code was hand-written.

Also the function prologue/epilogue are not commonly present in hand-written assembly.

Commonly there is no fixed system for passing arguments to functions in the hand-written code.

Example from the Windows 2003 kernel (ntoskrnl.exe file):

```
MultiplyTest proc near ; CODE XREF: Get386Stepping
xor cx, cx
loc_620555: ; CODE XREF: MultiplyTest+E
push cx
call Multiply
pop cx
jb short locret_620563
loop loc_620555
clc
locret_620563: ; CODE XREF: MultiplyTest+C
retn
MultiplyTest endp

Multiply proc near ; CODE XREF: MultiplyTest+5
mov ecx, 81h
mov eax, 417A000h
mul ecx
cmp edx, 2
stc
jnz short locret_62057F
cmp eax, 0FE7A000h
stc
jnz short locret_62057F
clc
```

```
locret_62057F:                ; CODE XREF: Multiply+10  
                                ; Multiply+18  
Multiply      retn  
Multiply      endp
```

Indeed, if we look in the [WRK<sup>1</sup>](#) v1.2 source code, this code can be found easily in file *WRK-v1.2\base\ntos\ke\j386\cpu.asm*.

---

<sup>1</sup>Windows Research Kernel

## Chapter 30

# Using magic numbers while tracing

Often, our main goal is to understand how the program uses a value that was either read from file or received via network. The manual tracing of a value is often a very labour-intensive task. One of the simplest techniques for this (although not 100% reliable) is to use your own *magic number*.

This resembles X-ray computed tomography in some sense: a radiocontrast agent is injected into the patient's blood, which is then used to improve the visibility of the patient's internal structure in to the X-rays. It is well known how the blood of healthy humans percolates in the kidneys and if the agent is in the blood, it can be easily seen on tomography, how blood is percolating, and are there any stones or tumors.

We can take a 32-bit number like 0x0badf00d, or someone's birth date like 0x11101979 and write this 4-byte number to some point in a file used by the program we investigate.

Then, while tracing this program with `tracer` in *code coverage* mode, with the help of `grep` or just by searching in the text file (of tracing results), we can easily see where the value was used and how.

Example of *grepable* `tracer` results in `cc` mode:

```
0x150bf66 (_kziaia+0x14), e=      1 [MOV EBX, [EBP+8]] [EBP+8]=0xf59c934
0x150bf69 (_kziaia+0x17), e=      1 [MOV EDX, [69AEB08h]] [69AEB08h]=0
0x150bf6f (_kziaia+0x1d), e=      1 [FS: MOV EAX, [2Ch]]
0x150bf75 (_kziaia+0x23), e=      1 [MOV ECX, [EAX+EDX*4]] [EAX+EDX*4]=0xf1ac360
0x150bf78 (_kziaia+0x26), e=      1 [MOV [EBP-4], ECX] ECX=0xf1ac360
```

This can be used for network packets as well. It is important for the *magic number* to be unique and not to be present in the program's code.

Aside of the `tracer`, DosBox (MS-DOS emulator) in `heavydebug` mode is able to write information about all registers' states for each executed instruction of the program to a plain text file<sup>1</sup>, so this technique may be useful for DOS programs as well.

<sup>1</sup>See also my blog post about this DosBox feature: [blog.yurichev.com](http://blog.yurichev.com)

# Chapter 31

## Other things

### 31.1 General idea

A reverse engineer should try to be in programmer's shoes as often as possible. To take his/her viewpoint and ask himself, how would one solve some task the specific case.

### 31.2 Some binary file patterns

Sometimes, we can clearly spot an array of 16/32/64-bit values visually, in hex editor. Here is an example of very typical MIPS code. As we may remember, every MIPS (and also ARM in ARM mode or ARM64) instruction has size of 32 bits (or 4 bytes), so such code is array of 32-bit values. By looking at this screenshot, we may see some kind of pattern. Vertical red lines are added for clarity:



### 31.3.1 Windows registry

It is also possible to compare the Windows registry before and after a program installation. It is a very popular method of finding which registry elements are used by the program. Probably, this is the reason why the “windows registry cleaner” shareware is so popular.

### 31.3.2 Blink-comparator

Comparison of files or memory snapshots remind us blink-comparator<sup>2</sup>: a device used by astronomers in past, intended to find moving celestial objects. Blink-comparator allows to switch quickly between two photographs shot in different time, so astronomer would spot the difference visually. By the way, Pluto was discovered by blink-comparator in 1930.

---

<sup>2</sup><http://go.yurichev.com/17348>

## **Part IV**

# **Tools**

## Chapter 32

# Disassembler

### 32.1 IDA

An older freeware version is available for download <sup>1</sup>.

---

<sup>1</sup>[hex-rays.com/products/ida/support/download\\_freeware.shtml](http://hex-rays.com/products/ida/support/download_freeware.shtml)

## Chapter 33

# Debugger

### 33.1 tracer

The author often use *tracer*<sup>1</sup> instead of a debugger.

The author of these lines stopped using a debugger eventually, since all he need from it is to spot function arguments while executing, or registers state at some point. Loading a debugger each time is too much, so a small utility called *tracer* was born. It works from command line, allows intercepting function execution, setting breakpoints at arbitrary places, reading and changing registers state, etc.

However, for learning purposes it is highly advisable to trace code in a debugger manually, watch how the registers state changes (e.g. classic SoftICE, OllyDbg, WinDbg highlight changed registers), flags, data, change them manually, watch the reaction, etc.

---

<sup>1</sup>[yurichev.com](http://yurichev.com)

## Chapter 34

# Decompilers

There is only one known, publicly available, high-quality decompiler to C code: Hex-Rays:  
[hex-rays.com/products/decompiler/](http://hex-rays.com/products/decompiler/)

## Chapter 35

# Other tools

- Microsoft Visual Studio Express<sup>1</sup>: Stripped-down free version of Visual Studio, convenient for simple experiments.
- Hiew<sup>2</sup> for small modifications of code in binary files.
- binary grep: a small utility for searching any byte sequence in a big pile of files, including non-executable ones: [GitHub](#).

---

<sup>1</sup>[visualstudio.com/en-US/products/visual-studio-express-vs](https://visualstudio.com/en-US/products/visual-studio-express-vs)

<sup>2</sup>[hiew.ru](https://hiew.ru)

## **Part V**

# **Books/blogs worth reading**

# Chapter 36

## Books

### 36.1 Windows

[RA09].

### 36.2 C/C++

[ISO13].

### 36.3 x86 / x86-64

[Int13], [AMD13]

### 36.4 ARM

ARM manuals: <http://go.yurichev.com/17024>

### 36.5 Cryptography

[Sch94]

# Chapter 37

## Blogs

### 37.1 Windows

- [Microsoft: Raymond Chen](#)
- [nynaeve.net](#)

# Chapter 38

## Other

There are two excellent RE<sup>1</sup>-related subreddits on reddit.com: [reddit.com/r/ReverseEngineering/](https://reddit.com/r/ReverseEngineering/) and [reddit.com/r/remath](https://reddit.com/r/remath/) (on the topics for the intersection of RE and mathematics).

There is also a RE part of the Stack Exchange website: [reverseengineering.stackexchange.com](https://reverseengineering.stackexchange.com).

On IRC there a ##re channel on FreeNode<sup>2</sup>.

---

<sup>1</sup>Reverse Engineering

<sup>2</sup>[freenode.net](https://freenode.net)

# Afterword

## Chapter 39

# Questions?

Do not hesitate to mail any questions to the author: <dennis(a)yurichev.com>

Any suggestions what also should be added to my book?

Please, do not hesitate to send me any corrections (including grammar (you see how horrible my English is?)),etc.

The author is working on the book a lot, so the page and listing numbers, etc. are changing very rapidly. Please, do not refer to page and listing numbers in your emails to me. There is a much simpler method: make a screenshot of the page, in a graphics editor underline the place where you see the error, and send it to me. He'll fix it much faster. And if you familiar with git and  $\LaTeX$  you can fix the error right in the source code:

[GitHub](#).

Do not worry to bother me while writing me about any petty mistakes you found, even if you are not very confident. I'm writing for beginners, after all, so beginners' opinions and comments are crucial for my job.

## Warning: this is a shortened LITE-version!

It is approximately 6 times shorter than full version (~150 pages) and intended to those who wants for very quick introduction to reverse engineering basics. There are nothing about MIPS, ARM, OllyDBG, GCC, GDB, IDA, there are no exercises, examples, etc.

If you still interesting in reverse engineering, full version of the book is always available on my website: [beginners.re](http://beginners.re).

## **Acronyms used**

<b>OS</b> Operating System .....	ix
<b>PL</b> Programming language .....	3
<b>ROM</b> Read-only memory .....	118
<b>RA</b> Return Address .....	45
<b>SP</b> <a href="#">stack pointer</a> . SP/ESP/RSP in x86/x64. SP in ARM.....	9
<b>PC</b> Program Counter. IP/EIP/RIP in x86/64. PC in ARM.....	143
<b>IDA</b> Interactive Disassembler and debugger developed by <a href="#">Hex-Rays</a>	
<b>MSVC</b> Microsoft Visual C++	
<b>AKA</b> Also Known As	
<b>CRT</b> C runtime library .....	6
<b>CPU</b> Central processing unit.....	ix
<b>SIMD</b> Single instruction, multiple data .....	53
<b>DBMS</b> Database management systems .....	viii
<b>ISA</b> Instruction Set Architecture.....	3
<b>SEH</b> Structured Exception Handling .....	12
<b>NOP</b> No OPeration .....	25
<b>RAM</b> Random-access memory .....	102
<b>API</b> Application programming interface.....	110
<b>ASCIIZ</b> ASCII Zero (null-terminated ASCII string).....	24
<b>VM</b> Virtual Memory	
<b>WRK</b> Windows Research Kernel .....	123
<b>GPR</b> General Purpose Registers .....	3
<b>RE</b> Reverse Engineering.....	136
<b>BOM</b> Byte order mark .....	113
<b>MBR</b> Master Boot Record.....	118
<b>RFC</b> Request for Comments .....	116

**EOF** End of file.....22

# Glossary

**real number** numbers which may contain a dot. this is *float* and *double* in C/C++. [61](#)

**decrement** Decrease by 1. [52](#), [57](#), [126](#)

**increment** Increase by 1. [52](#), [57](#)

**product** Multiplication result. [28](#)

**stack pointer** A register pointing to a place in the stack. [6](#), [9](#), [11](#), [14](#), [141](#)

**quotient** Division result. [61](#)

**anti-pattern** Generally considered as bad practice. [19](#), [107](#)

**callee** A function being called by another. [8](#), [11](#), [17](#), [22](#), [27](#), [28](#), [45](#), [102](#), [107](#)

**caller** A function calling another. [4](#), [6](#), [22](#), [27–29](#), [45](#), [102](#)

**heap** usually, a big chunk of memory provided by the [OS](#) so that applications can divide it by themselves as they wish. `malloc()/free()` work with the heap. [9](#), [11](#), [88](#)

**jump offset** a part of the `JMP` or `Jcc` instruction's opcode, to be added to the address of the next instruction, and this is how the new `PC`<sup>1</sup> is calculated. May be negative as well. [25](#), [37](#)

**NOP** “no operation”, idle instruction. [126](#)

**PDB** (Win32) Debugging information file, usually just function names, but sometimes also function arguments and local variables names. [109](#)

**POKE** BASIC language instruction for writing a byte at a specific address. [126](#)

**register allocator** The part of the compiler that assigns CPU registers to local variables. [57](#), [102](#)

**reverse engineering** act of understanding how the thing works, sometimes in order to clone it. [iv](#)

**stack frame** A part of the stack that contains information specific to the current function: local variables, function arguments, `RA`, etc. [18](#), [28](#)

**stdout** standard output. [12](#), [45](#)

**tracer** My own simple debugging tool. You can read more about it here: [33.1 on page 130](#). [111](#), [120](#), [124](#)

**Windows NT** Windows NT, 2000, XP, Vista, 7, 8. [114](#)

---

<sup>1</sup>Program Counter. IP/EIP/RIP in x86/64. PC in ARM.

# Index

- Buffer Overflow, 63
  - C language elements
    - Pointers, 17, 102
    - C99
      - bool, 75
      - variable length arrays, 68
    - const, 5
    - for, 52
    - if, 34, 44
    - return, 6, 23
    - switch, 43, 44
    - while, 56
  - C standard library
    - alloca(), 11, 68, 107
    - assert(), 117
    - free(), 107
    - longjmp(), 45
    - malloc(), 89, 107
    - memcmp(), 119
    - memcpy(), 17
    - rand(), 83, 110
    - realloc(), 107
    - scanf(), 17
    - strlen(), 56
  - Compiler's anomalies, 41, 80
  - C++
    - STL, 109
  - grep usage, 109, 120, 124
  - Global variables, 19
    - Buffer overflow, 67
    - Recursion, 8, 10
  - Stack, 9, 27, 45
    - Stack overflow, 10
    - Stack frame, 18
  - Syntactic Sugar, 44
  - OllyDbg, 66, 70, 71
  - Oracle RDBMS, 6, 116
- ARM
- Instructions
    - ASR, 81
    - CSEL, 42
    - LSL, 81
    - LSR, 81
    - MOV, 4
    - MOVcc, 42
    - POP, 9
    - PUSH, 9
    - TEST, 57
- AWK, 122
- Base64, 115
- base64, 116
- bash, 31
- BASIC
  - POKE, 126
- binary grep, 119, 132
- Borland Delphi, 112
- cdecl, 14
- column-major order, 70
- Compiler intrinsic, 12
- Cygwin, 111
- DosBox, 124
- Error messages, 116
- fastcall, 7, 16
- FORTRAN, 70
- Function epilogue, 8, 122
- Function prologue, 8, 122
- Hiew, 24, 37, 112
- IDA, 114
- Intel C++, 6
- jumptable, 46
- MD5, 118
- MIDI, 118
- MIPS, 125
- MS-DOS, 118, 124, 126
- Pascal, 112
- puts() instead of printf(), 30
- Register allocation, 102
- row-major order, 70
- SAP, 109
- Security through obscurity, 116
- Shadow space, 29
- Signed numbers, 35, 105
- tracer, 111, 120, 124, 130
- Unicode, 113
- UTF-16LE, 113, 114
- UTF-8, 113
- Windows
  - KERNEL32.DLL, 75
  - PDB, 109
  - Structured Exception Handling, 12
  - Win32, 75, 114
- x86
  - Instructions
    - ADC, 99

ADD, 6, 14, 28  
AND, 76–78, 81, 97  
CALL, 6, 10  
CBW, 106  
CDQ, 101, 106  
CDQE, 106  
CMOVcc, 40, 42  
CMP, 22, 23  
CMPSB, 119  
CPL, 94  
CWD, 106  
CWDE, 106  
DEC, 57  
DIV, 106  
DIVSD, 121  
FDIV, 120  
IDIV, 106  
IMUL, 28, 106  
INC, 57  
INT3, 111  
JA, 35, 105  
JAE, 35  
JB, 35, 105  
JBE, 35  
Jcc, 41  
JE, 45  
JG, 35, 105  
JGE, 35  
JL, 35, 105  
JLE, 35  
JMP, 10  
JNE, 22, 23, 35  
JZ, 45  
LEA, 19, 28  
LOOP, 52, 55, 122  
MOV, 4, 6  
MOVSX, 57, 106  
MOVSXD, 69  
MOVZX, 89  
MUL, 106  
OR, 77  
POP, 6, 9, 10  
PUSH, 6, 9, 10, 18  
RCL, 122  
RET, 4, 6, 10  
ROL, 80  
SAR, 81, 106  
SBB, 99  
SHL, 59, 63, 81  
SHR, 61, 81, 97  
SHRD, 101  
SUB, 6, 23, 45  
TEST, 57, 76, 81  
XOR, 6, 23, 122

Registers  
Flags, 23  
EAX, 22, 30  
EBP, 18, 28  
ESP, 14, 18  
JMP, 48  
ZF, 23, 76

x86-64, 6, 15, 17, 19, 25, 28, 102

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